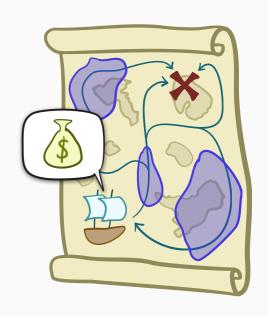
The Gittins Policy

in the M/G/1 Queue

Ziv Scully Mor Harchol-Balter

Carnegie Mellon University





The *Gittins policy* solves a variety of queue scheduling problems



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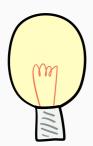
But prior results have limitations



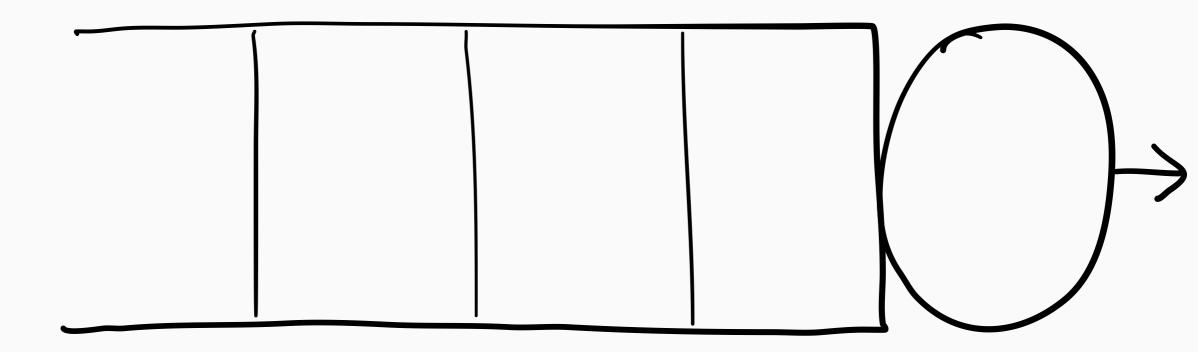
The *Gittins policy* solves a variety of queue scheduling problems

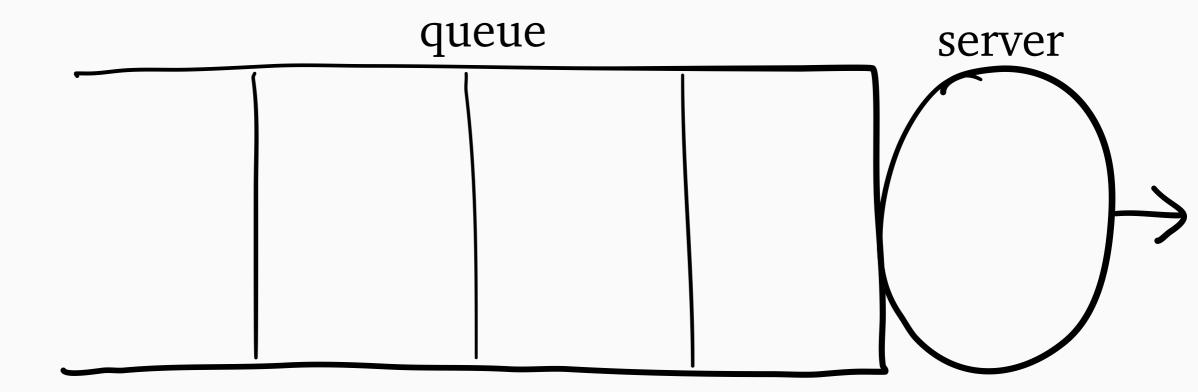


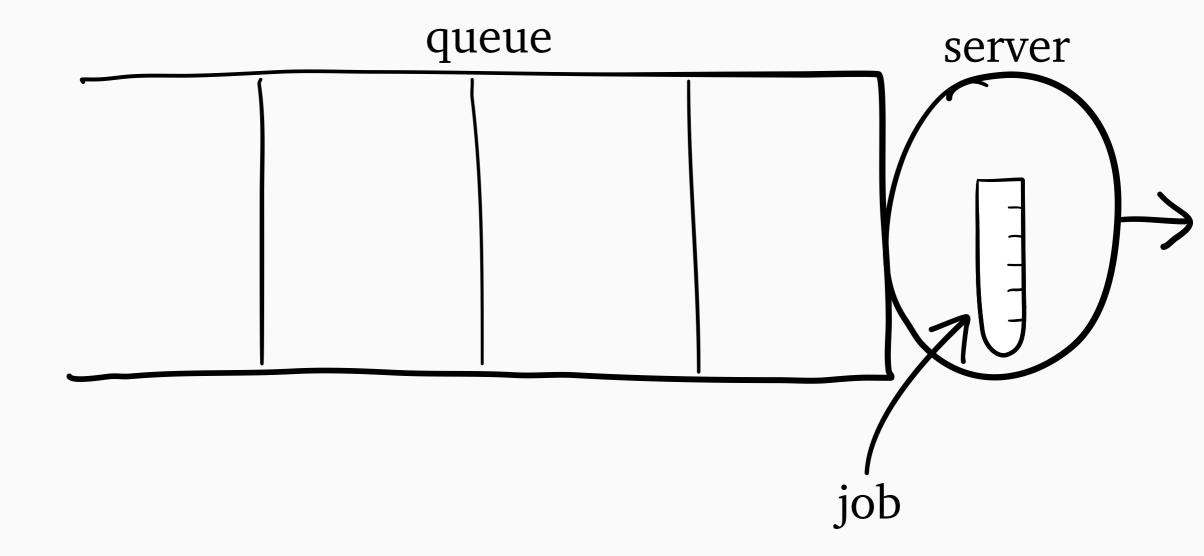
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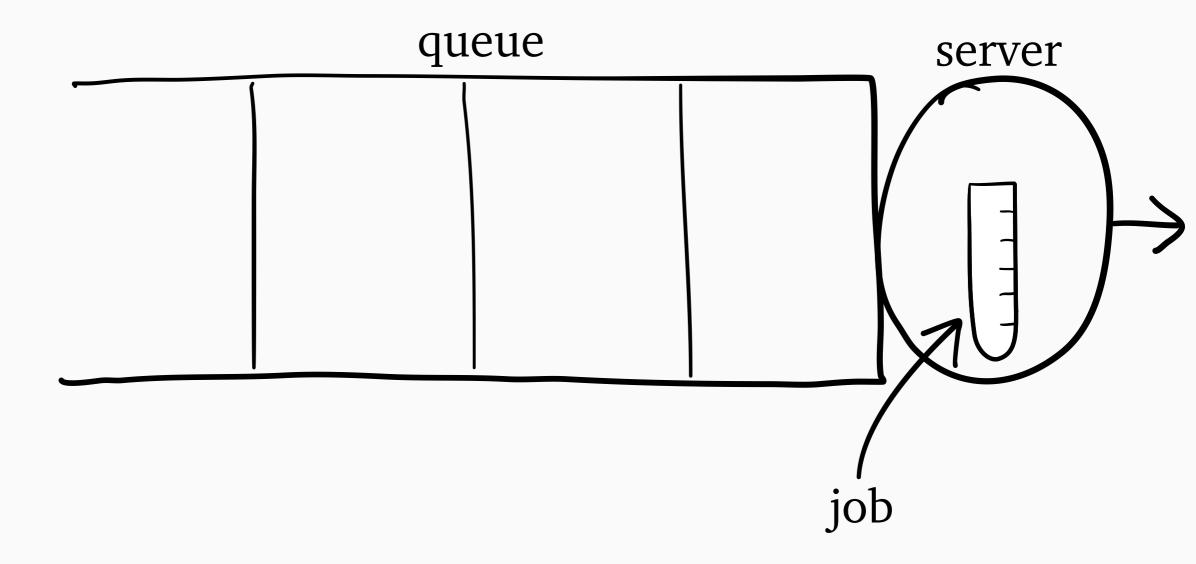


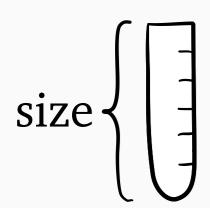
We unify and generalize all prior Gittins optimality results

