

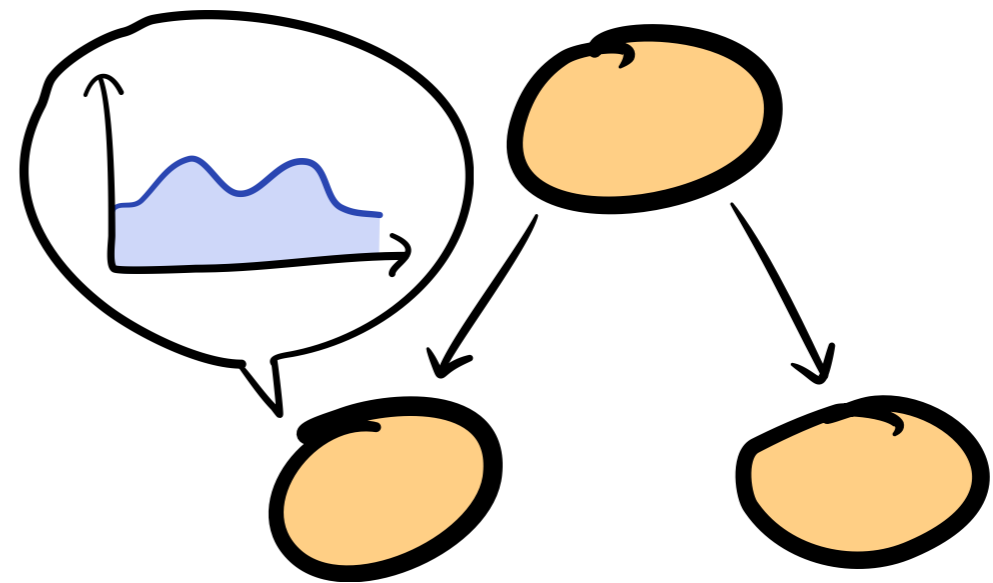
*Optimal Scheduling and Exact  
Response Time Analysis for*  
**Multistage Jobs**