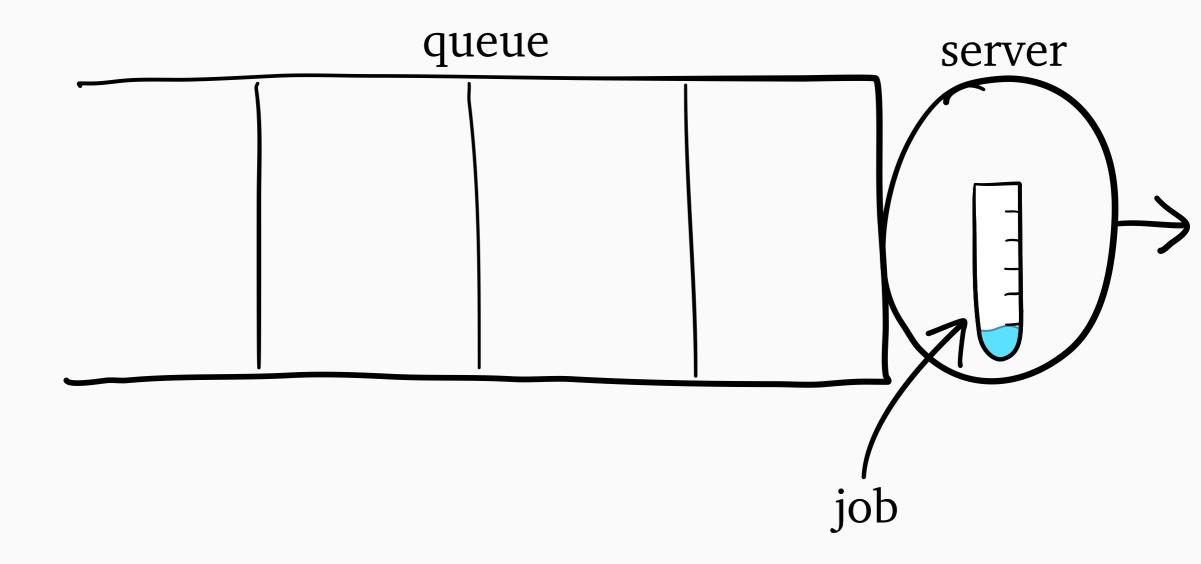


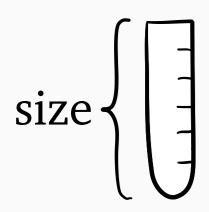


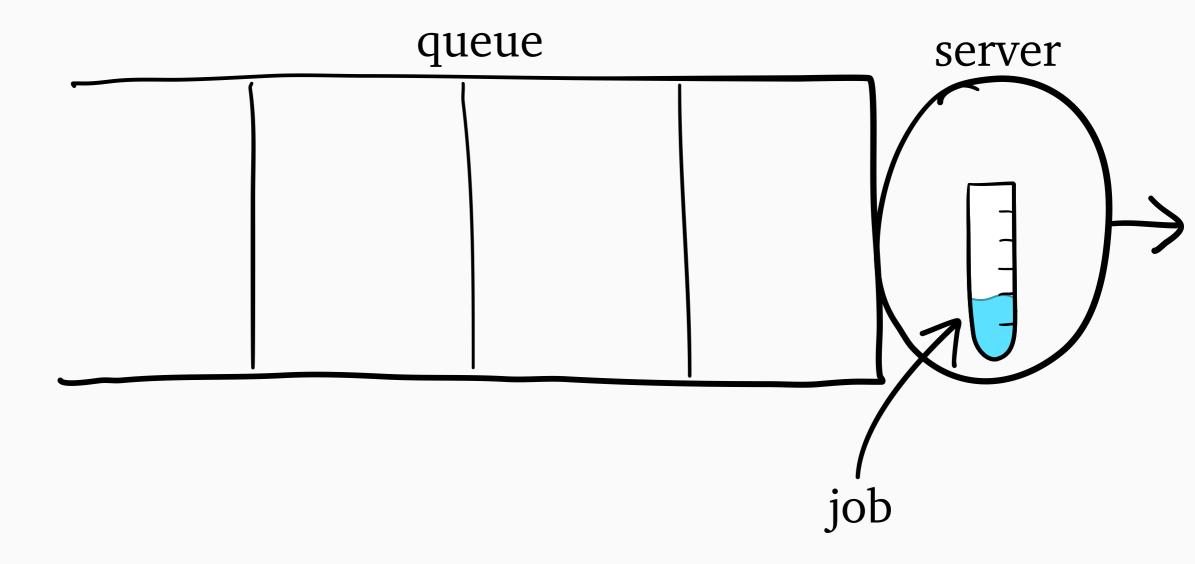


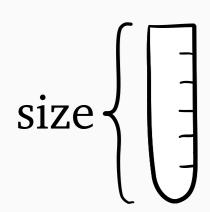


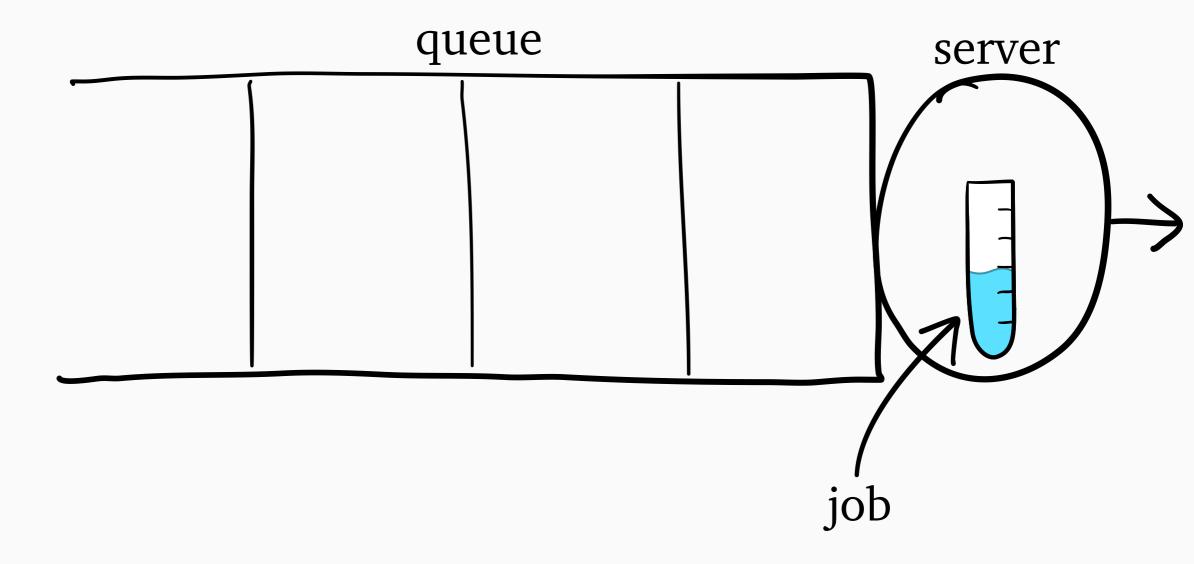


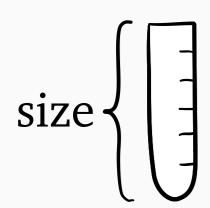


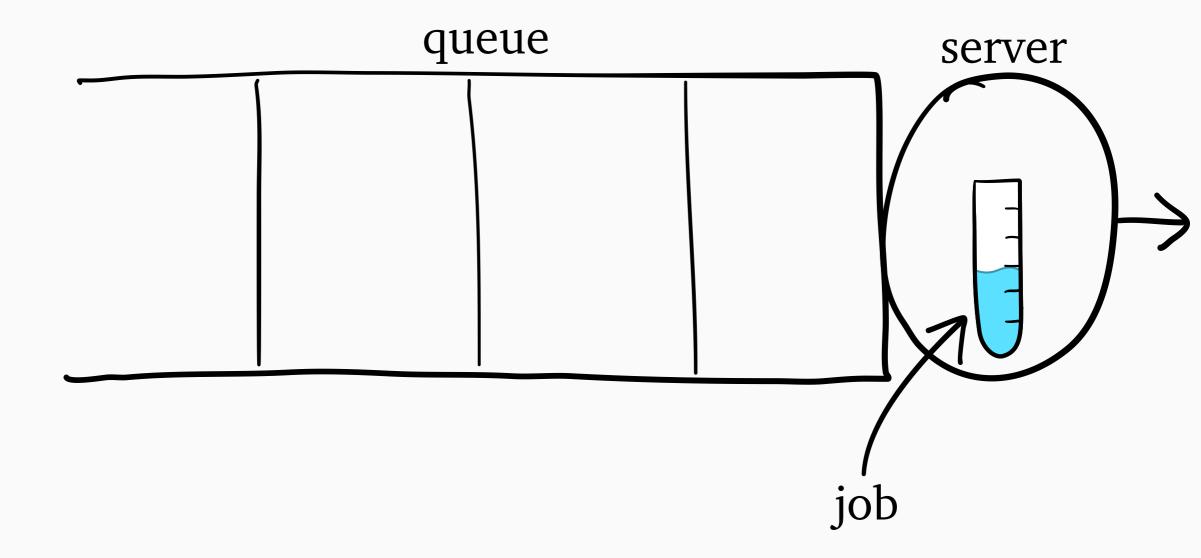


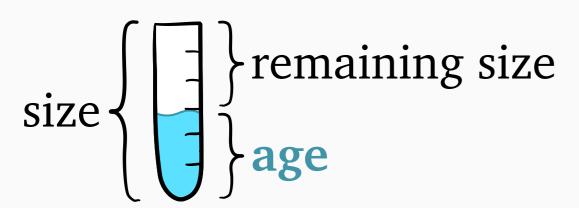


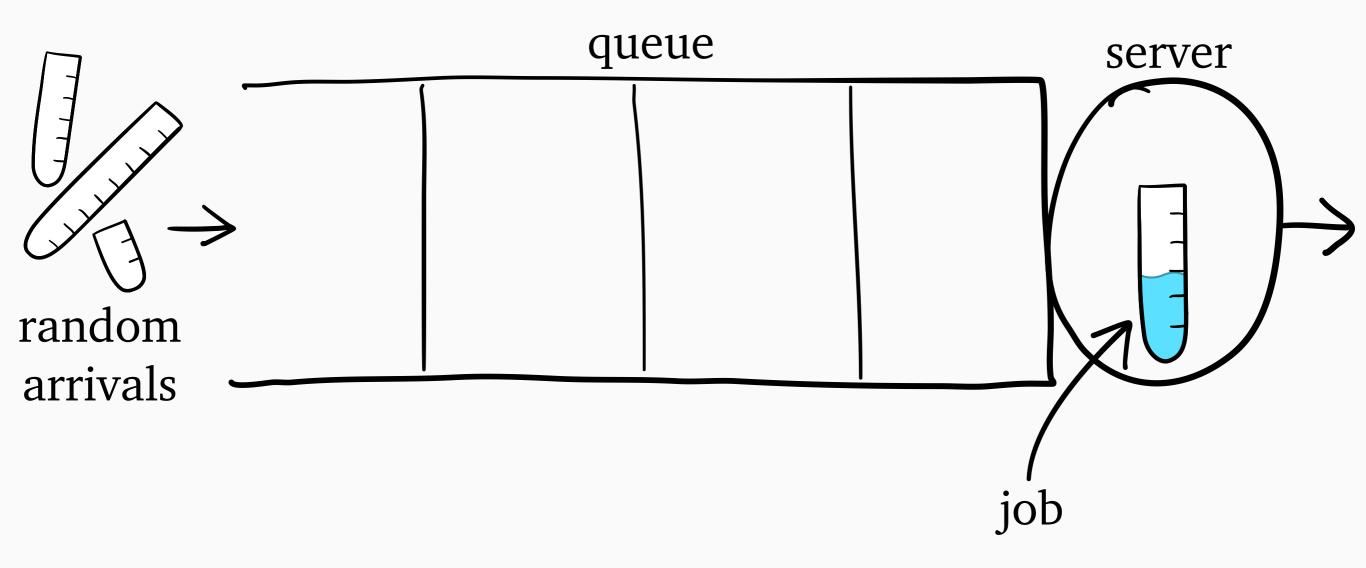


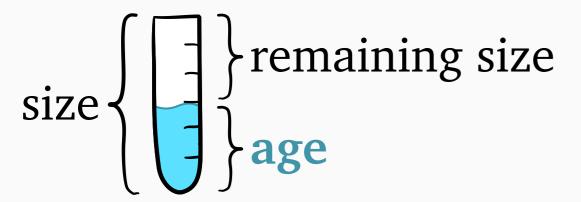


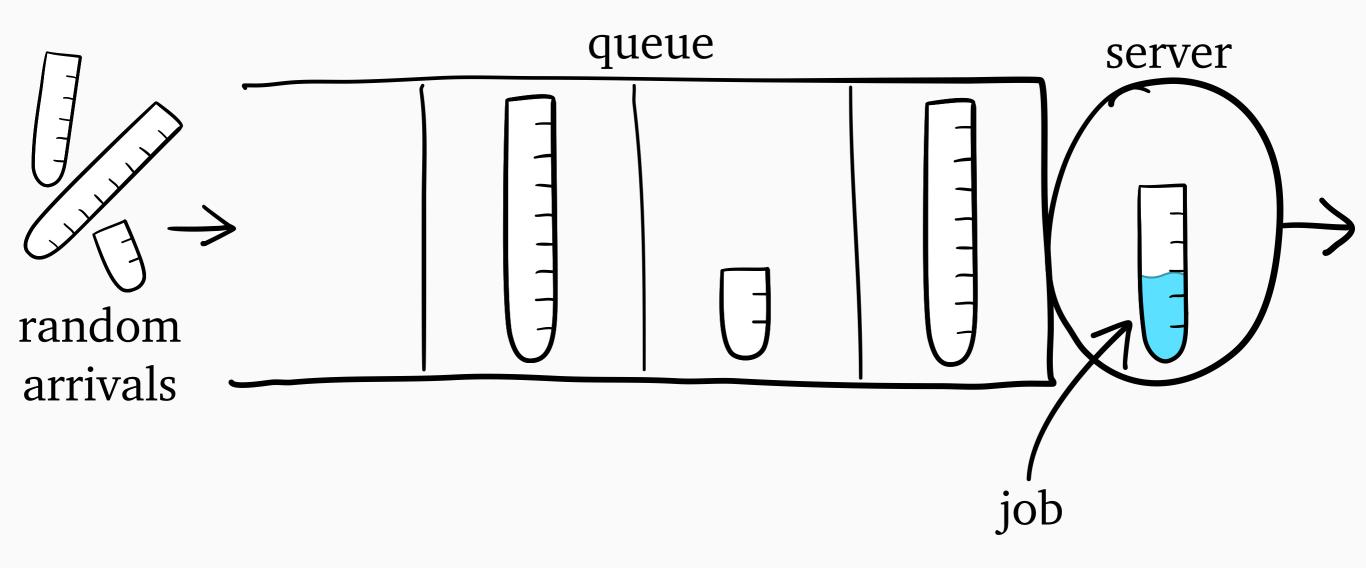


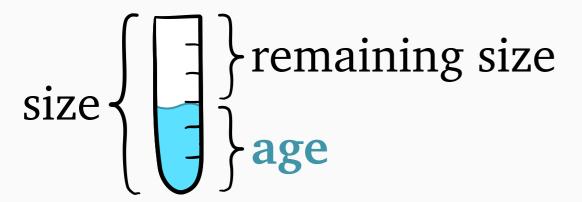


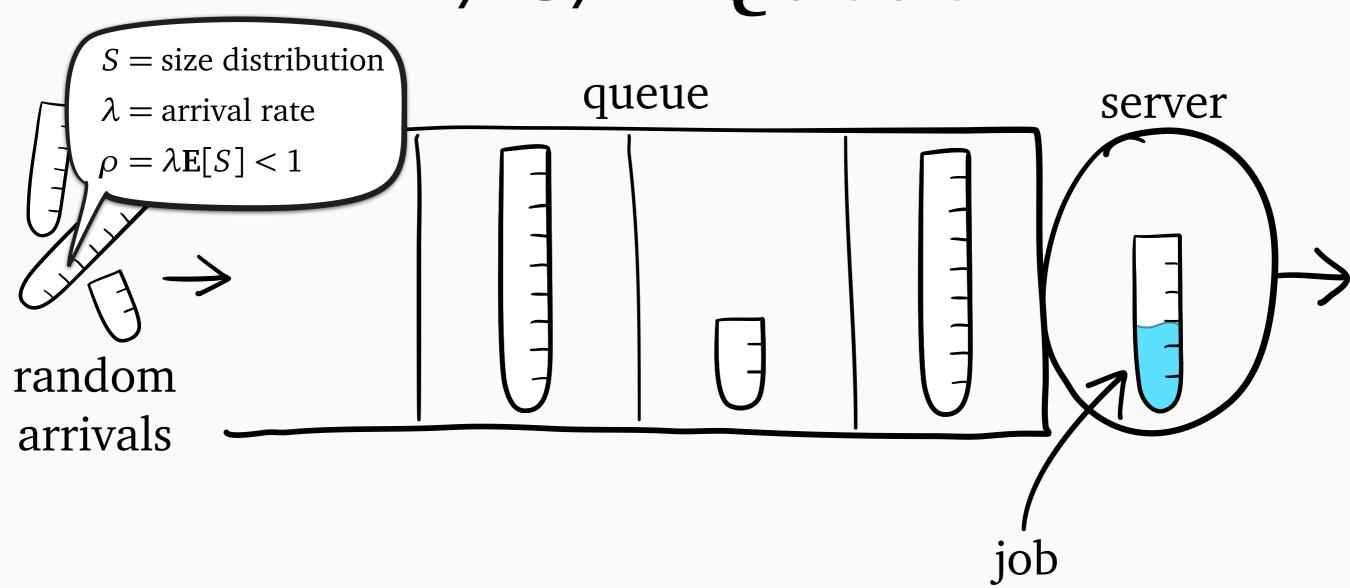


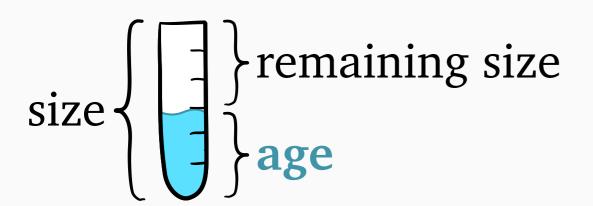


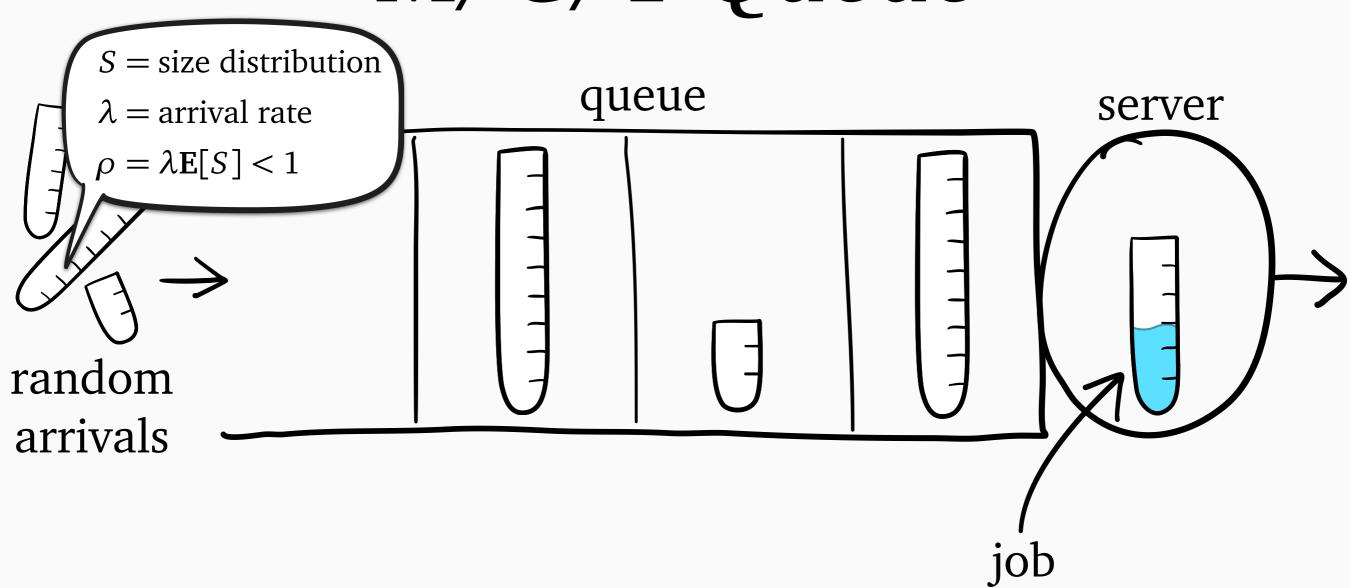


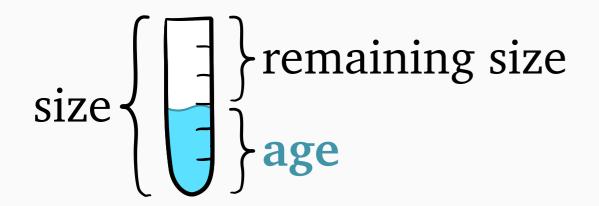




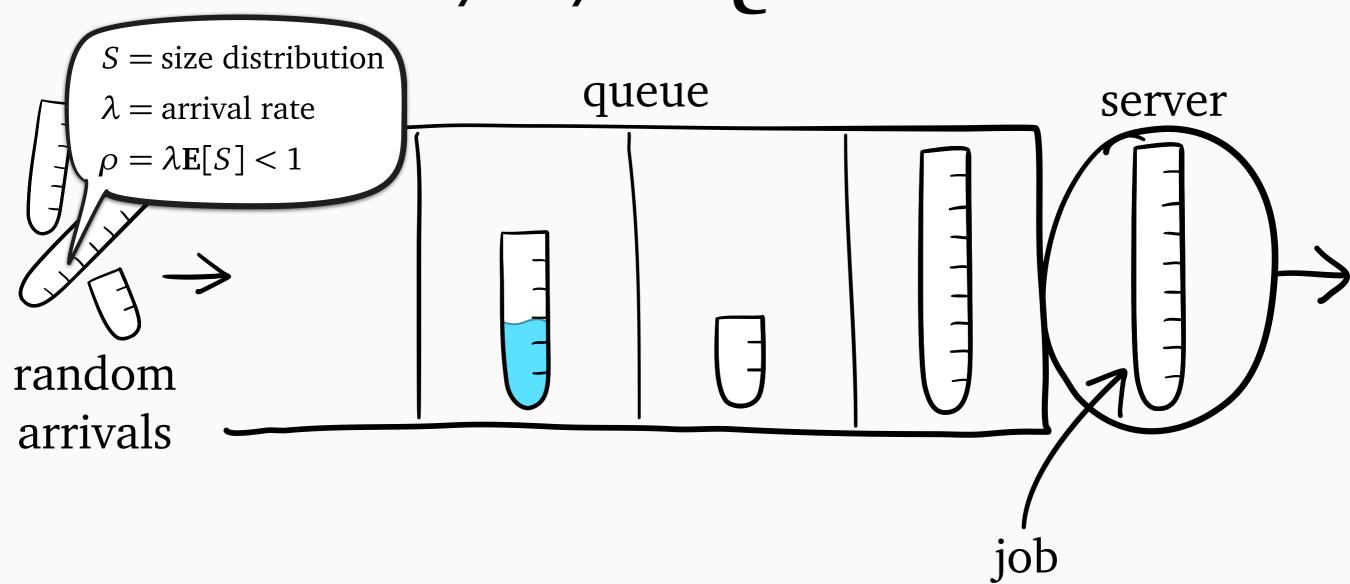


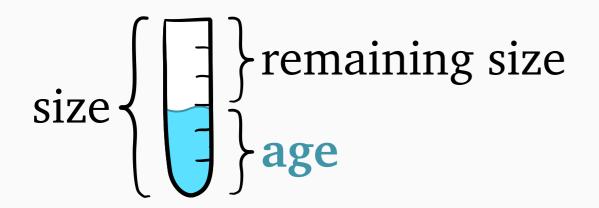




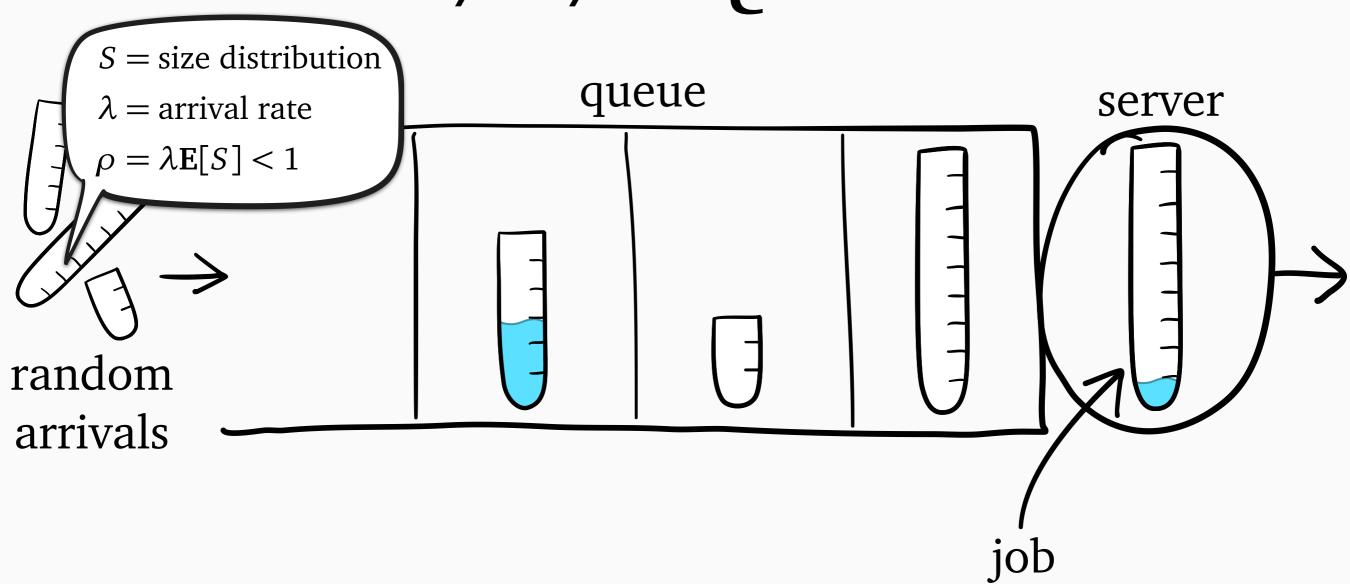


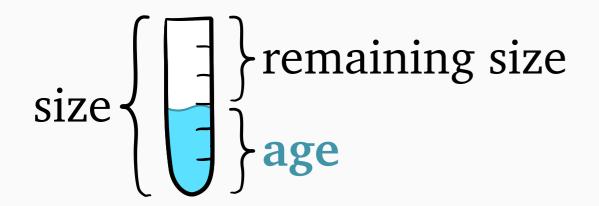




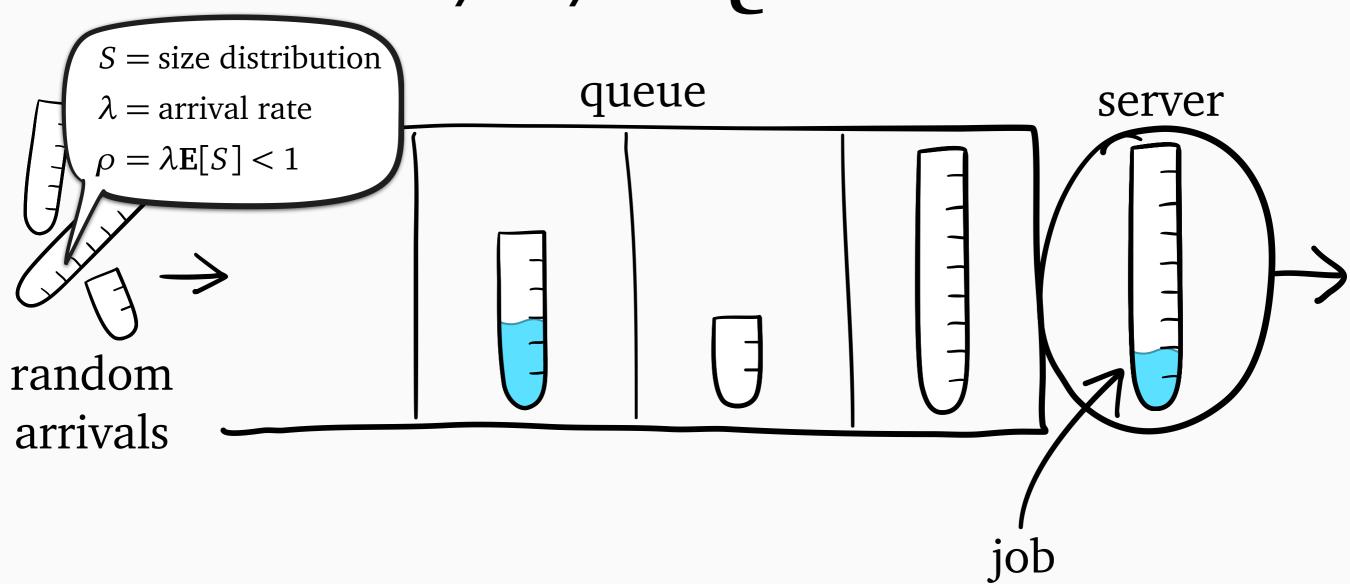


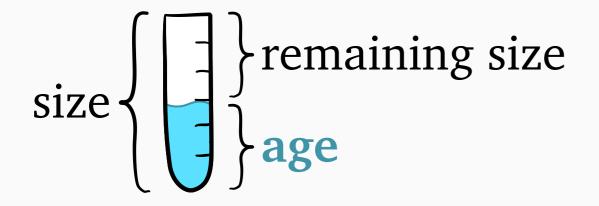




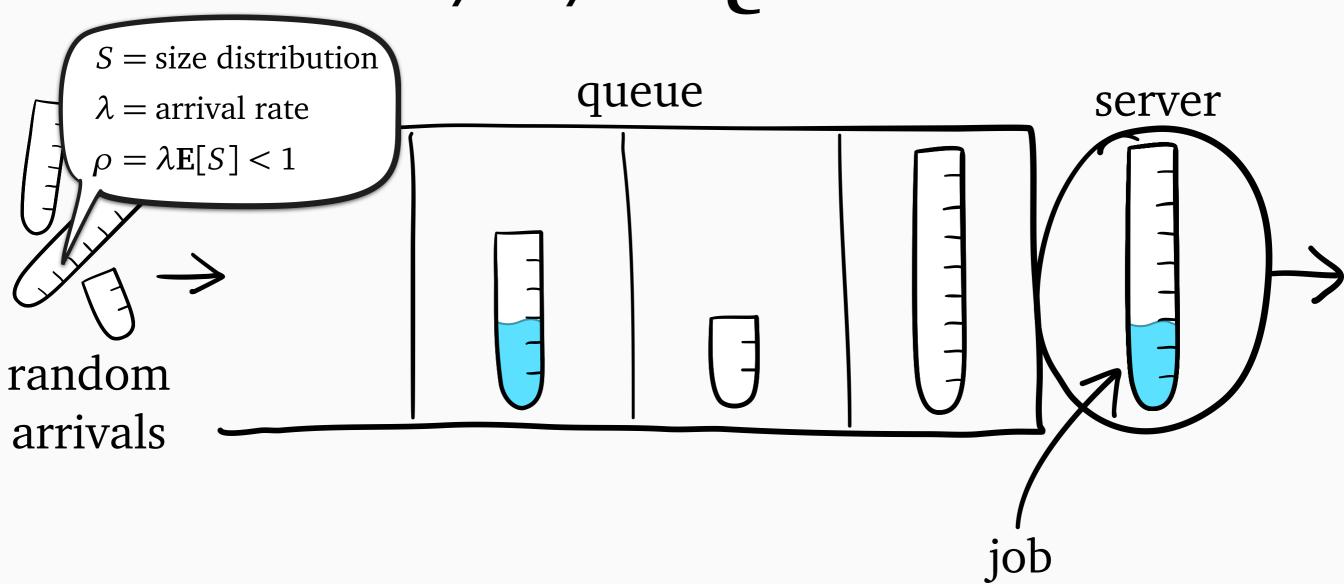


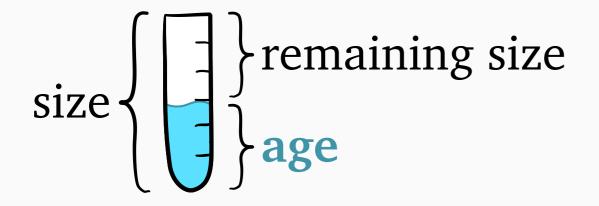




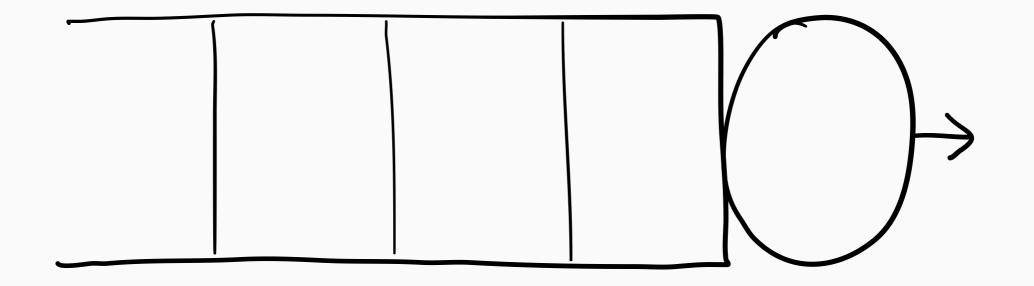


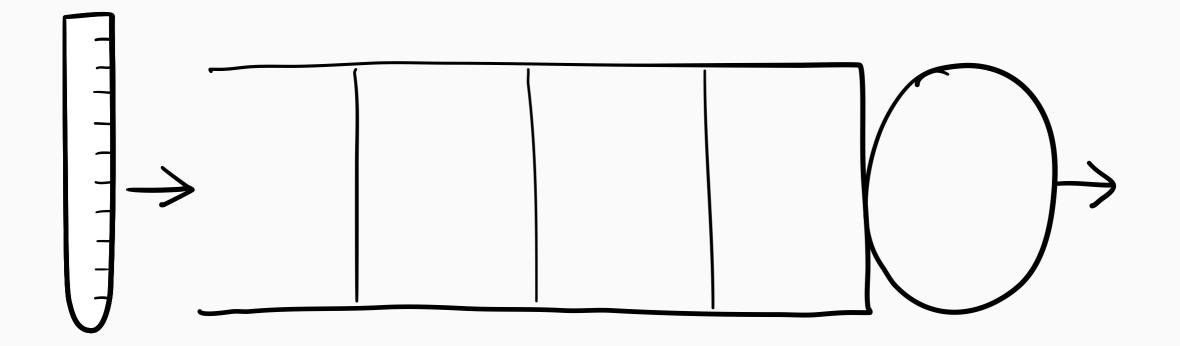


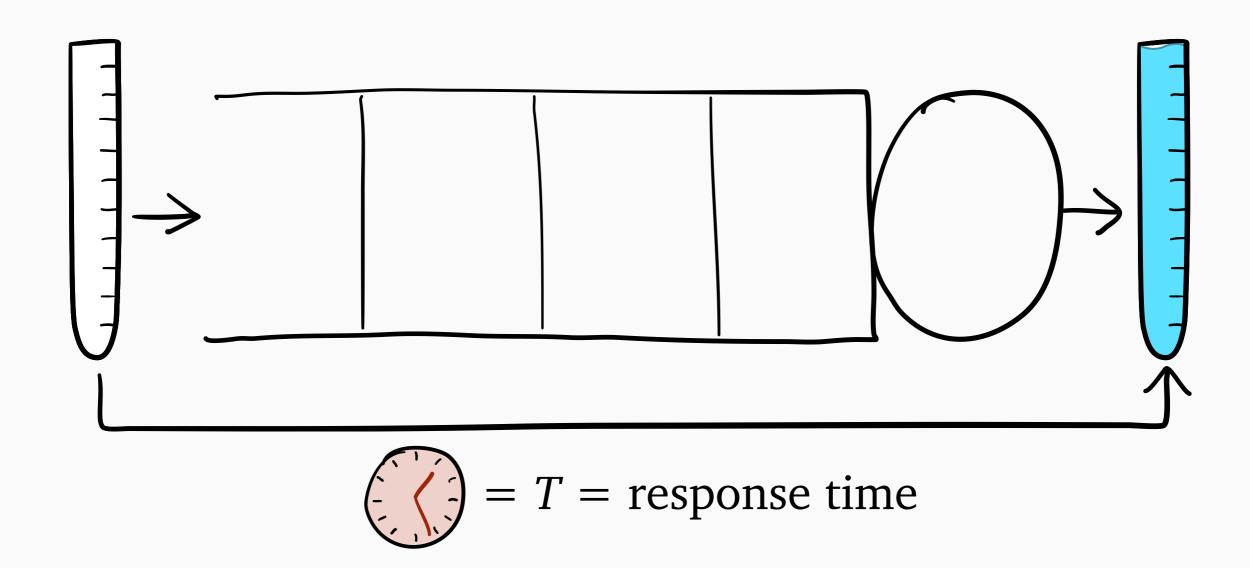


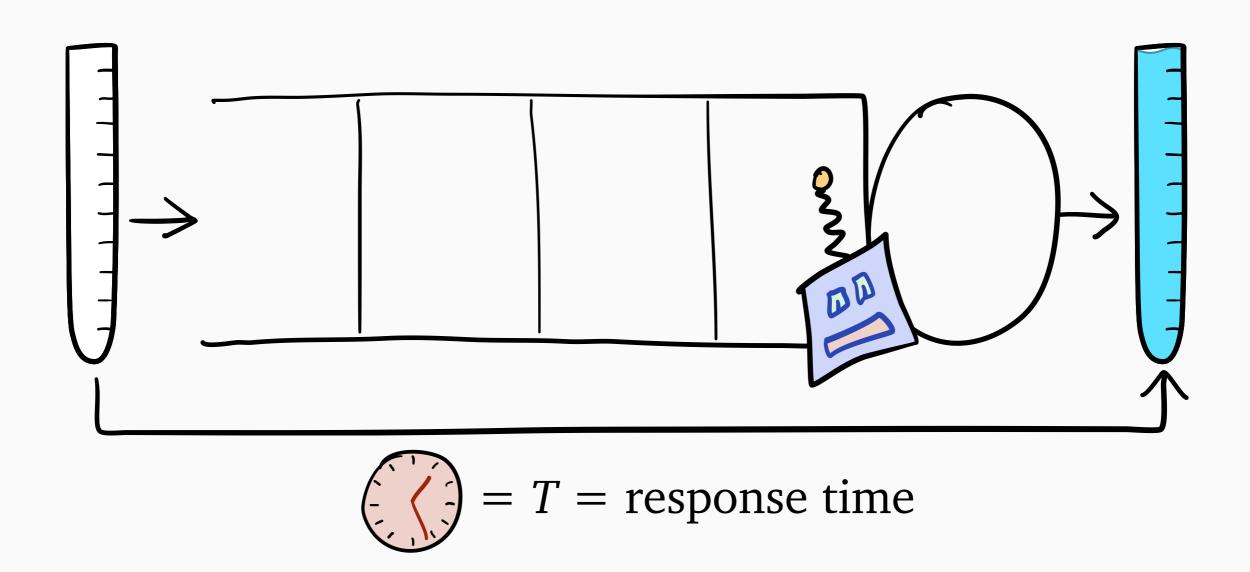


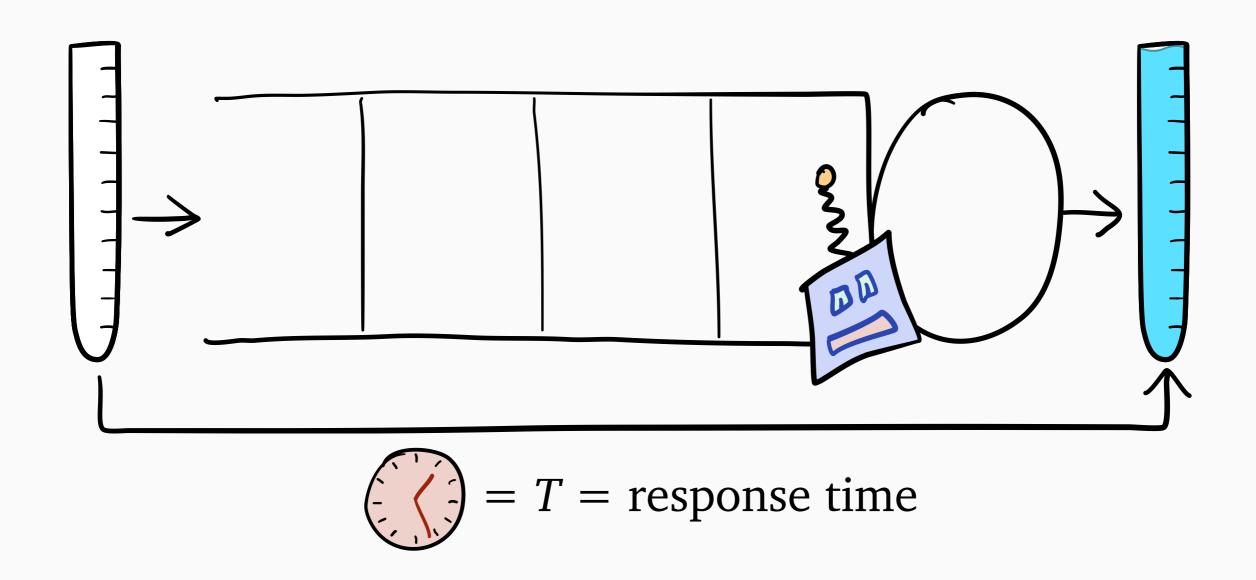




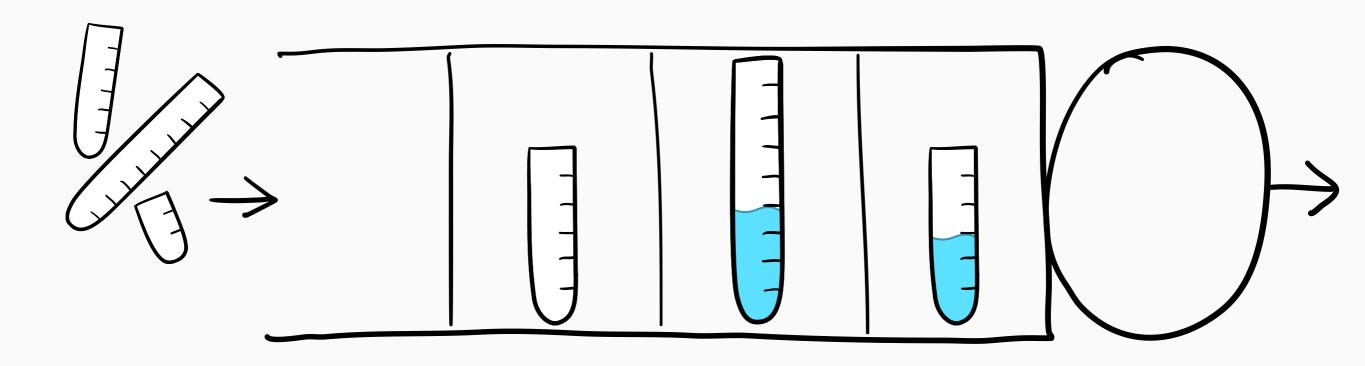


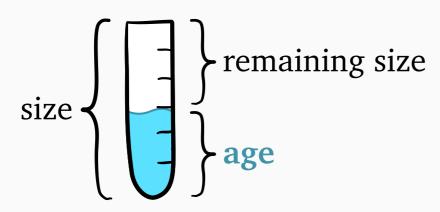


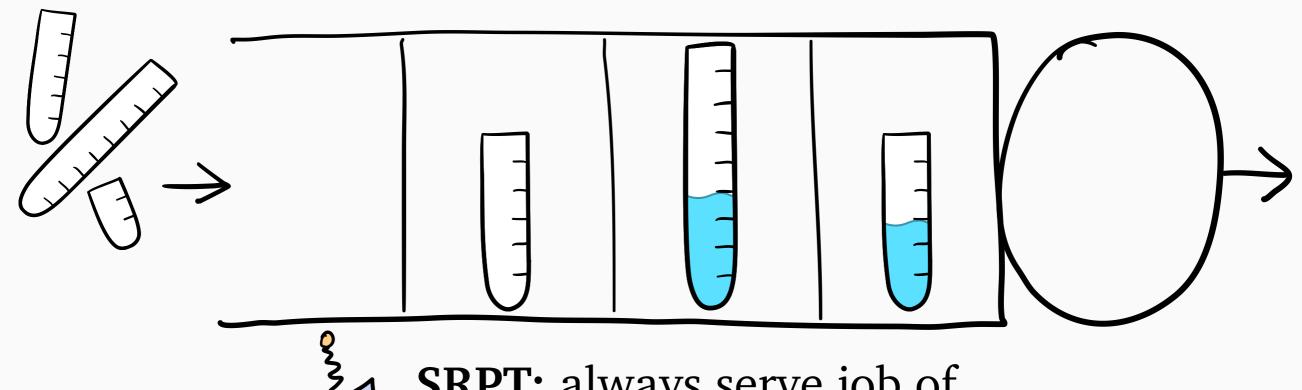




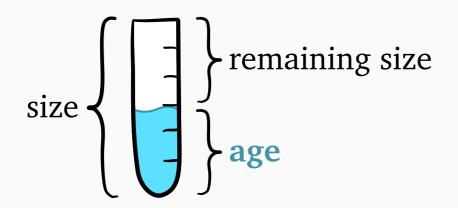
Goal: schedule to minimize metrics like *mean response time* $\mathbf{E}[T]$

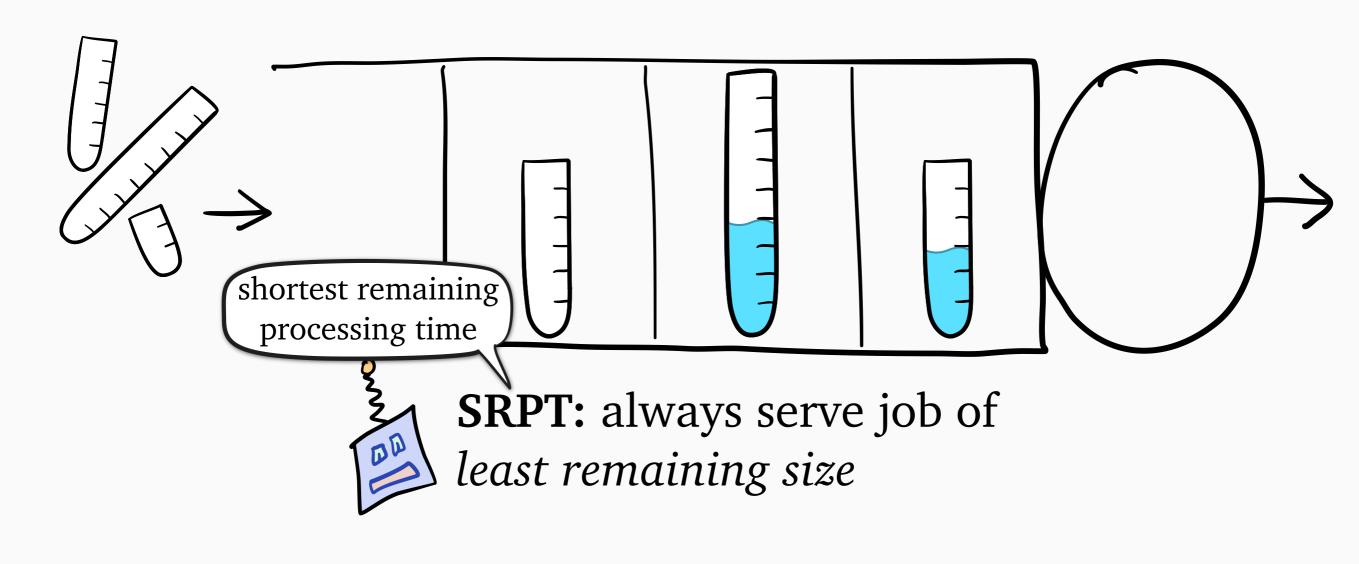


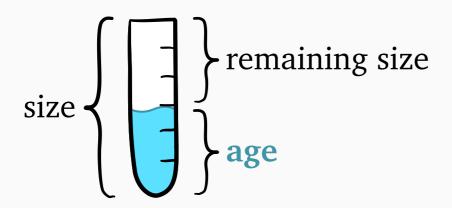


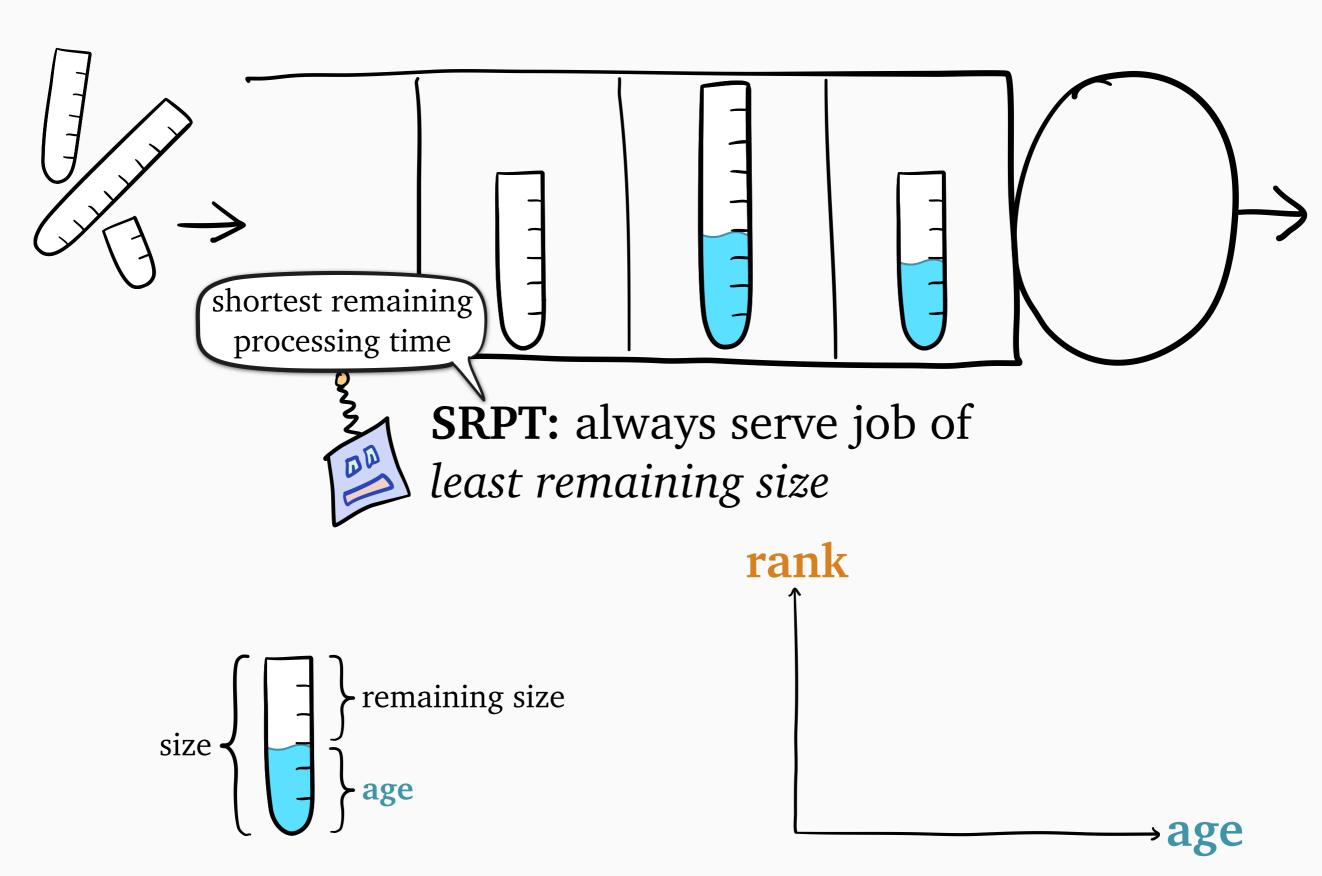


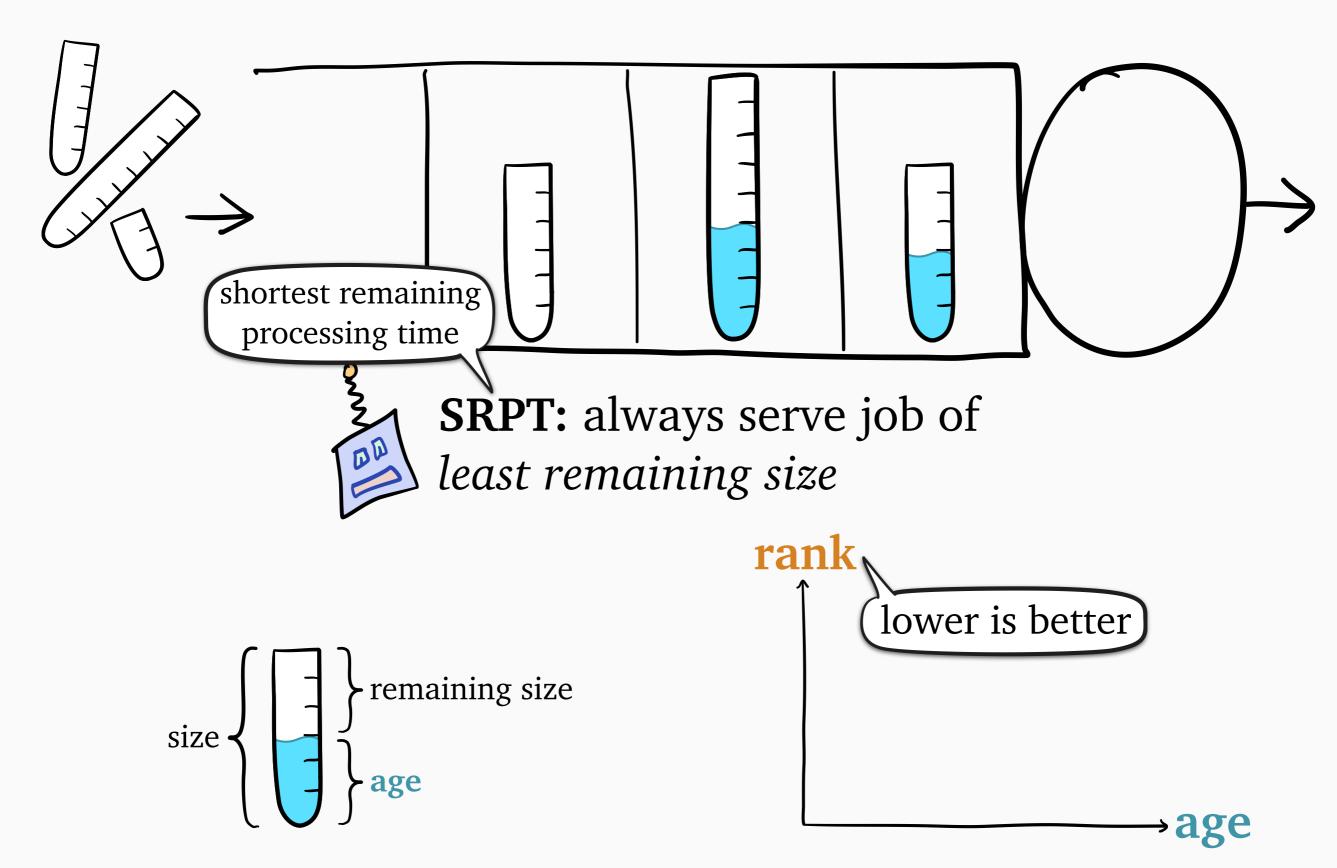
SRPT: always serve job of least remaining size