Ziv Scully

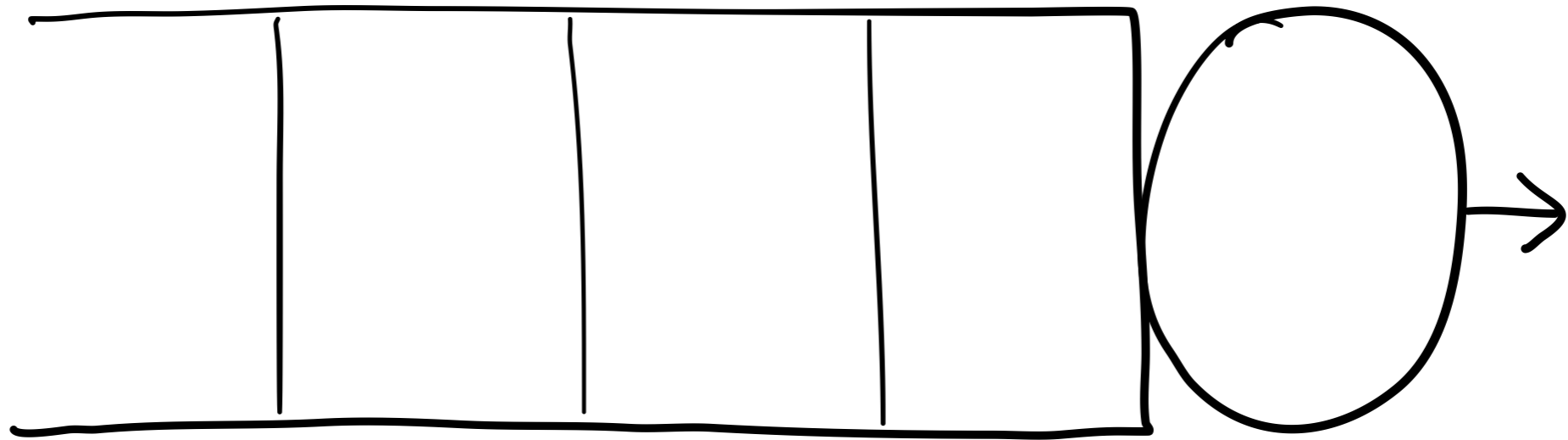
Mor Harchol-Balter

Alan Scheller-Wolf

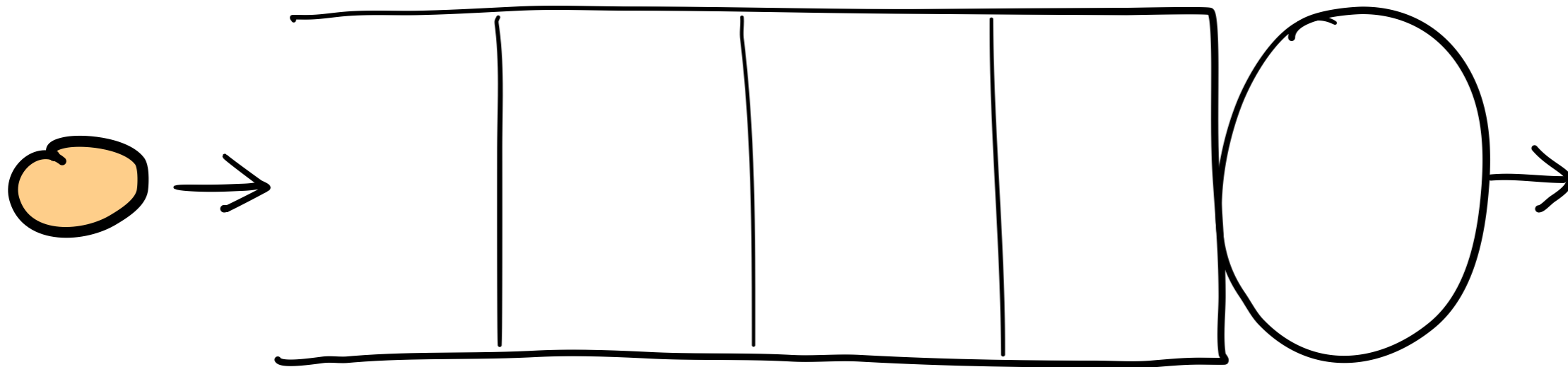
Carnegie Mellon University