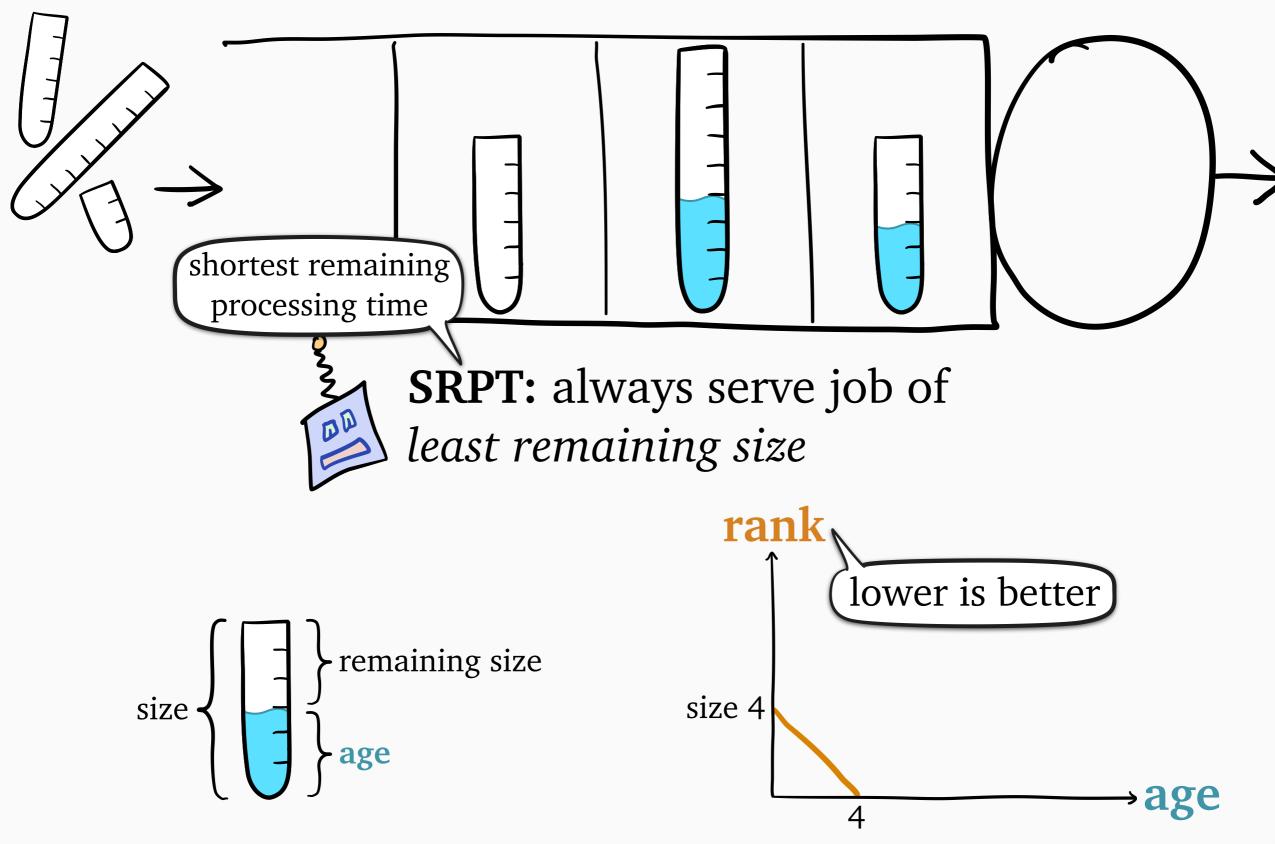


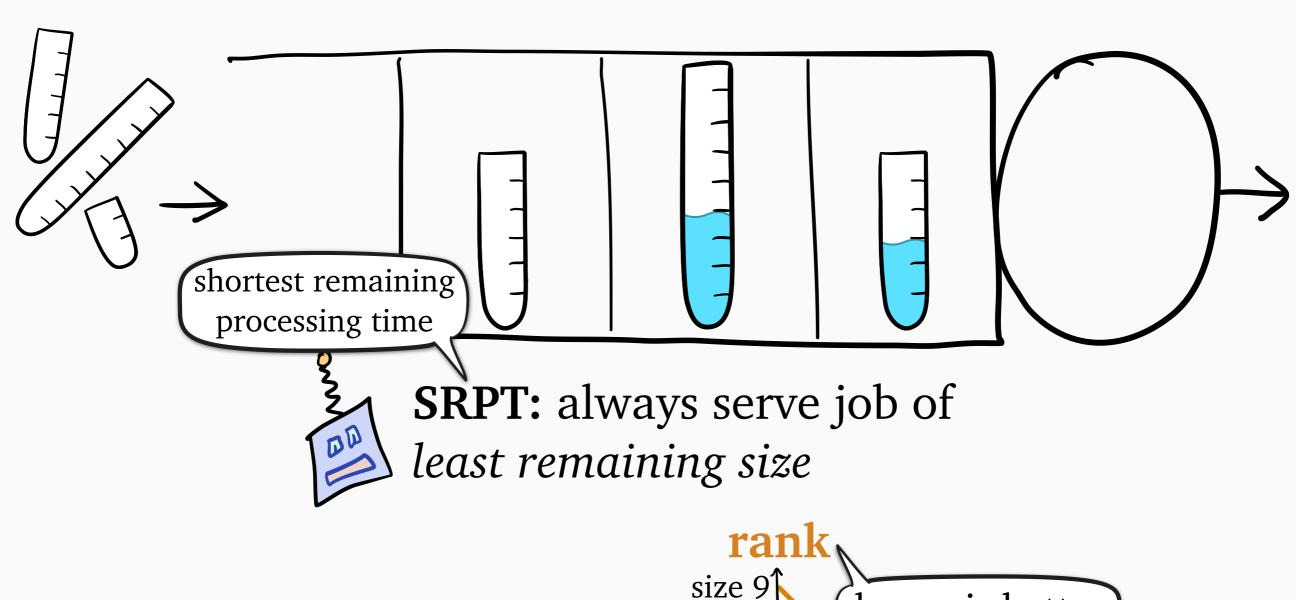


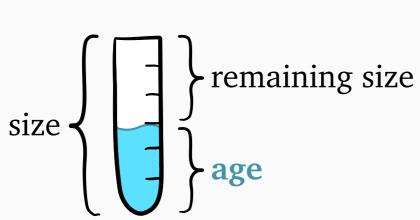


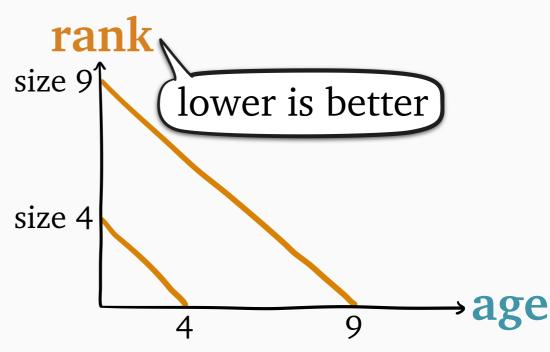


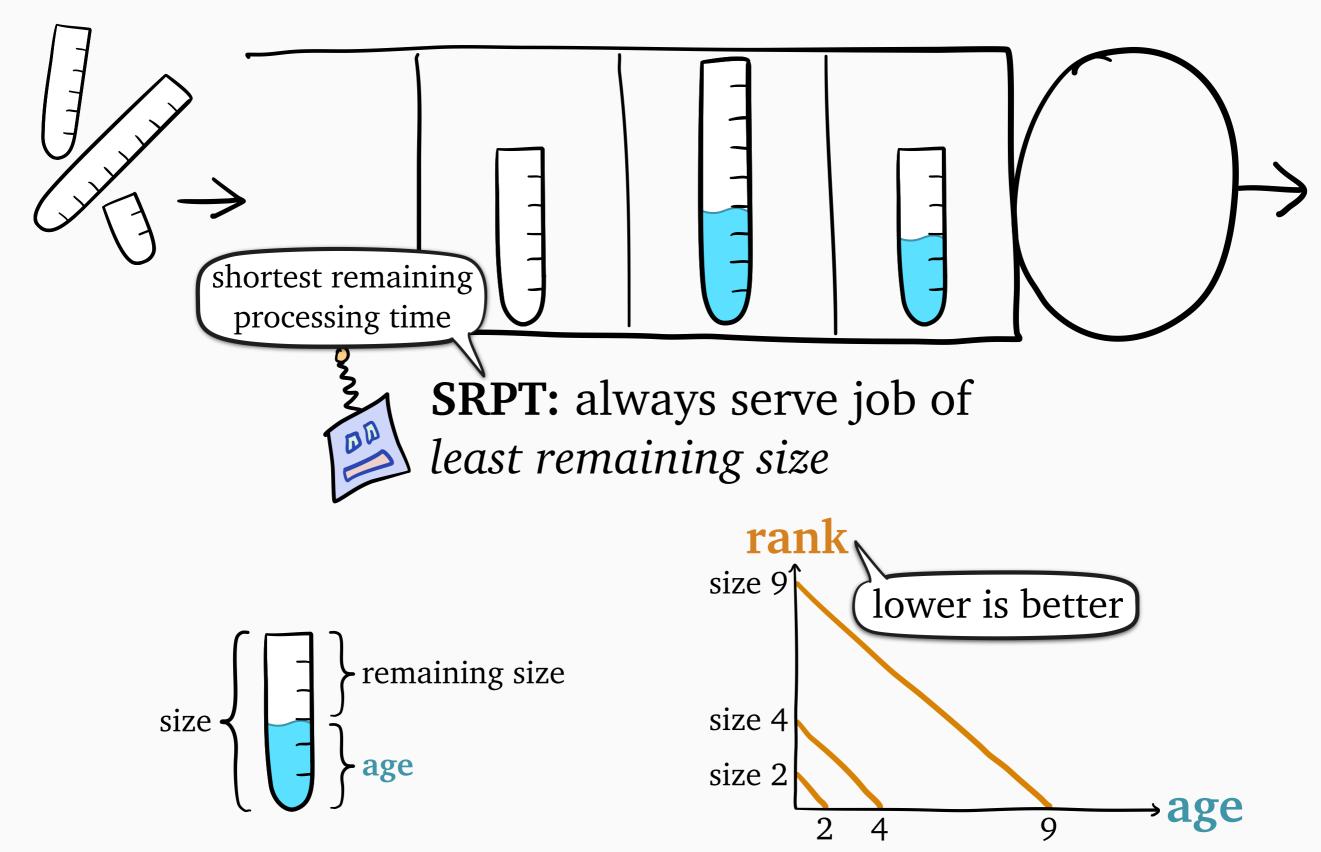


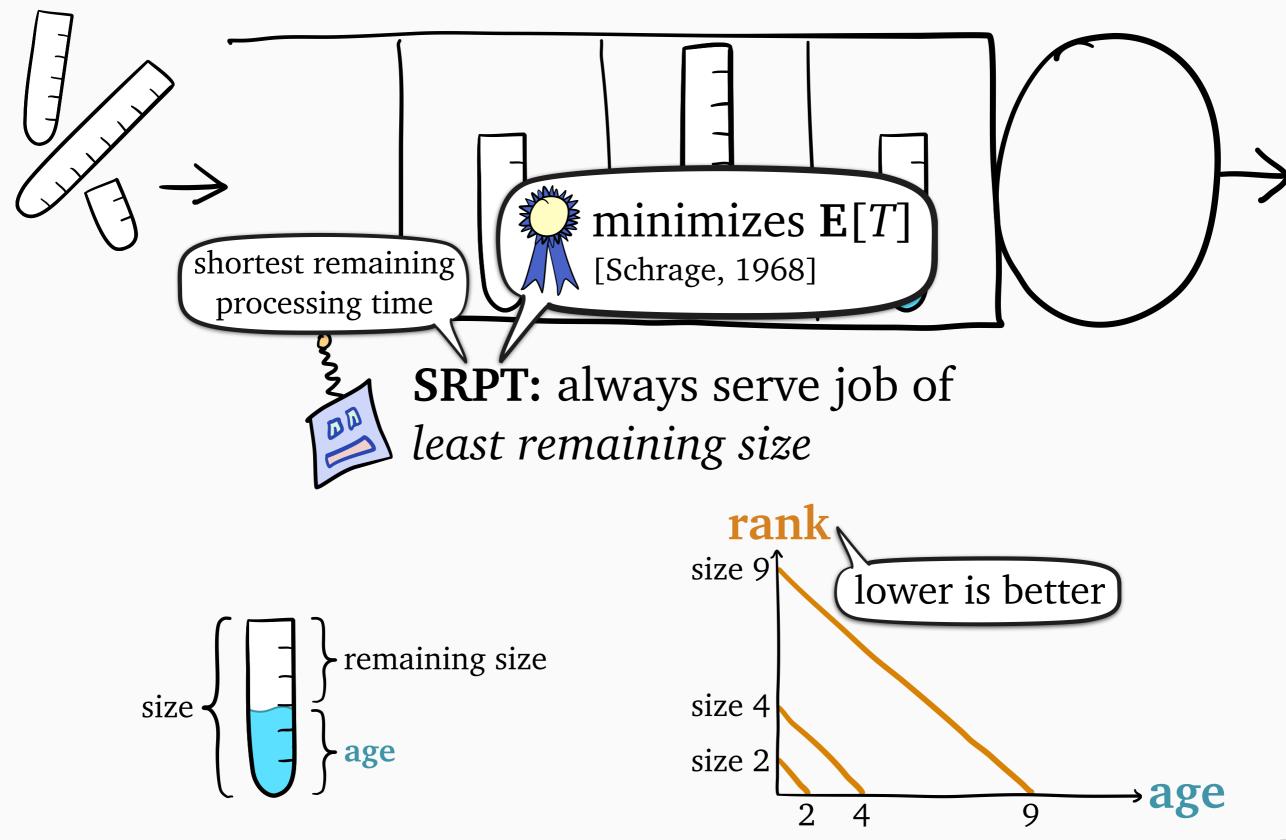




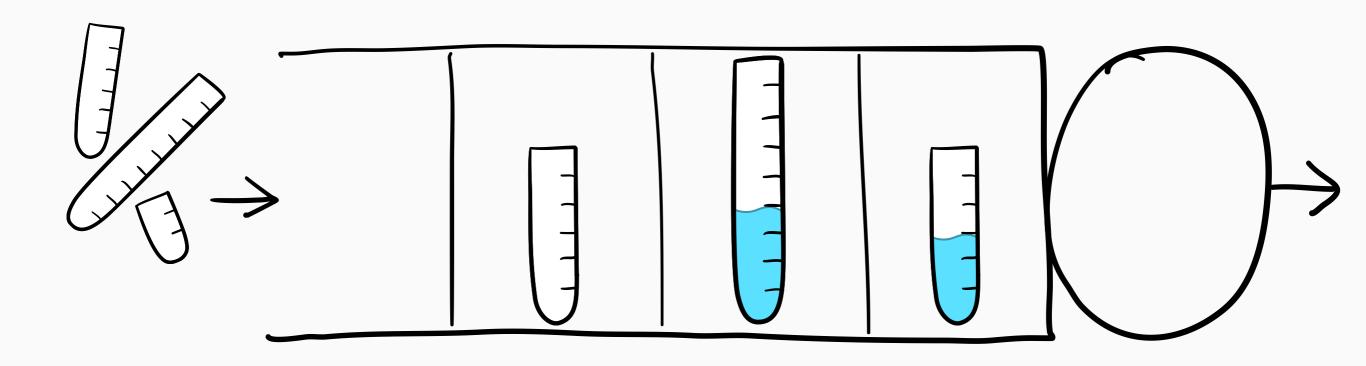


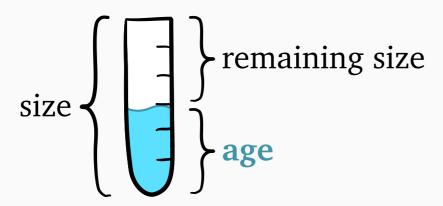


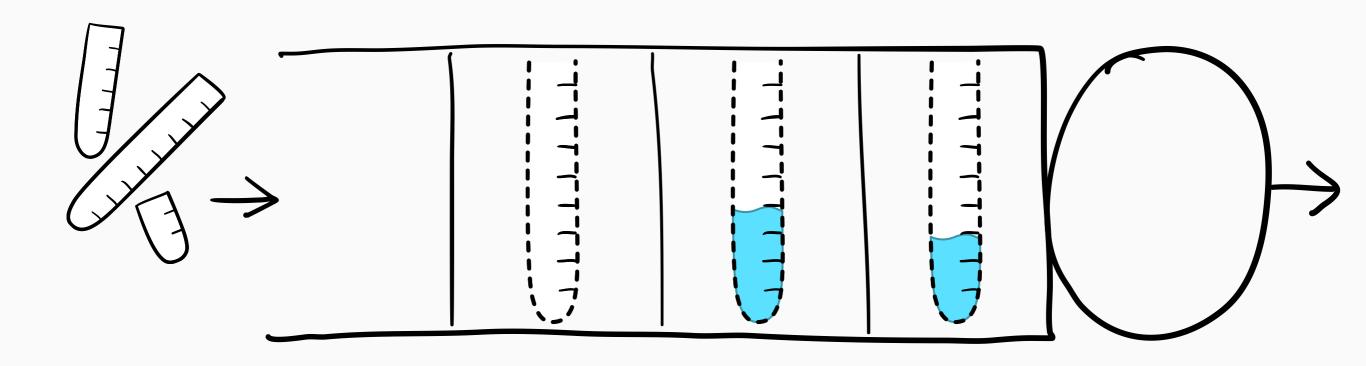


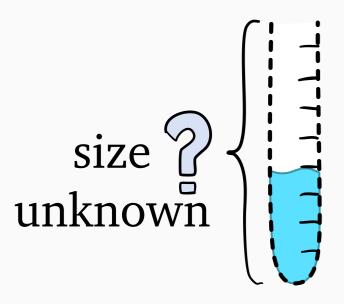


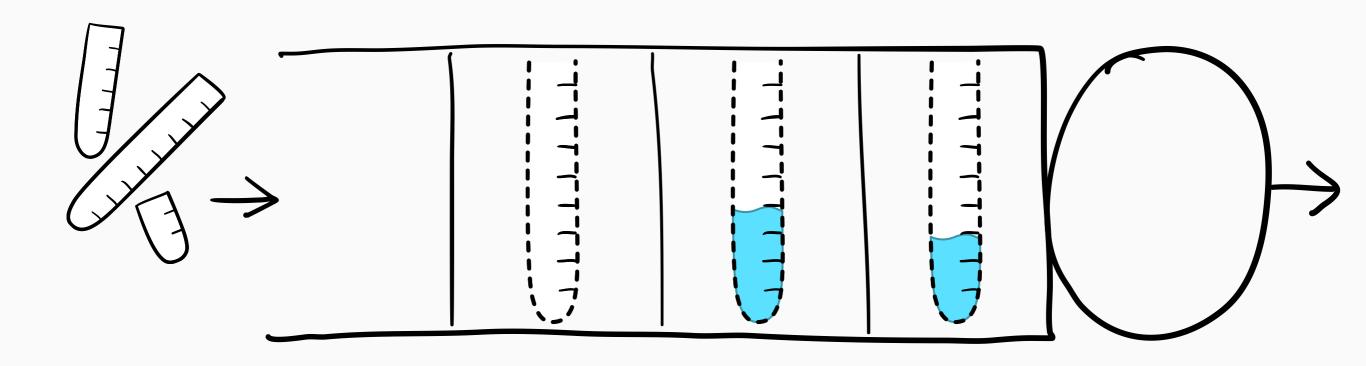
Unknown Job Sizes

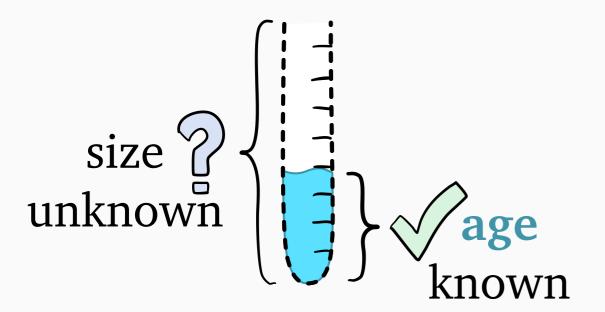


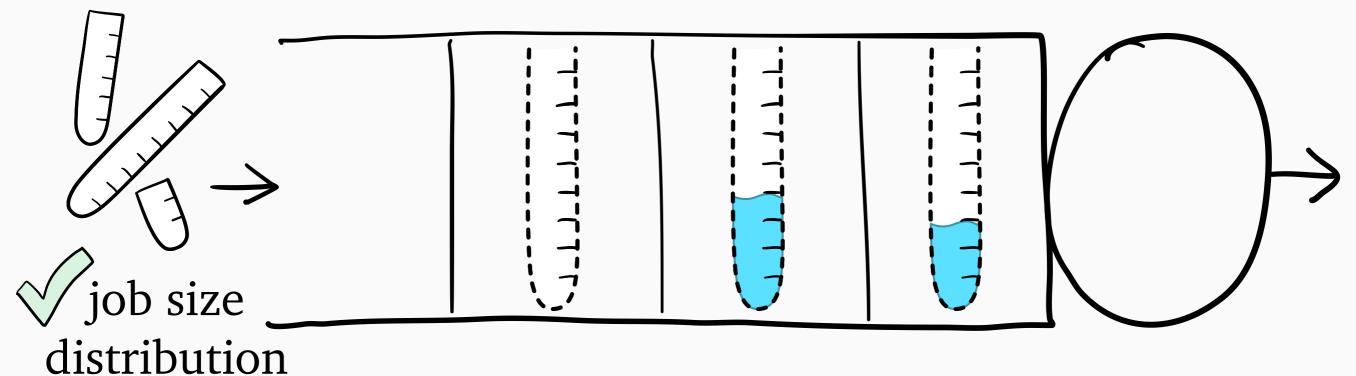




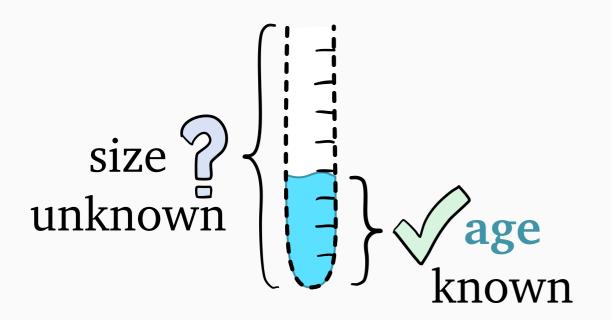


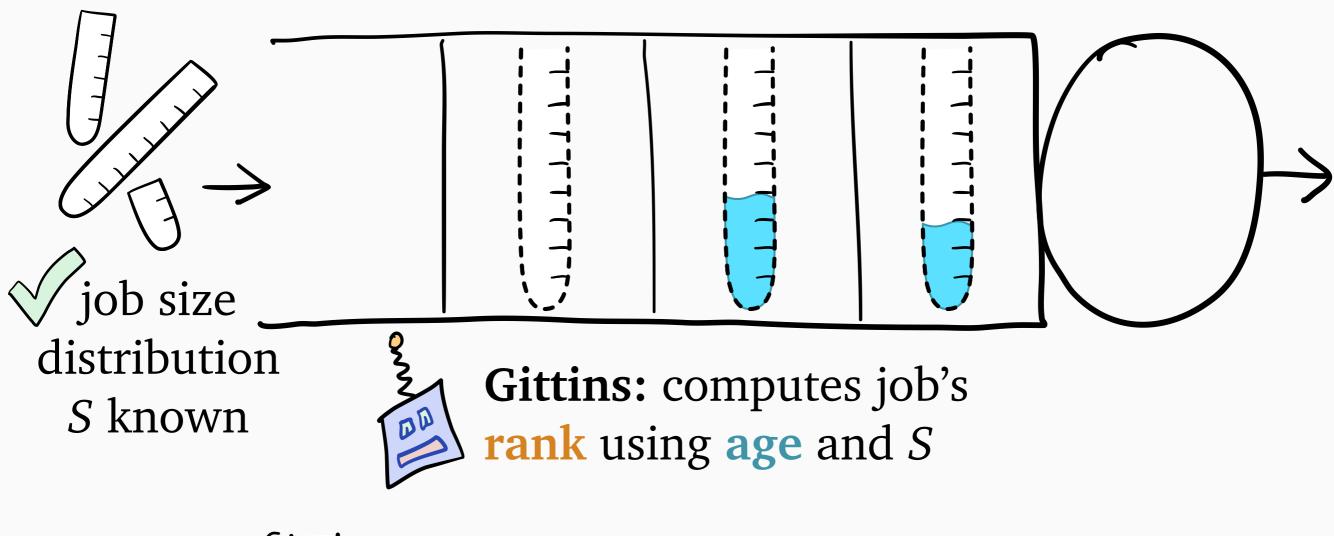


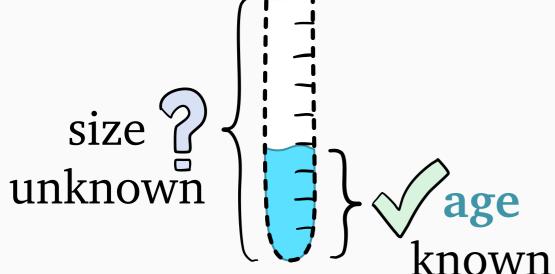


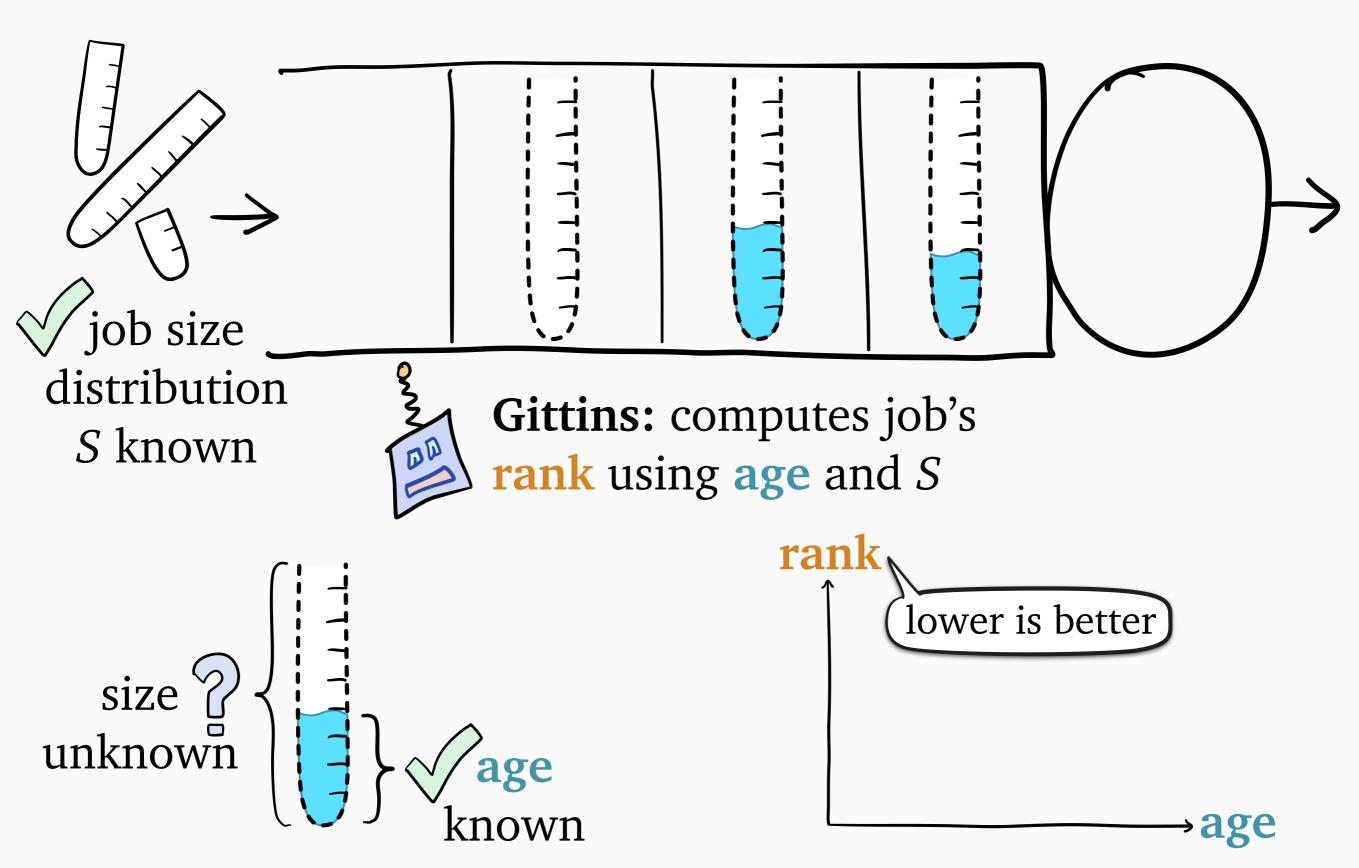


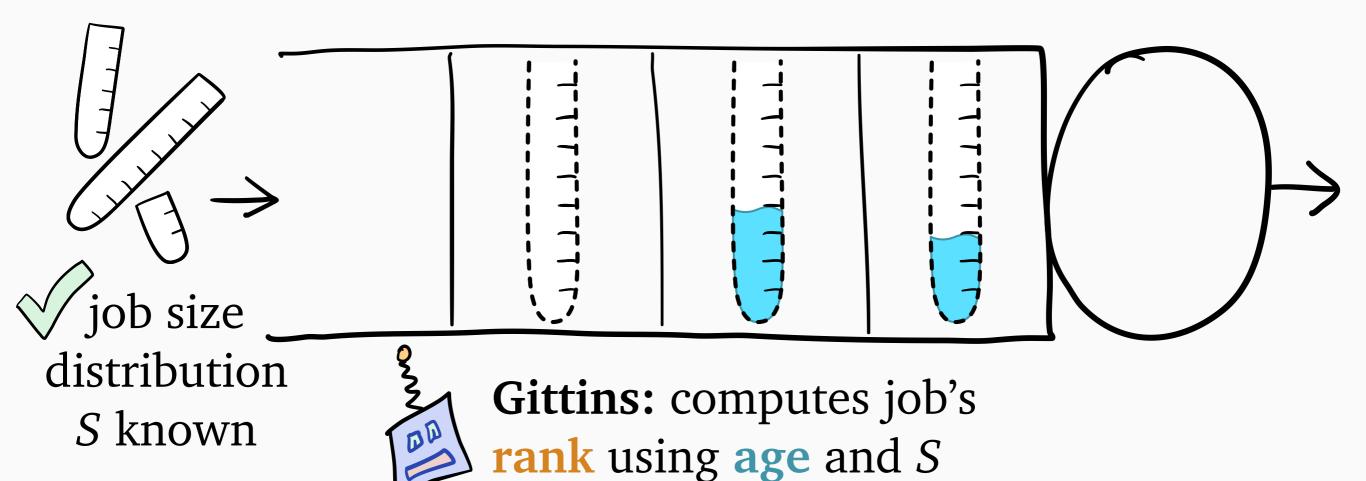
aistributioi S known

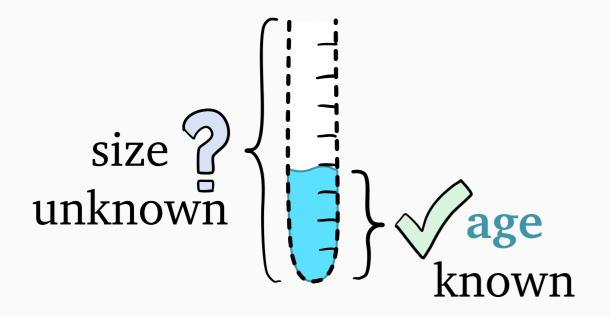


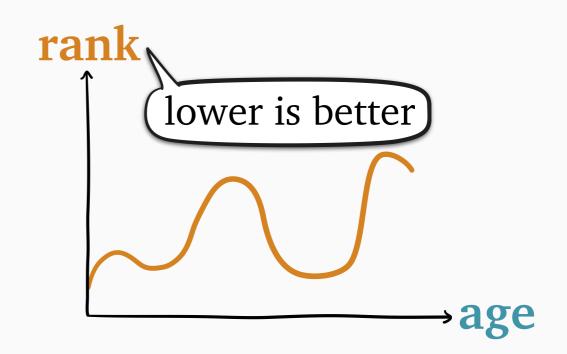


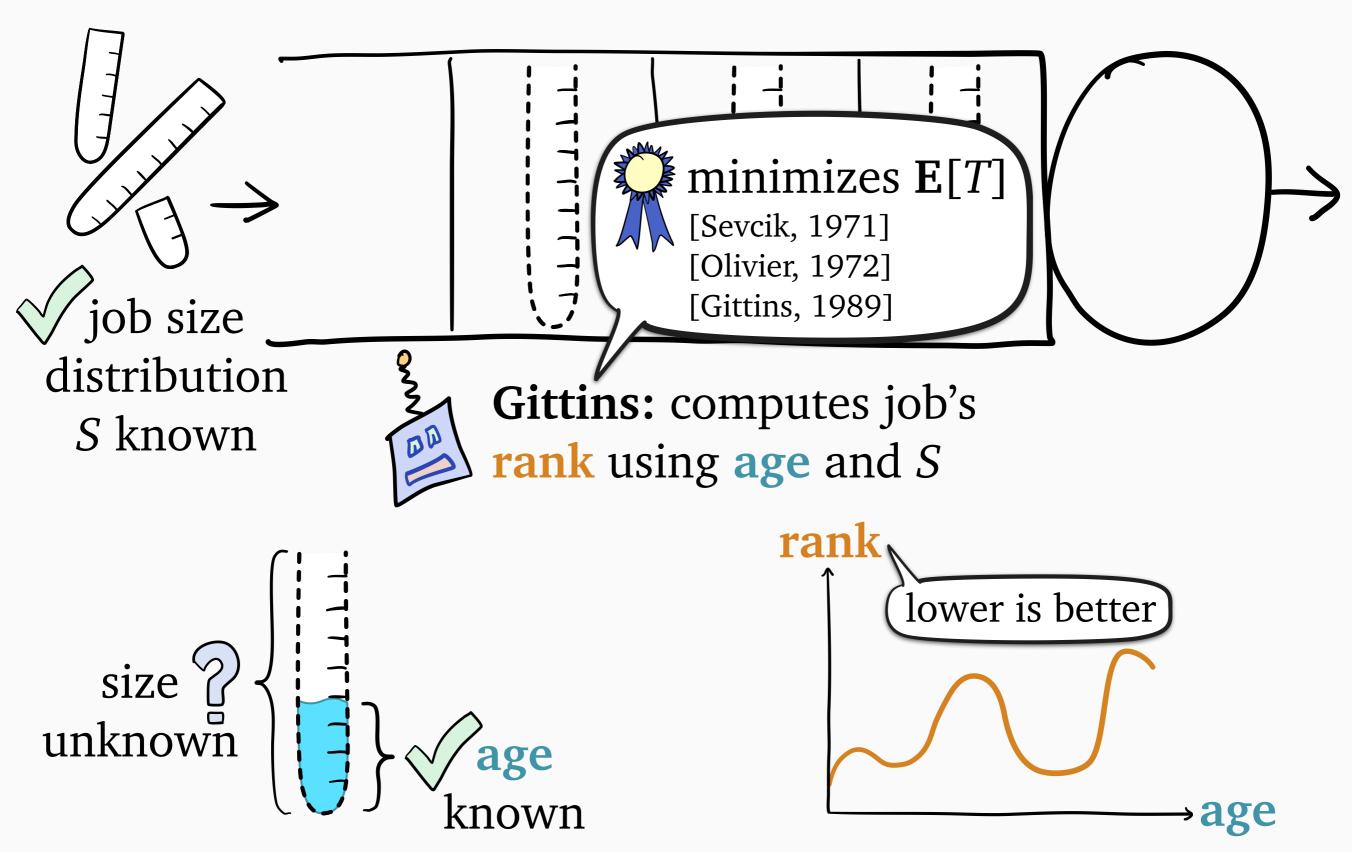












minimizes $\mathbf{E}[T]$

Size info:

unknown

Size distribution:

general

[Sevcik, 1971]

[Olivier, 1972]

Service:

preemptive

Size info:

unknown

Size distribution:

[Sevcik, 1971]

general

[Olivier, 1972]

Service:

preemptive

[Gittins, 1989]

Job weights:

equal, class-based

Job types:

Size info:

unknown

Size distribution:

general

[Sevcik, 1971]

[Olivier, 1972]

Service:

preemptive

[Gittins, 1989]

Job weights:

equal, class-based

Job types:

Size info:

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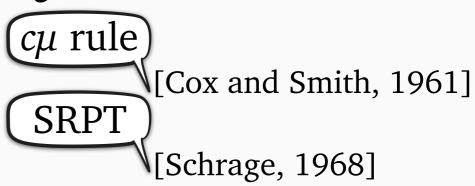
preemptive

Job weights:

equal, class-based, size-based

Job types:

all same, multiple classes



[Sevcik, 1971]

[Olivier, 1972]

Size info:

unknown, known

Size distribution:

general

Service:

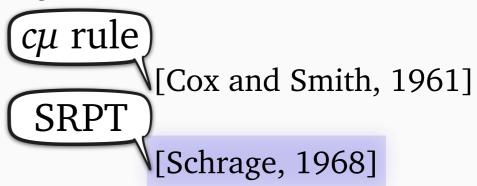
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Job weights:

equal, class-based, size-based

Job types:

all same, multiple classes



[Sevcik, 1971]

[Olivier, 1972]

Size info:

unknown, known

Size distribution:

general, exponential

Service:

preemptive

Job weights:

equal, class-based, size-based

Job types:

all same, multiple classes

Cμ rule

[Cox and Smith, 1961]

SRPT

[Schrage, 1968]

[Sevcik, 1971]

[Olivier, 1972]

Size info:

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Size distribution:

general, exponential

Service:

preemptive, nonpreemptive

Job weights:

equal, class-based, size-based

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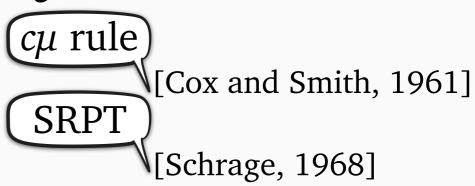
preemptive, nonpreemptive

Job weights:

equal, class-based, size-based

Job types:

all same, multiple classes, multistage



[Sevcik, 1971]

[Olivier, 1972]

[Klimov, 1975]

[Gittins, 1989]

[Lai and Ying, 1988]

Size info:

unknown, known

Size distribution:

general, exponential

Service:

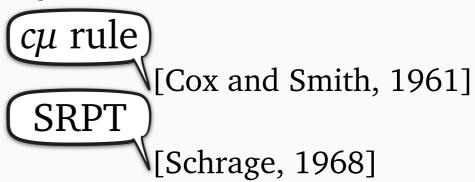
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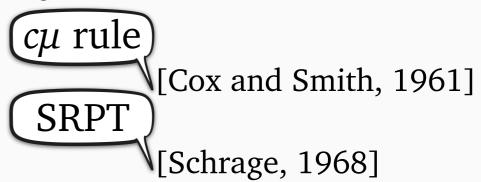
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[Cox and Smith, 1961]

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[Sevcik, 1971]

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[Klimov, 1975]

[Gittins, 1989]

[Lai and Ying, 1988]

[Bertsimas, 1995]

[Dacre et al., 1999]

[Whittle, 2007]

Size info:

unknown, known, noisily estimated?

Size distribution:

general, exponential

Service:

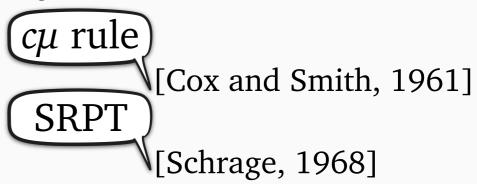
preemptive, nonpreemptive

Job weights:

equal, class-based, size-based

Job types:

all same, multiple classes, multistage



[Sevcik, 1971]

[Olivier, 1972]

[Klimov, 1975]

[Gittins, 1989]

[Lai and Ying, 1988]

[Bertsimas, 1995]

[Dacre et al., 1999]

[Whittle, 2007]

Size info:

Size distribution:

general, exponential

unknown, known, noisily estimated?

[Sevcik, 1971]

Schrage, 1968]

[Cox and Smith, 1961]

*c*μ rule

[Olivier, 1972]

Service: [Klimov, 1975]

preemptive, nonpreemptive, partly preemptive? [Gittins, 1989]

Job weights: [Lai and Ying, 1988]

equal, class-based, size-based [Bertsimas, 1995]

Job types: [Dacre et al., 1999]

all same, multiple classes, multistage [Whittle, 2007]

Size info:

Size distribution:

general, exponential

unknown, known, noisily estimated?

[Sevcik, 1971]

cμ rule

[Olivier, 1972]

Schrage, 1968]

[Cox and Smith, 1961]

Service:

preemptive, nonpreemptive, partly preemptive?

[Klimov, 1975]

[Gittins, 1989]

Job weights:

equal, class-based, size-based, non-constant?

[Lai and Ying, 1988]

[Dacre et al., 1999]

[Bertsimas, 1995]

Job types:

all same, multiple classes, multistage

[Whittle, 2007]

Size info:

unknown, known, noisily estimated?

[Sevcik, 1971]

[Schrage, 1968]

[Cox and Smith, 1961]

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[Olivier, 1972]

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[Lai and Ying, 1988]

[Bertsimas, 1995]

[Dacre et al., 1999]

[Whittle, 2007]

Size distribution:

general, exponential

Service:

preemptive, nonpreemptive, partly preemptive?

Job weights:

assuming finitely e-based, non-constant? many classes

Job types:

all same, multiple classes, multistage

Size info:

unknown, known, noisily estimated?

Cμ rule

[Cox and Smith, 1961]

SRPT

[Schrage, 1968]

Size distribution:

general, exponential

assuming upper

pr bound on job sizes e, partly preemptive?

[Sevcik, 1971]

[Olivier, 1972]

[Klimov, 1975]

[Gittins, 1989]

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Job types:

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[Lai and Ying, 1988]

[Bertsimas, 1995]

[Dacre et al., 1999]

[Whittle, 2007]

We unify and generalize all prior Gittins optimality results

Size info:

unknown, known, noisily estimated?

Size distribution:

general, exponential

Service:

preemptive, nonpreemptive, partly preemptive?

Job weights:

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Job types:

all same, multiple classes, multistage

[Cox and Smith, 1961]

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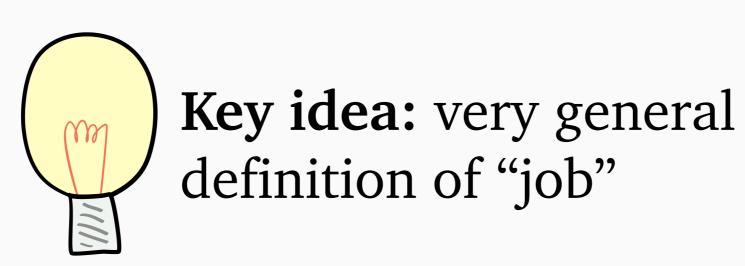
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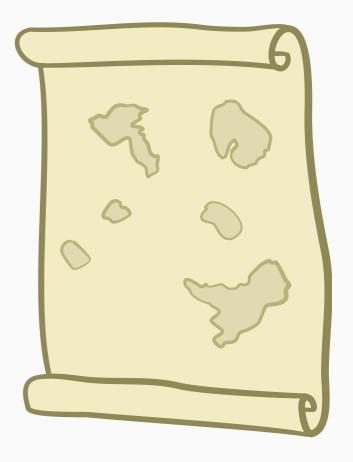
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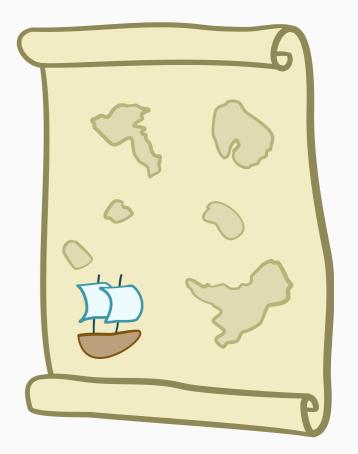






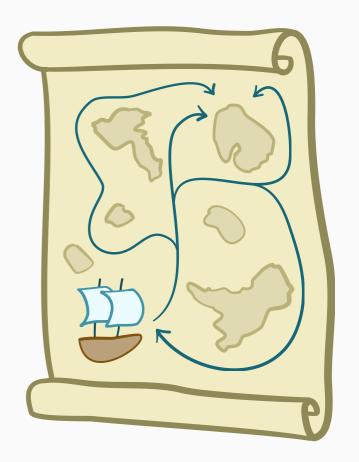






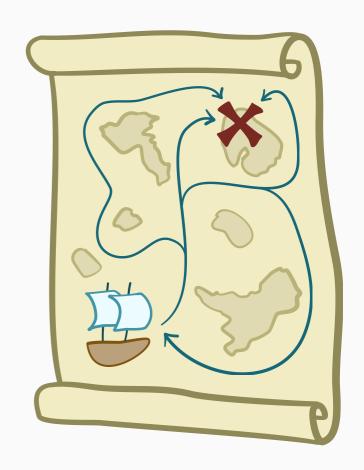


- general state space
- job's *state* encodes all known info
- state stochastically evolves with service





- general state space
- igob's state encodes all known info
- state stochastically evolves with service
- * completes upon entering goal state

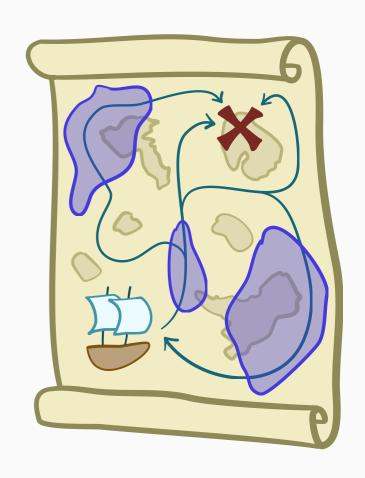


General Job Model



Key idea: a job is a Markov process

- general state space
- job's *state* encodes all known info
- state stochastically evolves with service
- * completes upon entering goal state
- set of nonpreemptible states

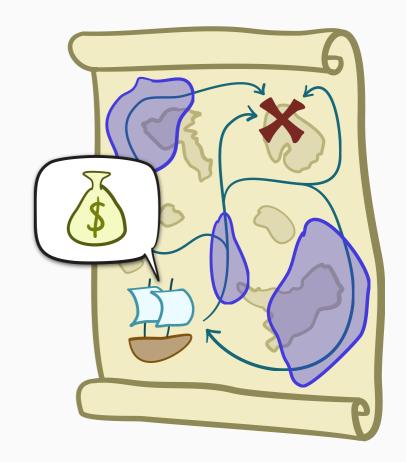


General Job Model



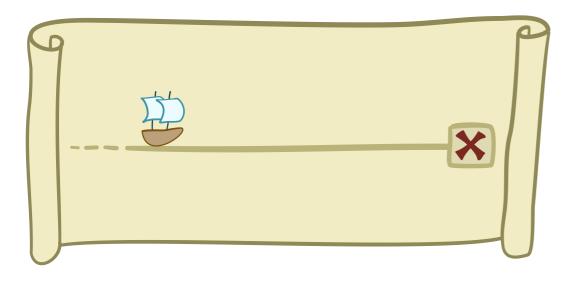
Key idea: a job is a Markov process

- general state space
- igob's state encodes all known info
- state stochastically evolves with service
- * completes upon entering goal state
- set of nonpreemptible states
- state has a holding cost



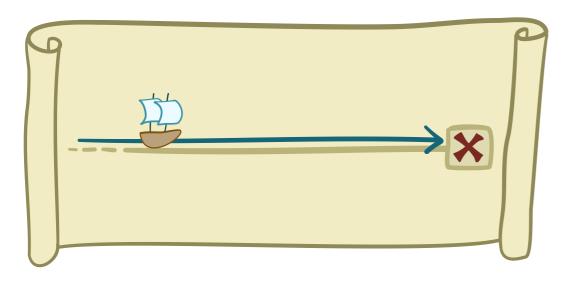
- general state space
- igob's **state** encodes all known info
- state stochastically evolves with service
- **★** completes upon entering *goal state*

Known Size state = remaining size



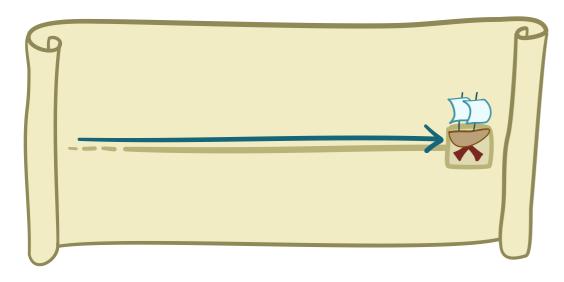
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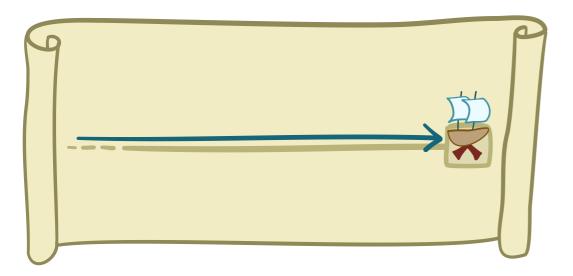
Known Size state = remaining size