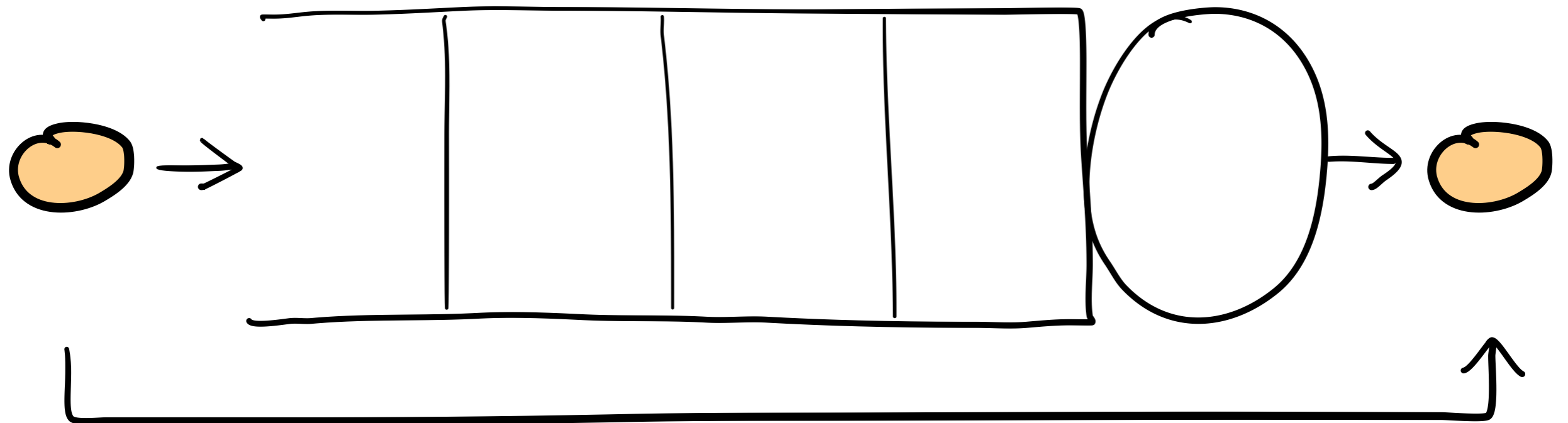
# Response Time




# Response Time

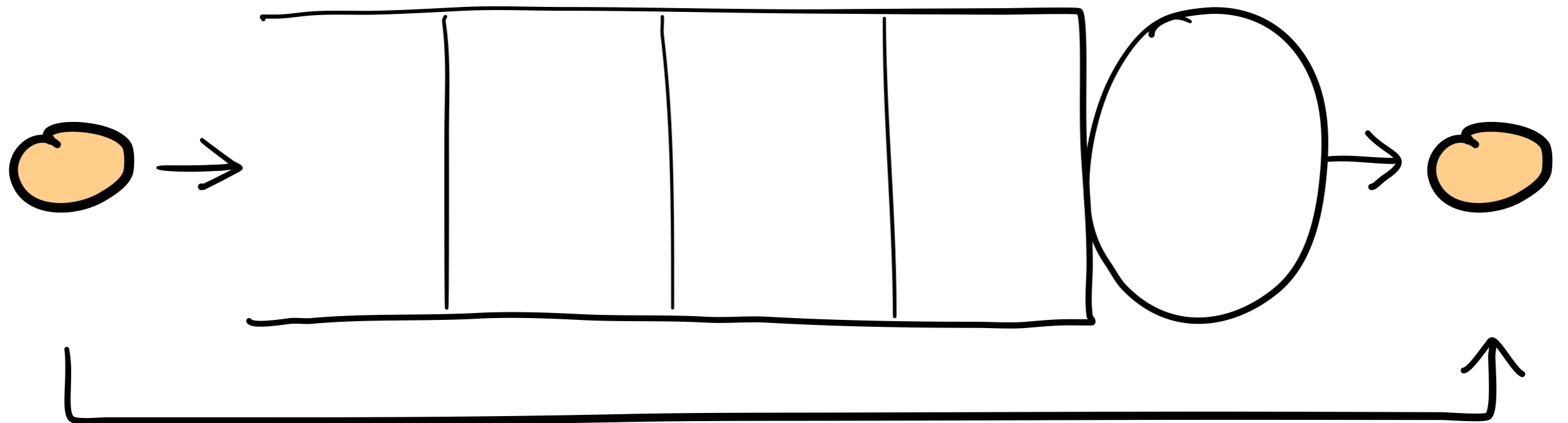



# Response Time



 =  $T$  = *response time*

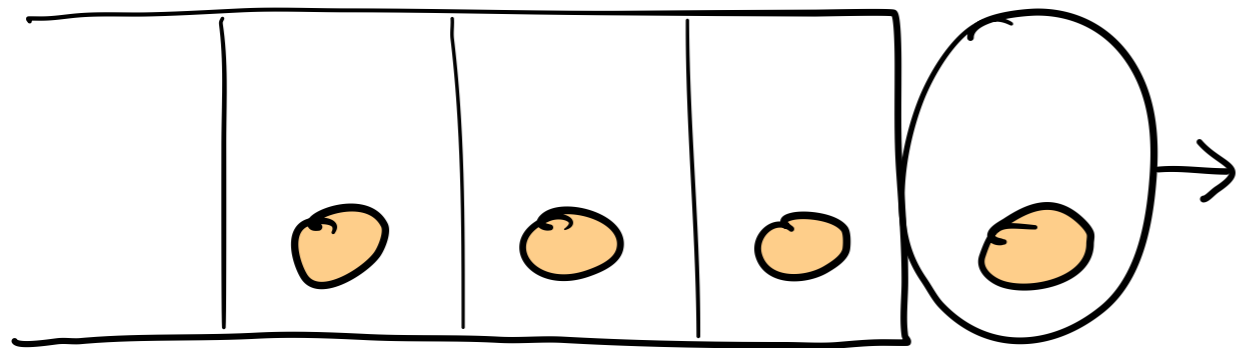