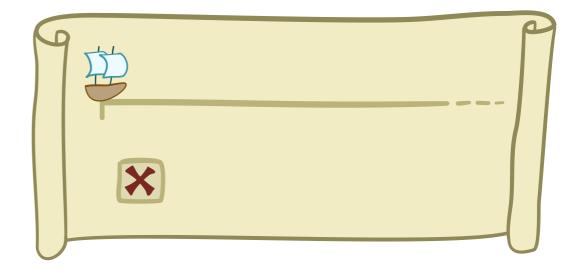
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Known Size

state = remaining size



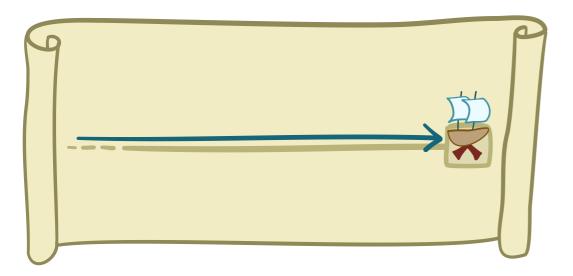
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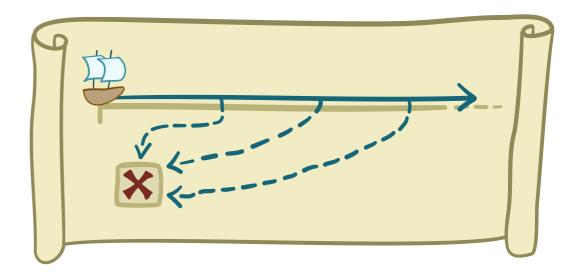
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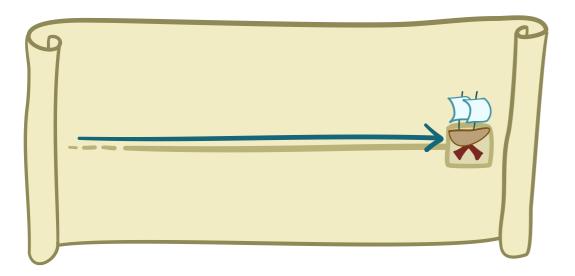
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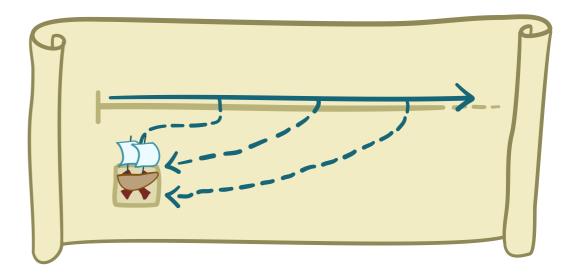
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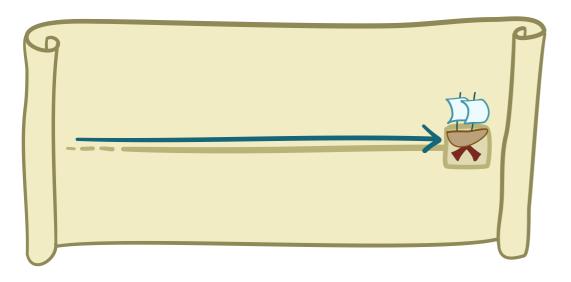
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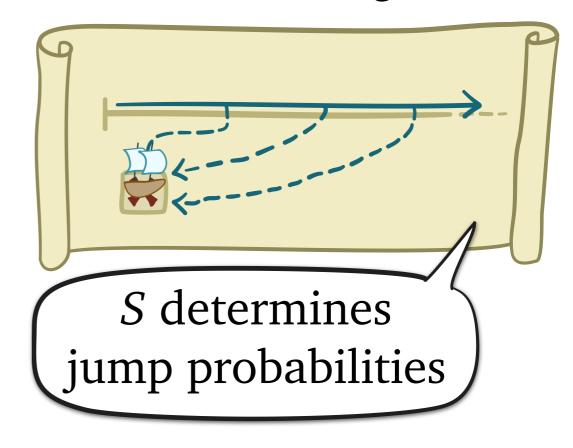
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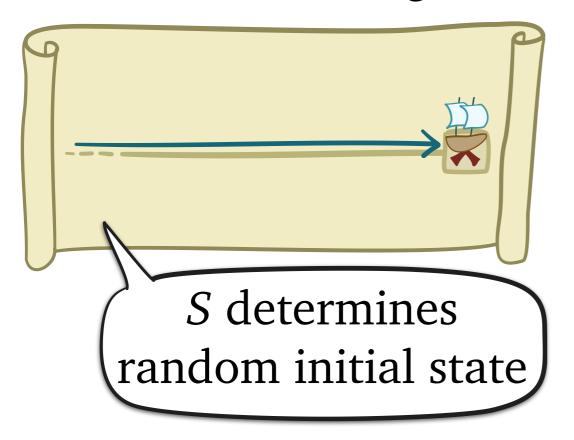
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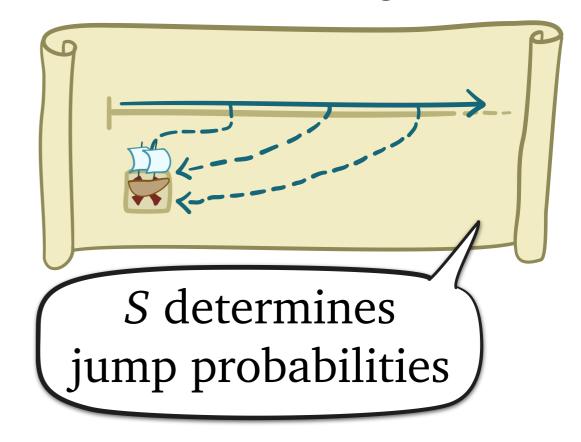
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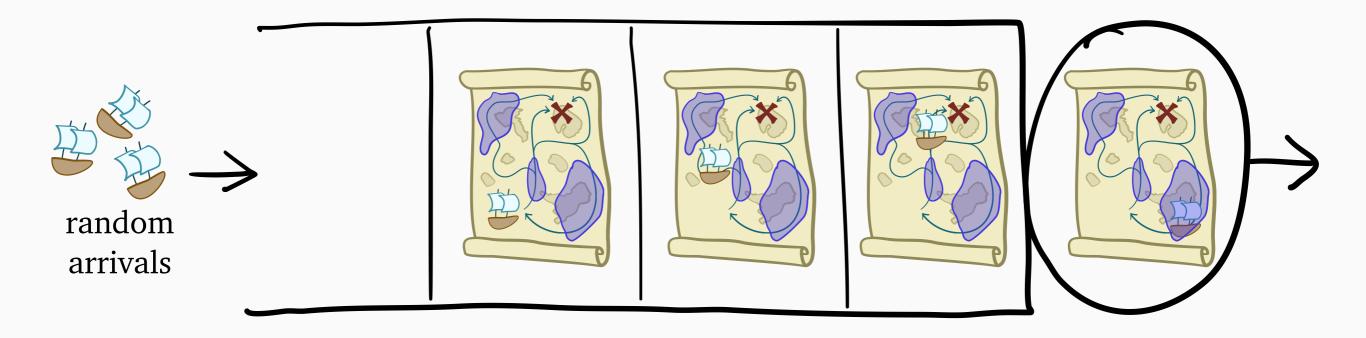
state = remaining size

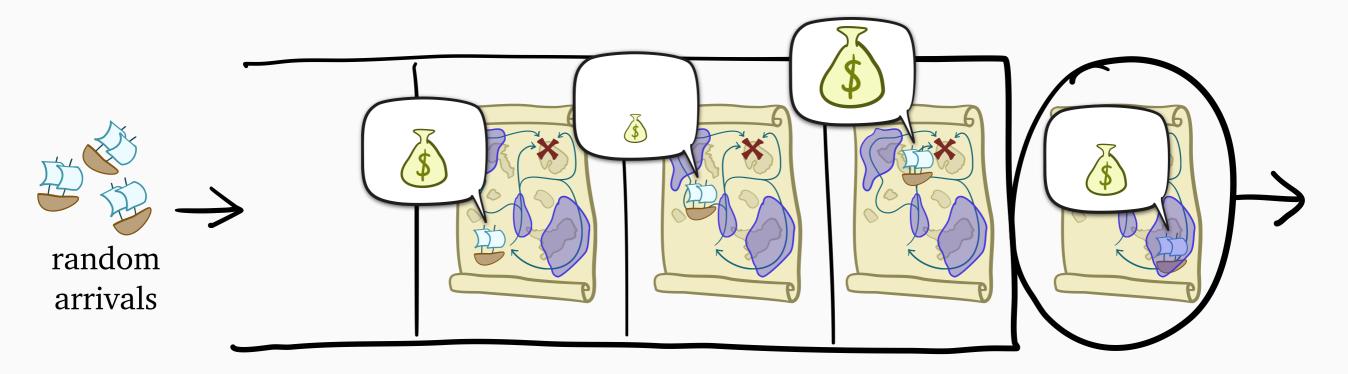


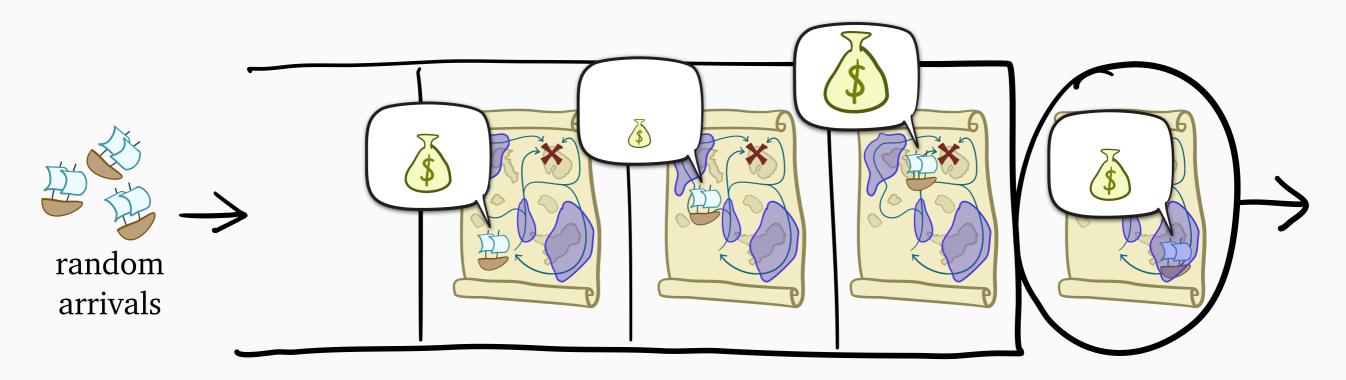
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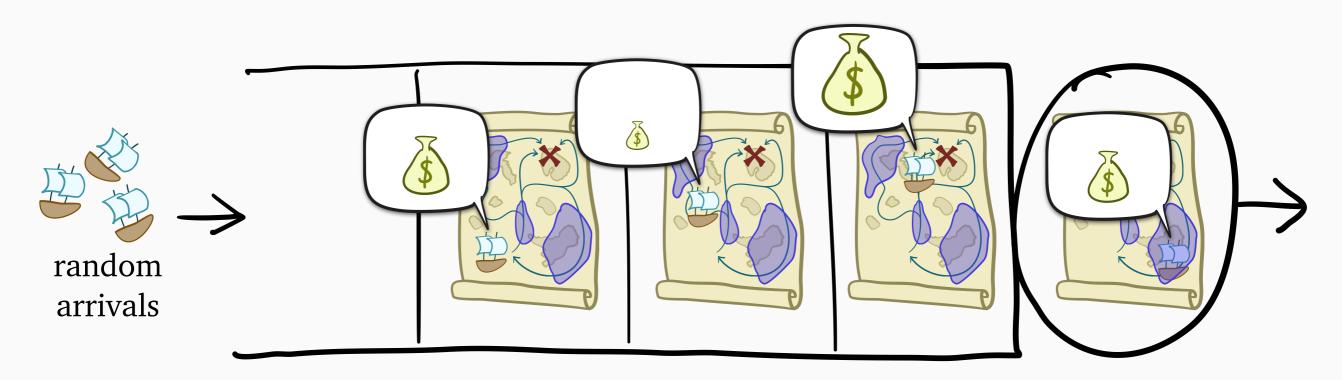
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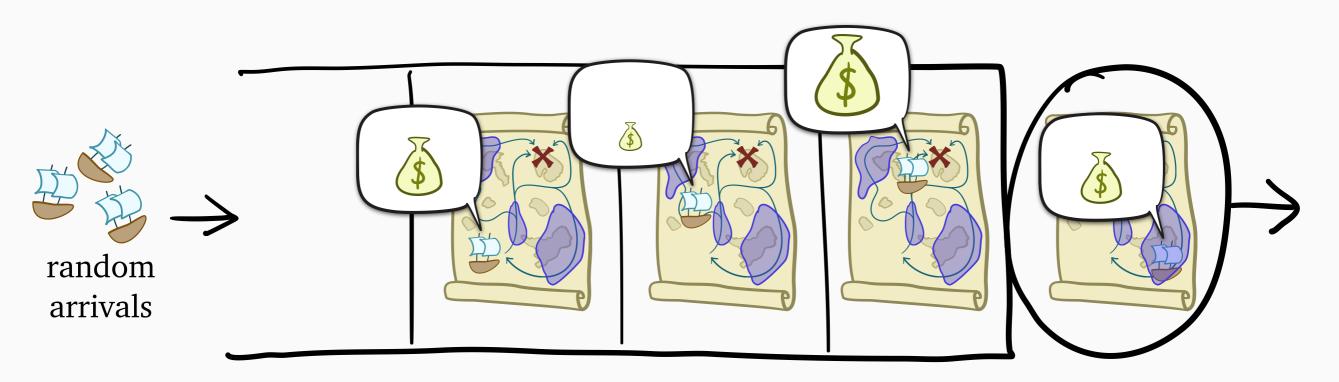


In paper:



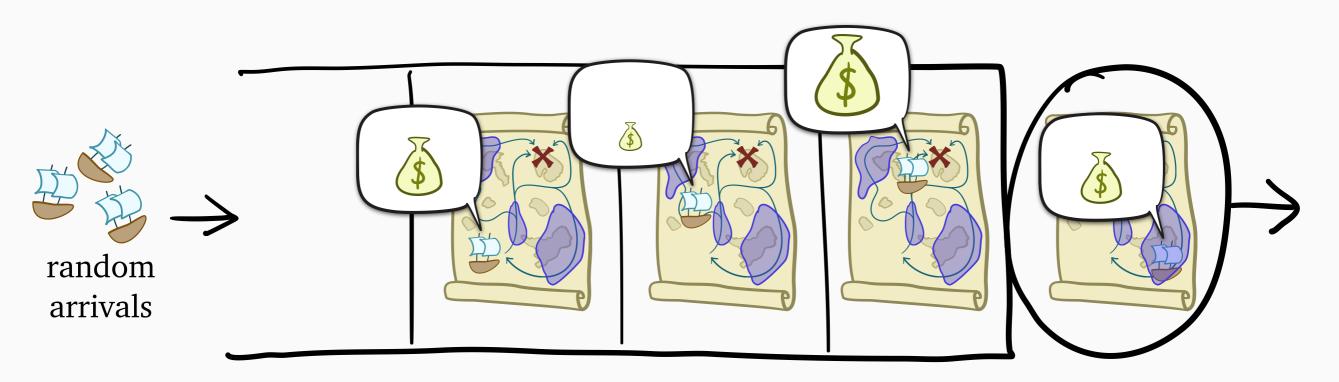
In paper:

How to define the rank of each state



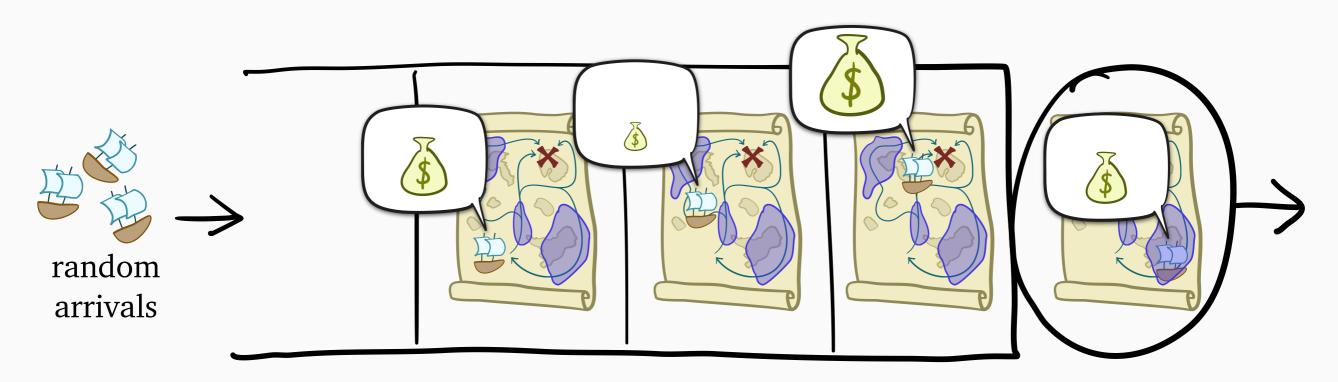
In paper:

- How to define the rank of each state
- Review of 10+ prior proofs



In paper:

- How to define the rank of each state
- Review of 10+ prior proofs
- New proof that handles general job model



In paper:

Today: re-prove by define the rank of each state SRPT's optimality w of 10+ prior proofs

New proof that handles general job model

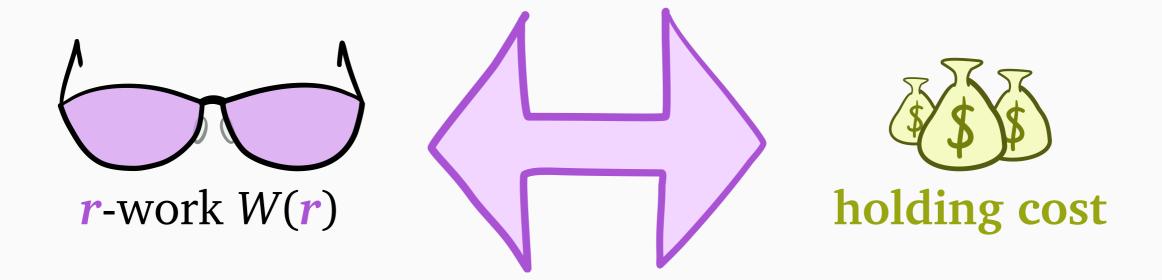






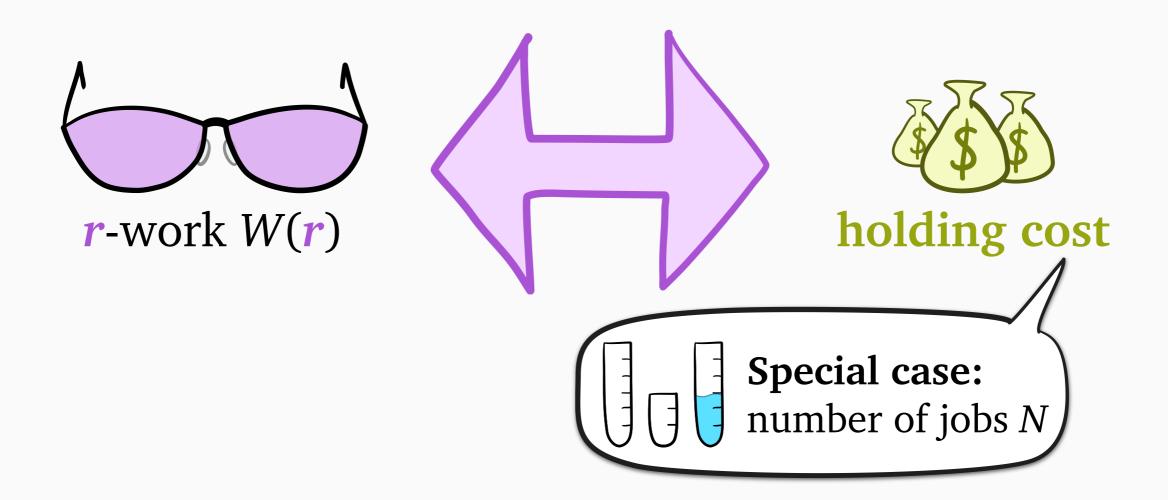


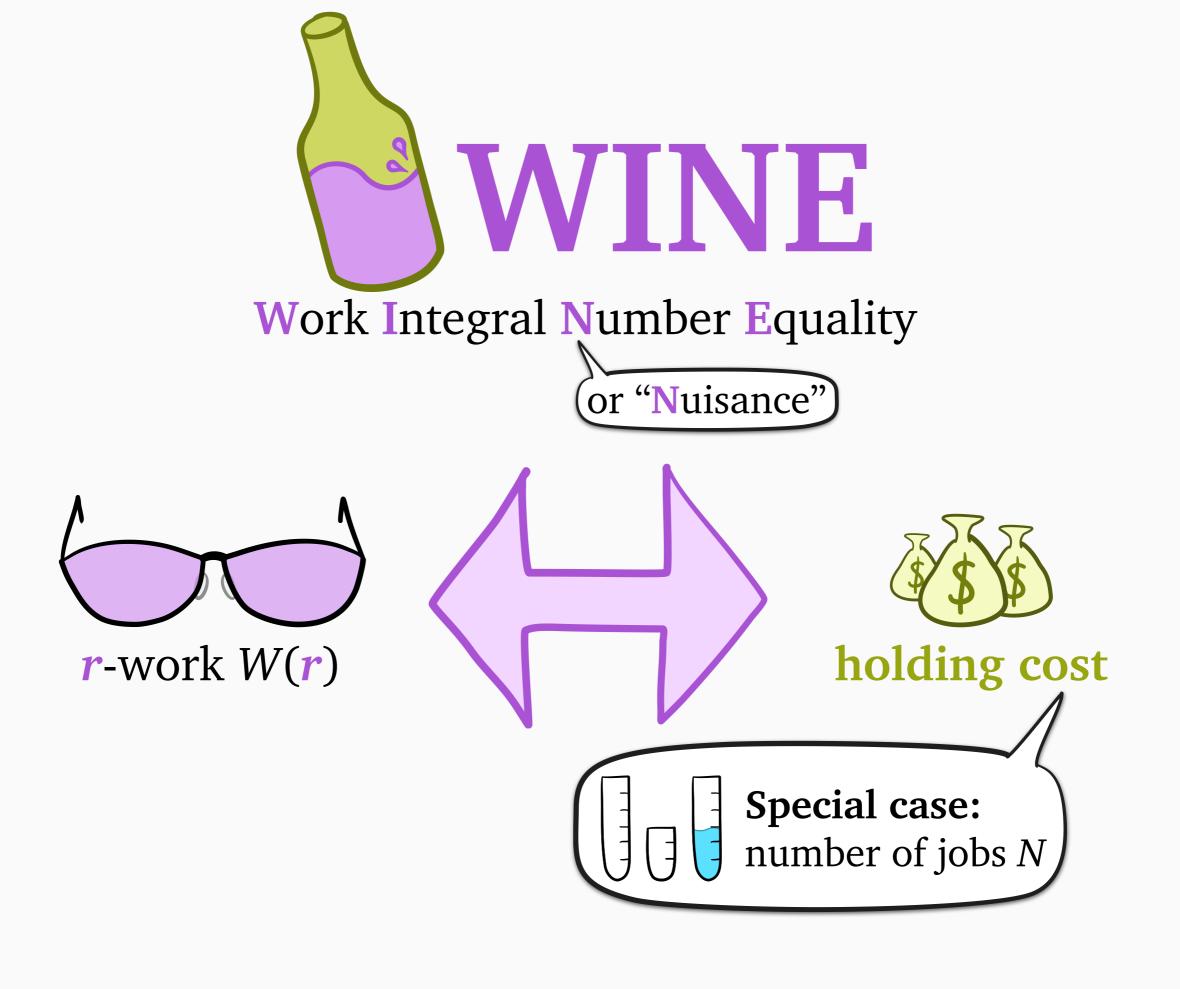






Work Integral Number Equality





Defining r-work for SRPT

for SRPT

rank = priority (lower is better)

rank = priority
(lower is better)

for SRPT

 $W(r) = \text{work relevant to } \frac{r}{r}$

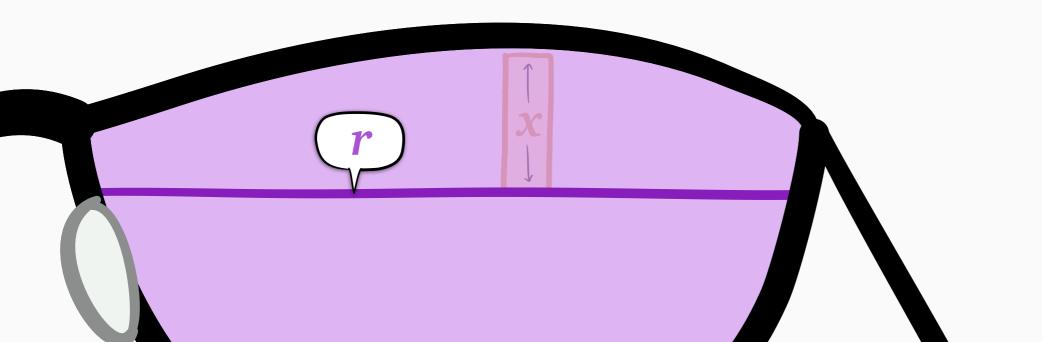
$$w_{\mathbf{x}}(\mathbf{r}) = \mathbf{r}$$
-work of single job of rem. size $\mathbf{x} = \left\{ \right.$



rank = priority
(lower is better)