# Response Time



 =  $T$  = *response time*

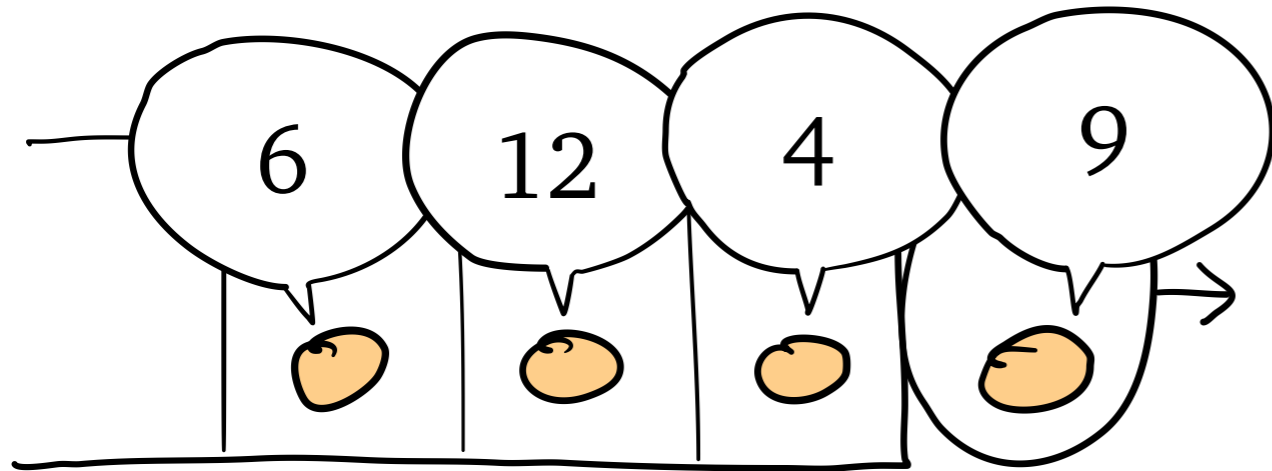
**Goal:** schedule to minimize  
*mean response time*  $\mathbf{E}[T]$

# Perfect Information



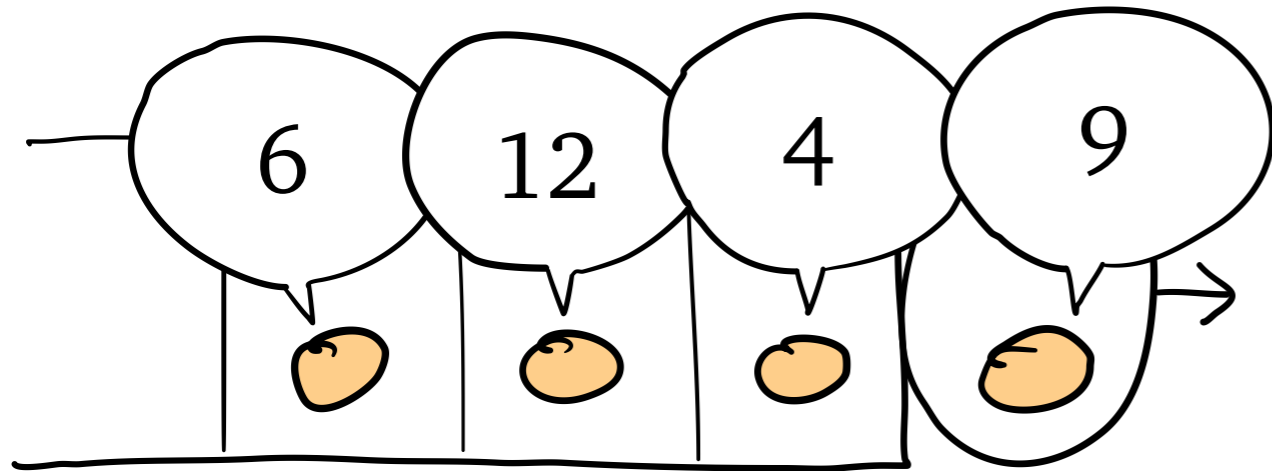
Known job sizes

# Perfect Information



Known job sizes

# Perfect Information

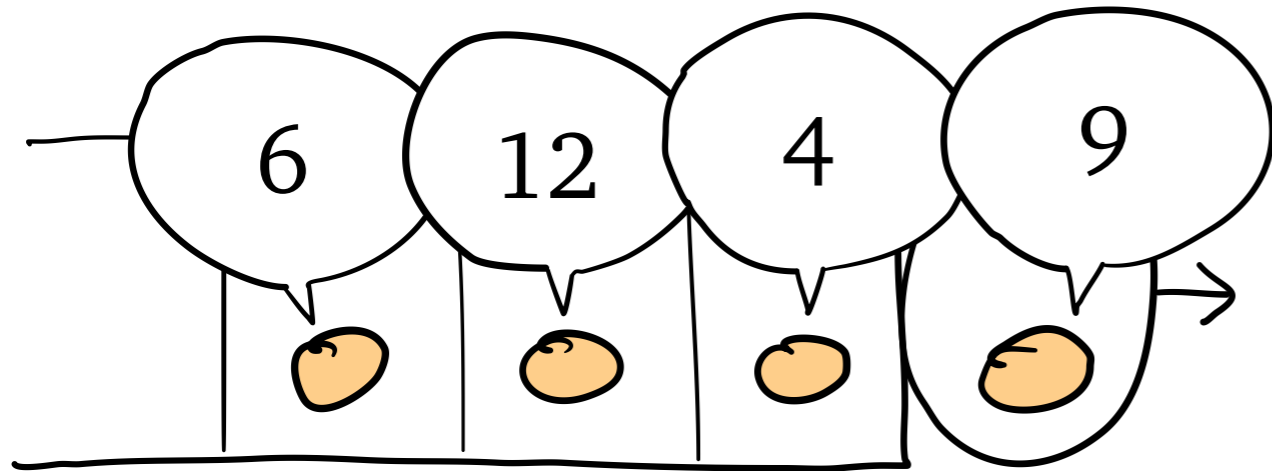


Known job sizes

Optimal policy: *SRPT*  
(serve job of smallest *remaining size*)