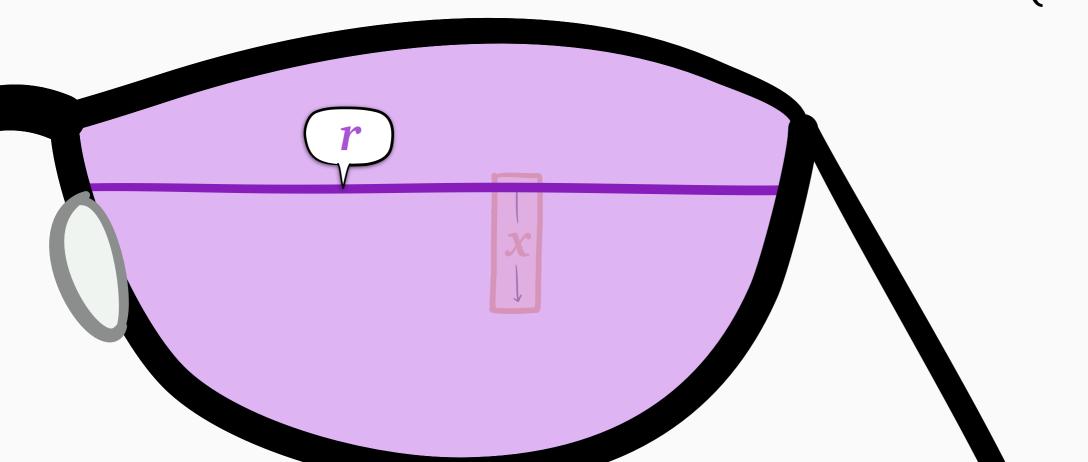
(for SRPT)

$$w_x(r) = r$$
-work of single job of rem. size $x = \begin{cases} 1 & \text{we seed } \\ 1 & \text{we seed } \end{cases}$

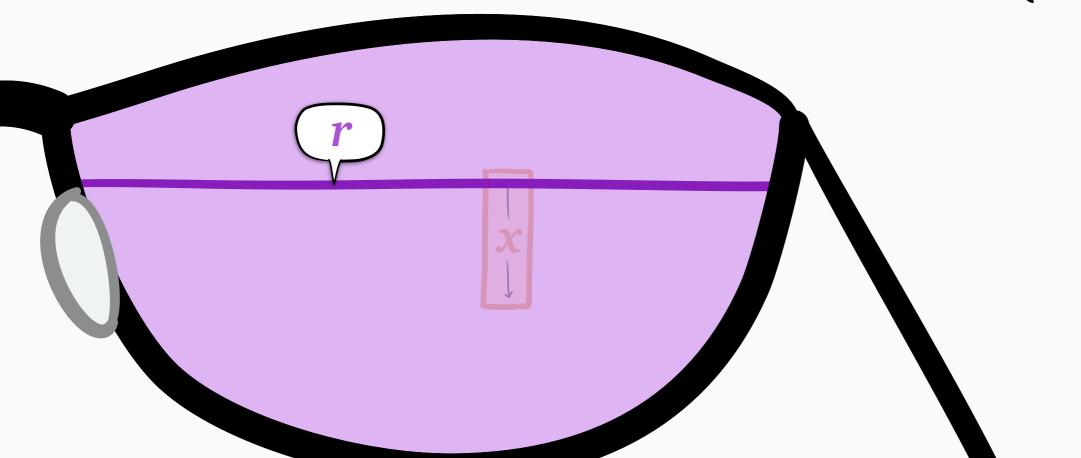


Defining r-work rank = priority (lower is better) respectively for SRPT

$$w_x(r) = r$$
-work of single job of rem. size $x = \begin{cases} 1 & \text{we seed } \\ 1 & \text{we seed } \end{cases}$



$$w_{\mathbf{x}}(\mathbf{r}) = \mathbf{r}$$
-work of single job of rem. size $\mathbf{x} = \begin{cases} 0 & \text{if } \mathbf{r} < \mathbf{x} \\ \end{cases}$

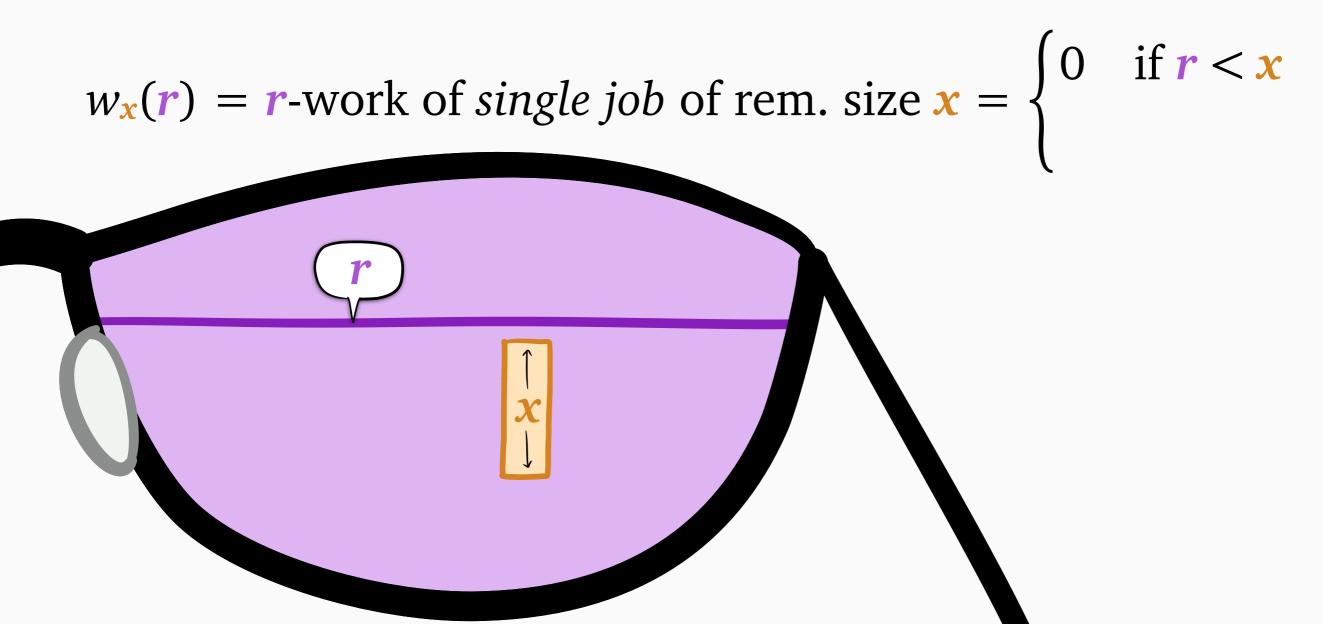


Defining r-work rank = priority (lower is better) respectively for SRPT

W(r) = work relevant to rank r

 $w_{\mathbf{x}}(\mathbf{r}) = \mathbf{r}$ -work of single job of rem. size $\mathbf{x} = \begin{cases} 0 & \text{if } \mathbf{r} < \mathbf{x} \\ 0 & \text{of } \mathbf{r} < \mathbf{x} \end{cases}$

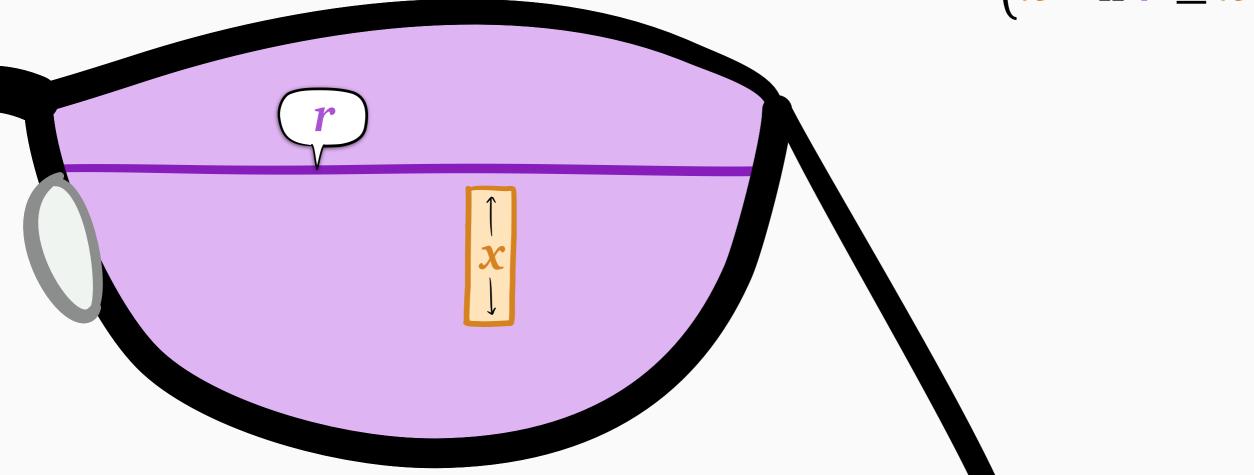
Defining r-work rank = priority (lower is better) for SRPT



Defining r-work rank = priority (lower is better) rank rank for SRPT

 $W(r) = \text{work relevant to } \frac{\mathbf{r}}{\mathbf{r}}$

$$w_{\mathbf{x}}(r) = r$$
-work of single job of rem. size $\mathbf{x} = \begin{cases} 0 & \text{if } r < \mathbf{x} \\ \mathbf{x} & \text{if } r \ge \mathbf{x} \end{cases}$



rank = priority
(lower is better)

for SRPT)

 $W(r) = \text{work relevant to } \frac{r}{r}$

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rank = priority (lower is better)

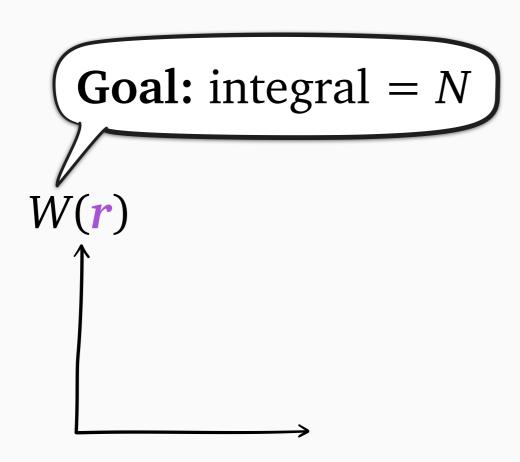
for SRPT

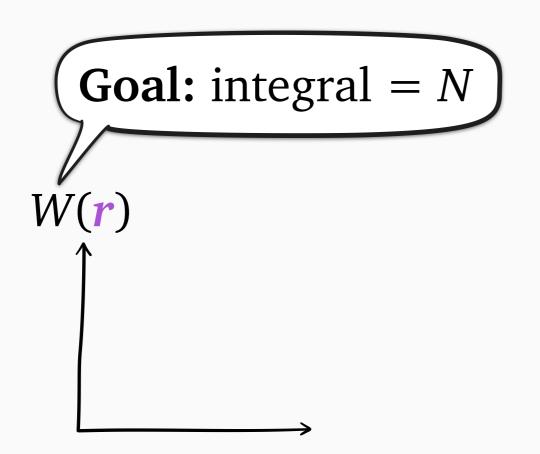
W(r) = work relevant to rank r= total r-work of all jobs

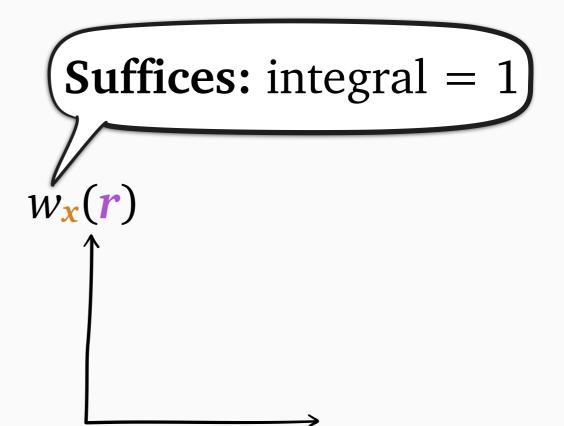
$$w_x(r) = r$$
-work of single job of rem. size $x = \begin{cases} 0 & \text{if } r < x \\ x & \text{if } r \ge x \end{cases}$



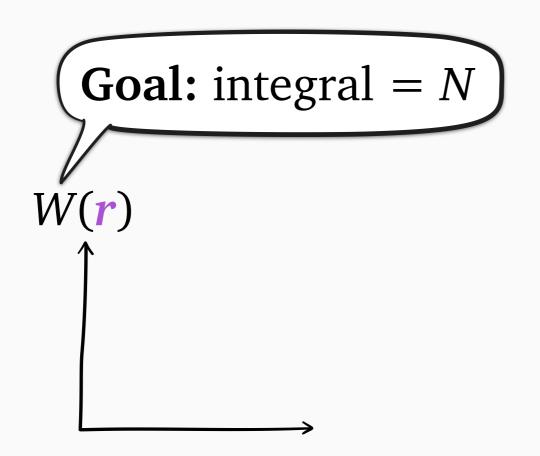
From *r*-work to number of jobs *N*

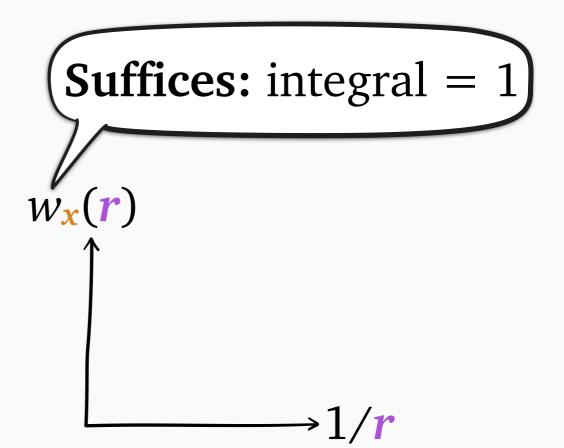




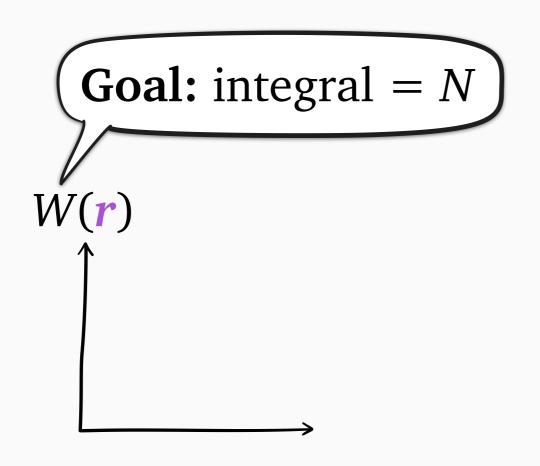


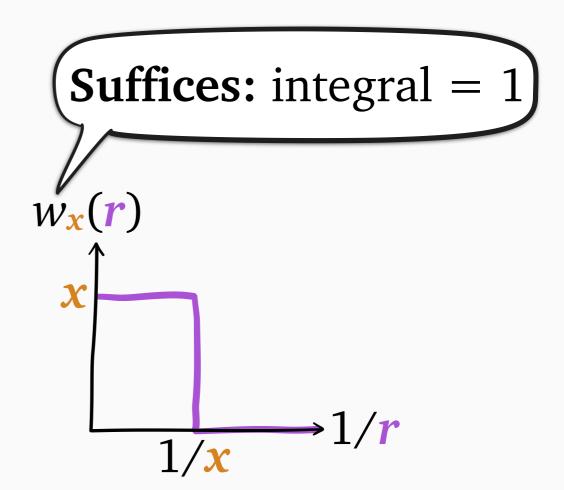
$$w_{\mathbf{x}}(r) = r$$
-work of job of rem. size $\mathbf{x} = \begin{cases} 0 & \text{if } r < \mathbf{x} \\ \mathbf{x} & \text{if } r \ge \mathbf{x} \end{cases}$



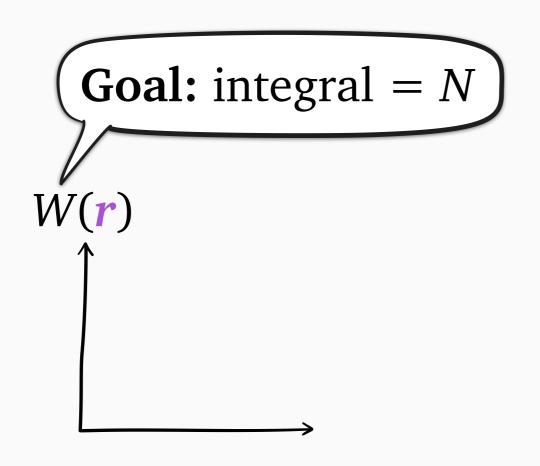


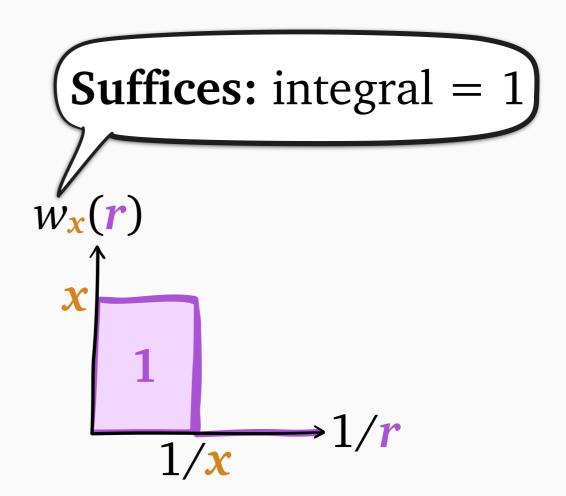
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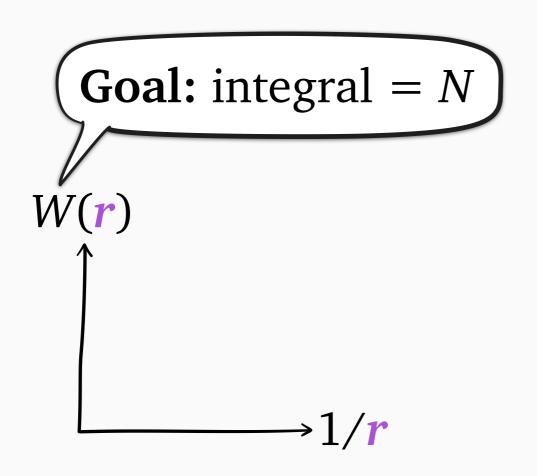


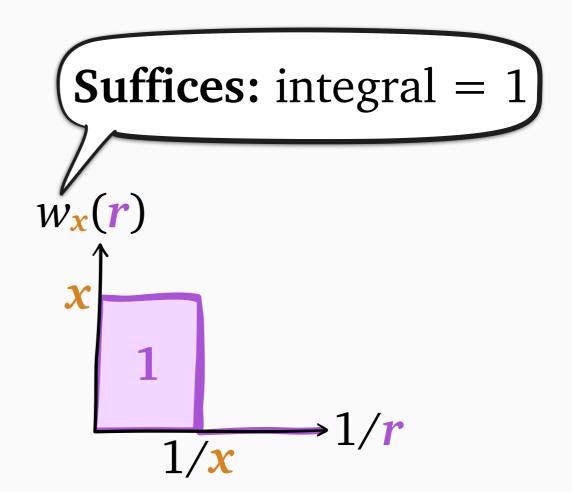
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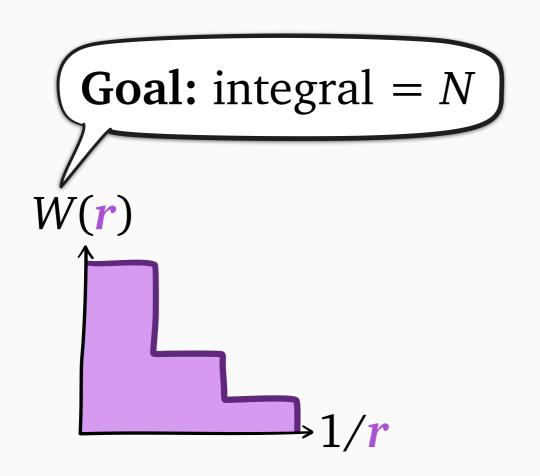