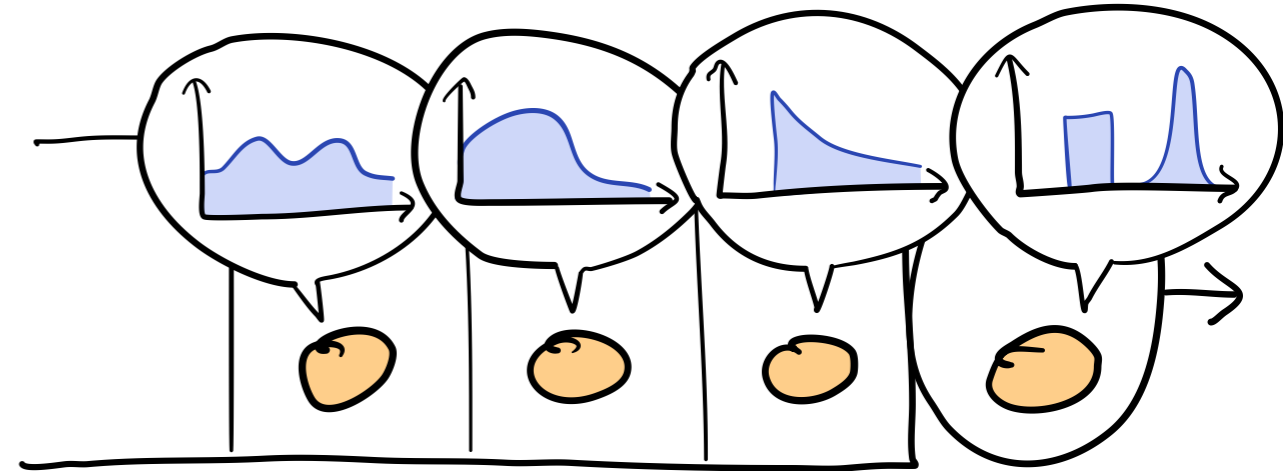
# Perfect Information



Known job sizes

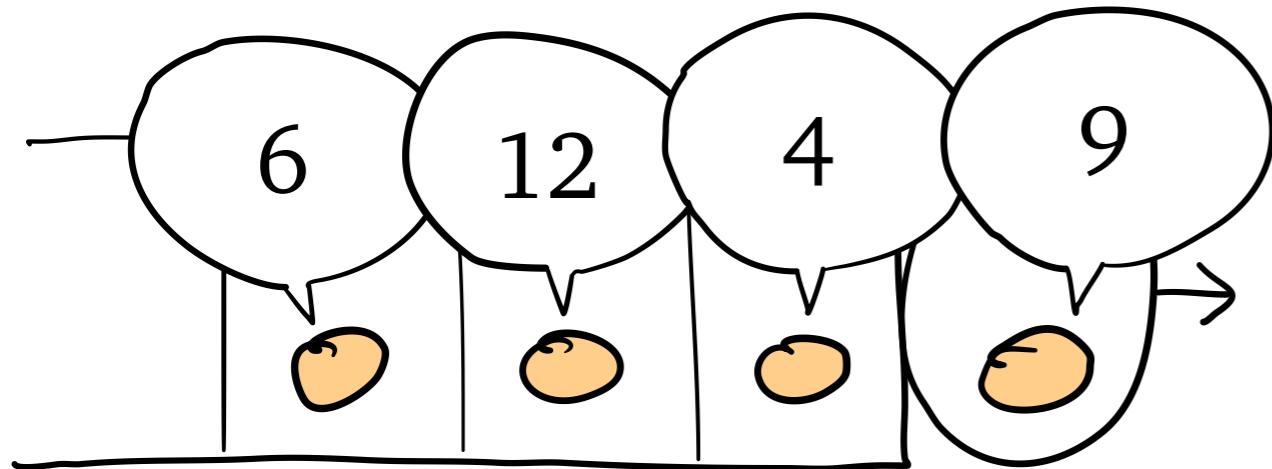
Optimal policy: *SRPT*  
(serve job of smallest *remaining size*)

# Zero Information



Unknown job sizes

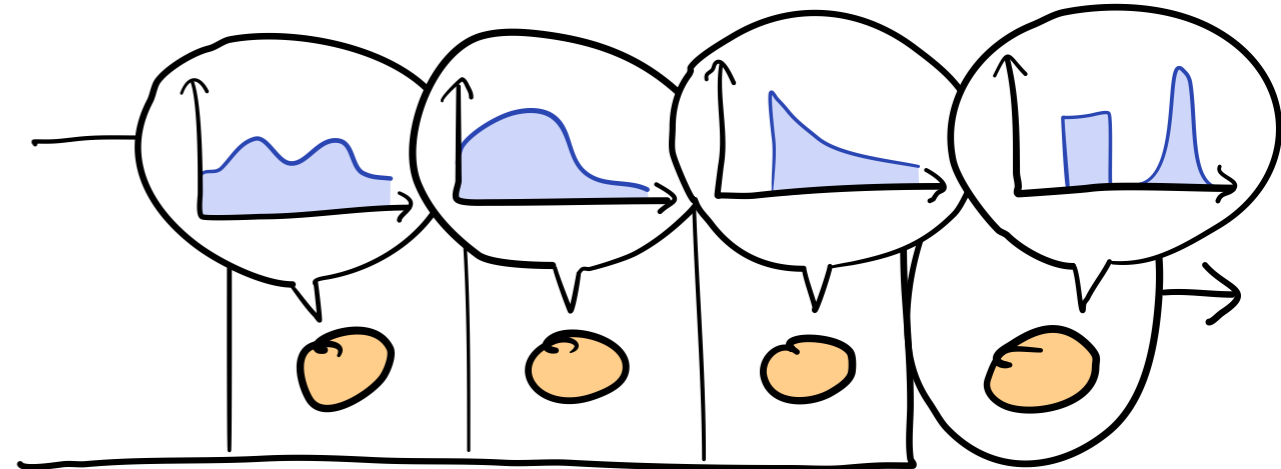
# Perfect Information



Known job sizes

Optimal policy: *SRPT*  
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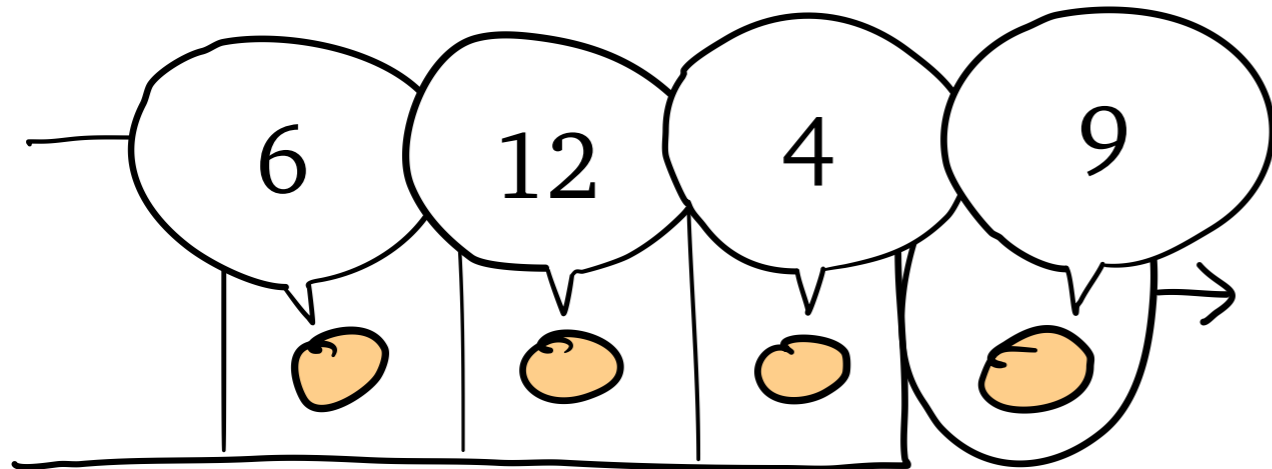
# Zero Information



Unknown job sizes

Optimal policy: *Gittins policy*  
(serve job of smallest *Gittins rank*)