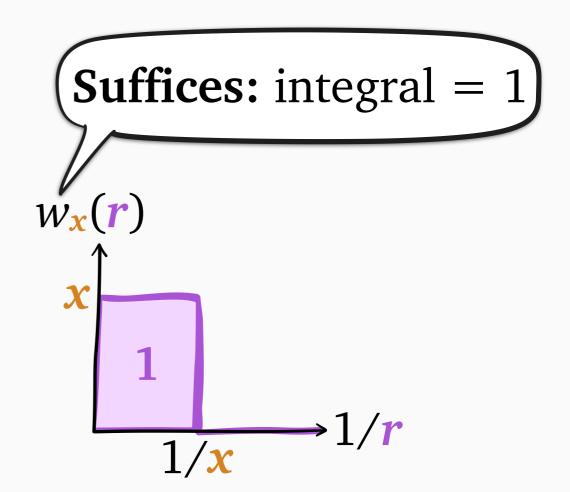
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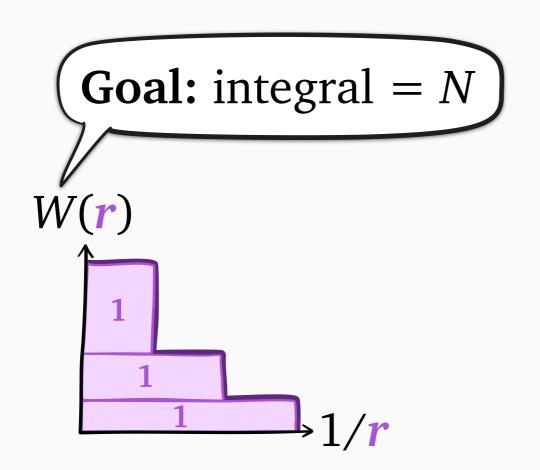


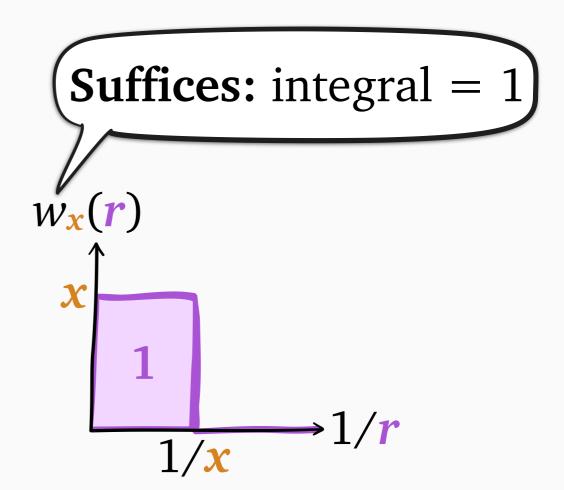
$$w_{\mathbf{x}}(\mathbf{r}) = \mathbf{r}$$
-work of $\mathbf{j}\mathbf{o}\mathbf{b}$ of rem. size $\mathbf{x} = \begin{cases} 0 & \text{if } \mathbf{r} < \mathbf{x} \\ \mathbf{x} & \text{if } \mathbf{r} \ge \mathbf{x} \end{cases}$



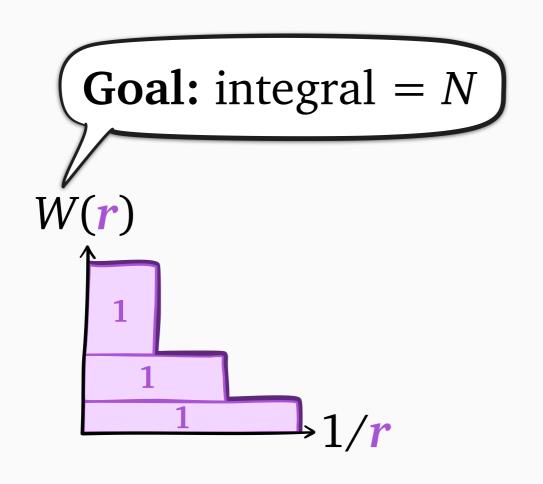


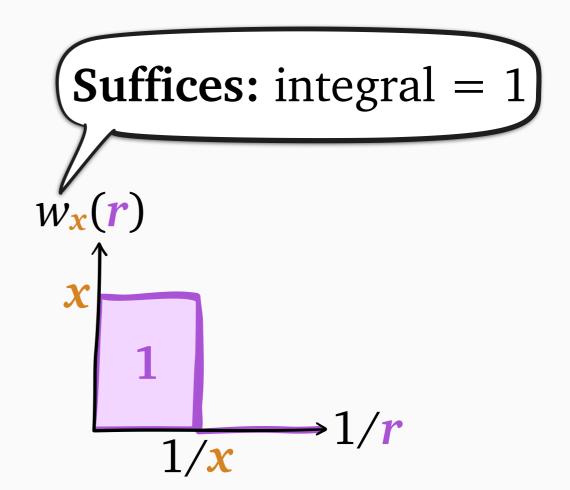
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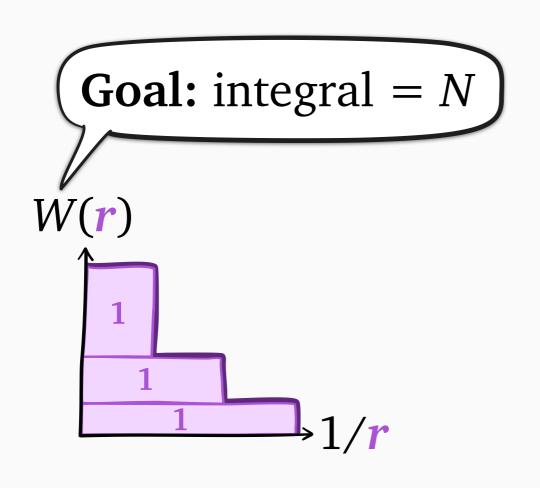


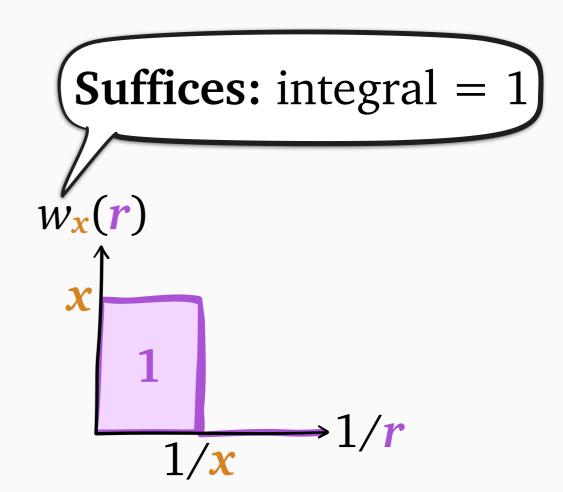
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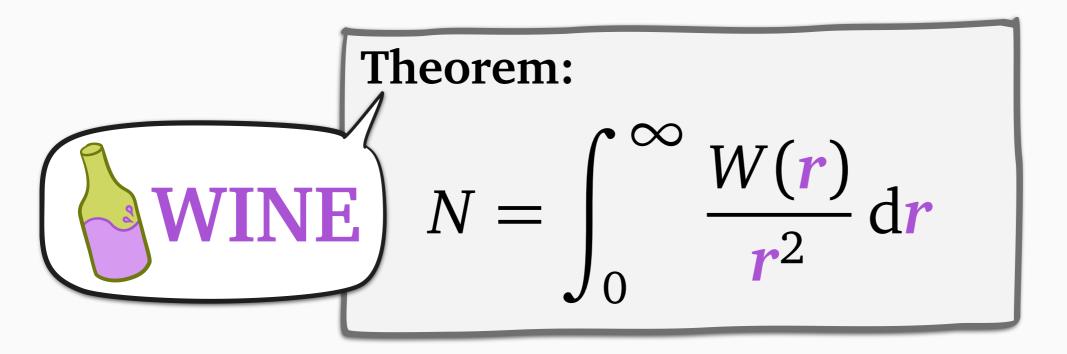


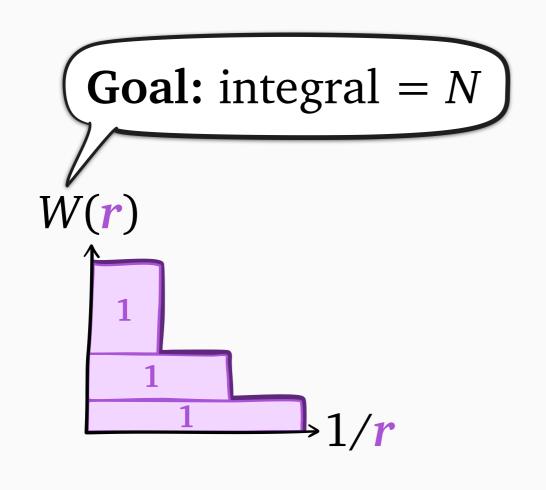


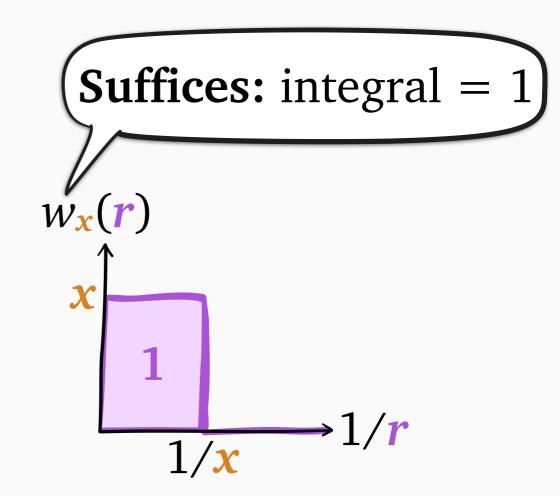
Theorem:
$$N = \int_0^\infty \frac{W(r)}{r^2} dr$$

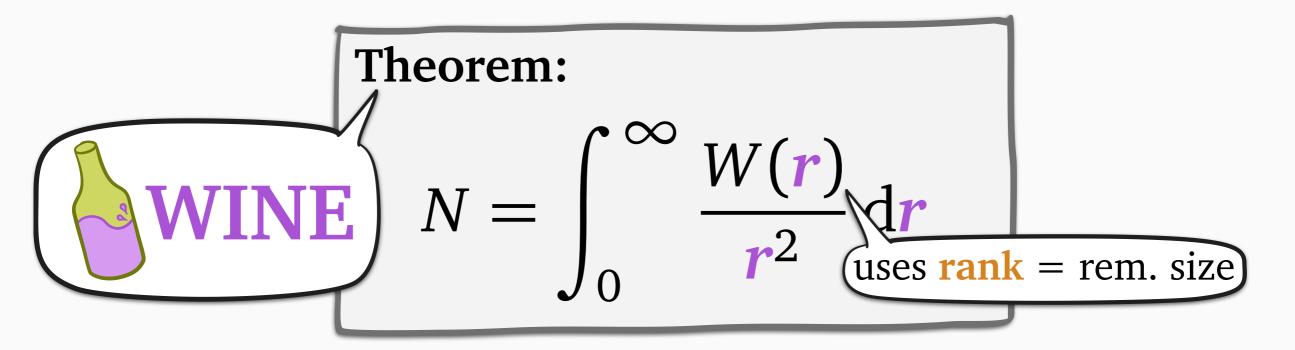


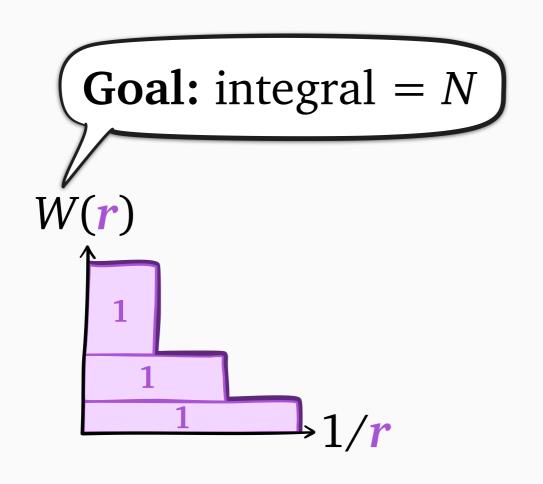


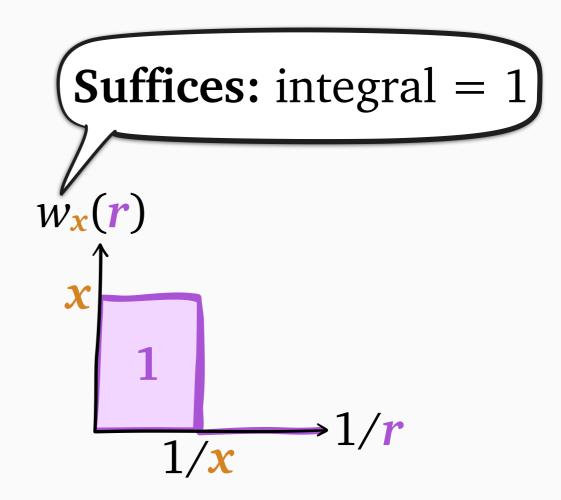


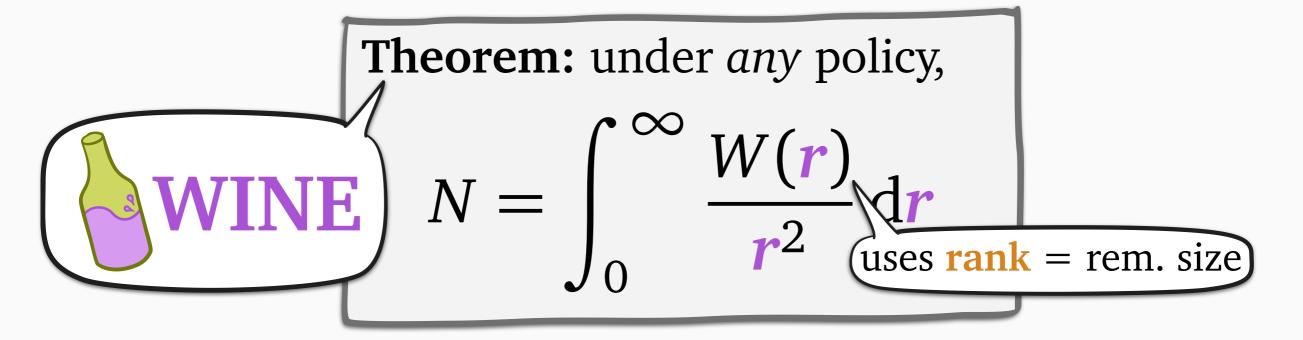




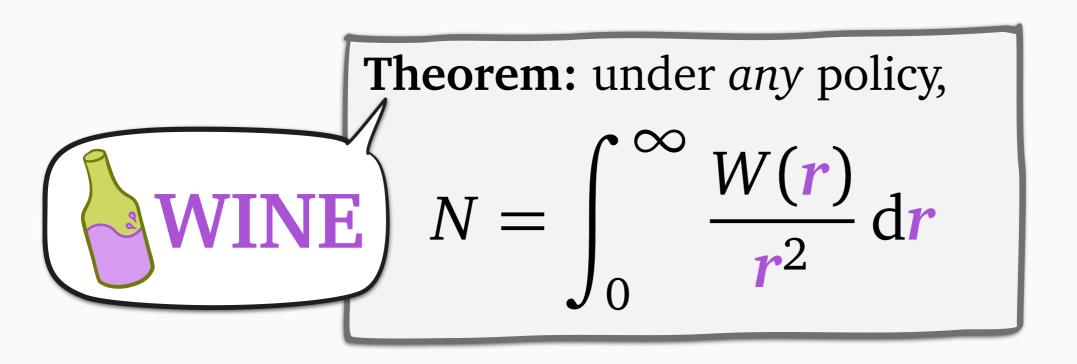




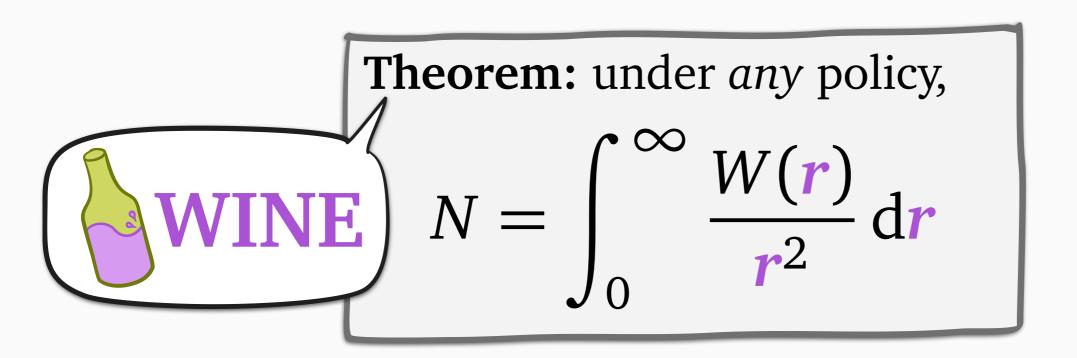




Optimality of SRPT

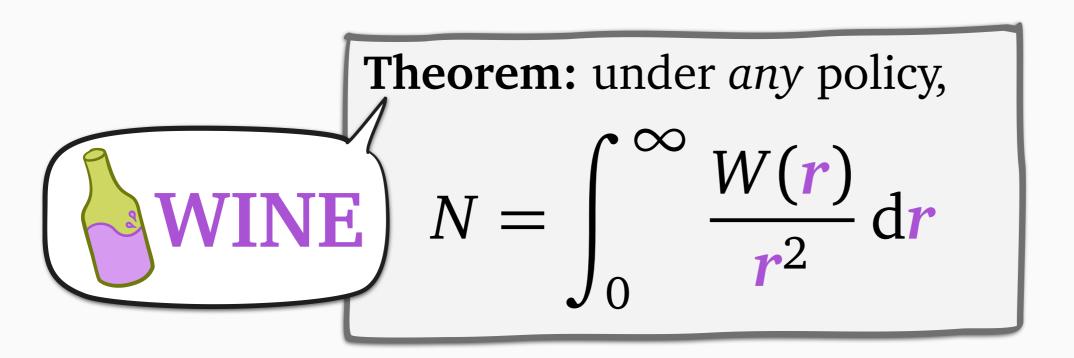


Optimality of SRPT



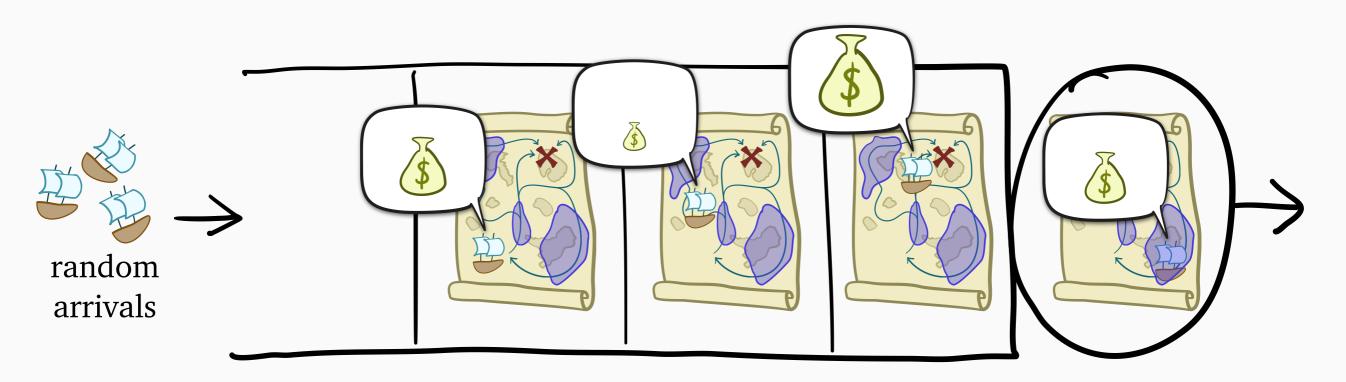
Why does SRPT minimize E[N] in M/G/1?

Optimality of SRPT



Why does SRPT minimize E[N] in M/G/1? Because it minimizes E[W(r)] for all r!

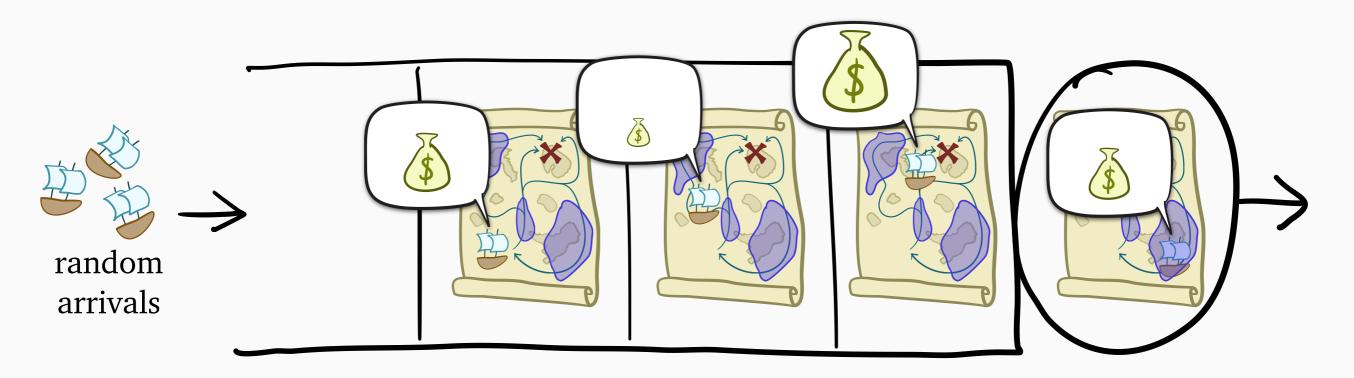
Theorem: Gittins minimizes mean holding cost in M/G/1



In paper:

- How to define the rank of each state
- Review of 10+ prior proofs
- New proof that handles general job model

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