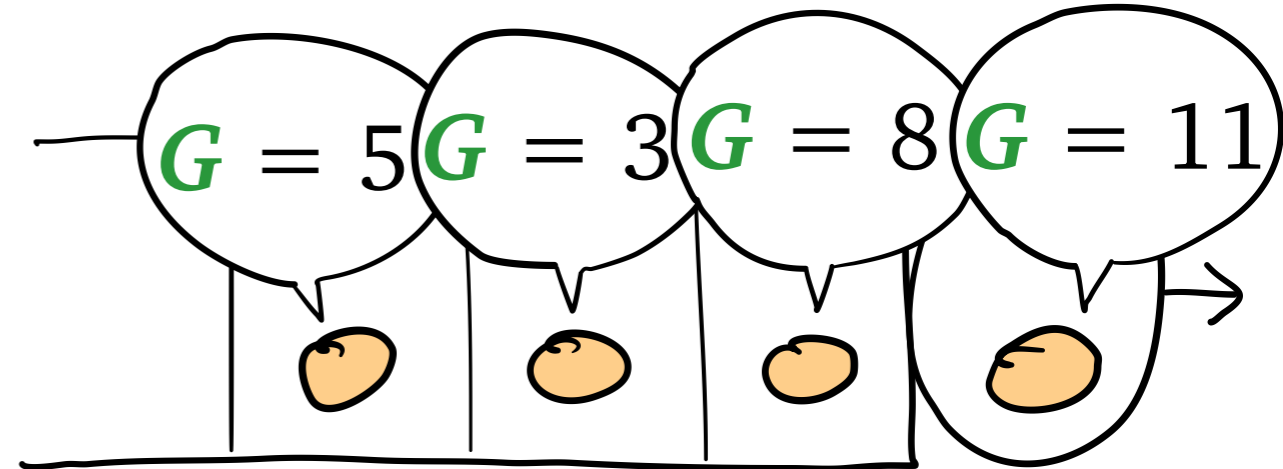
# Perfect Information



Known job sizes

Optimal policy: *SRPT*  
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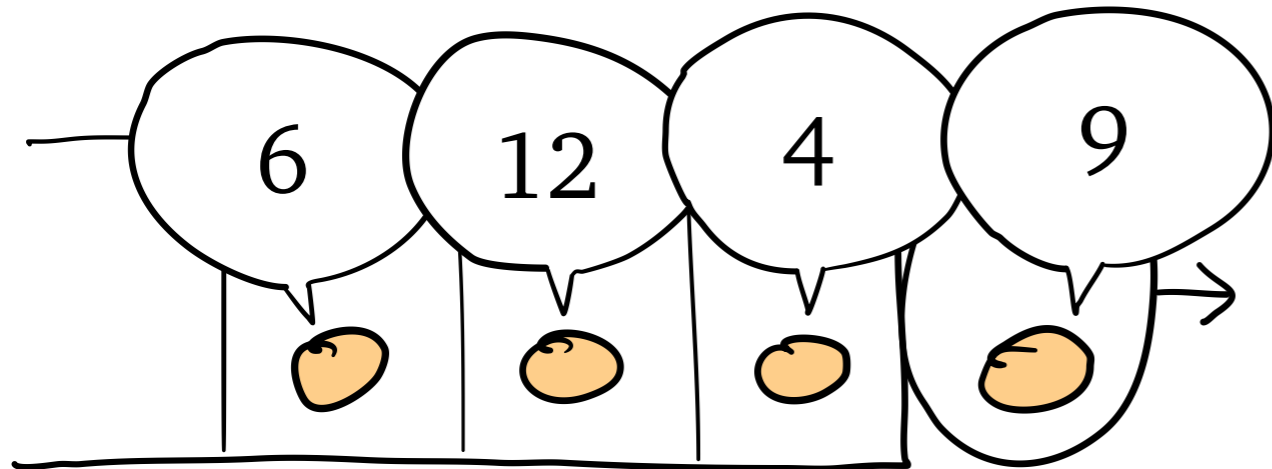
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Unknown job sizes

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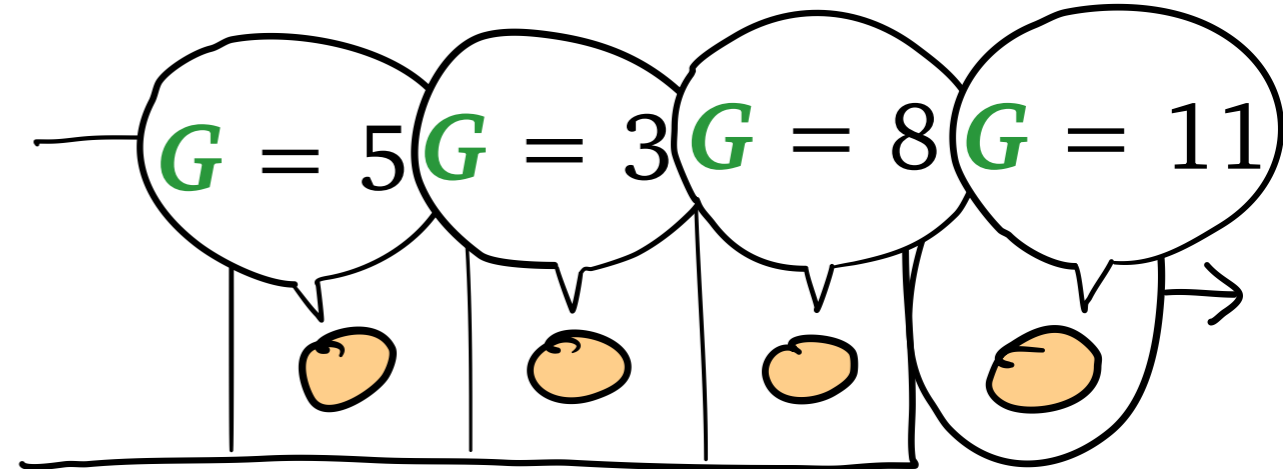
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# Zero Information



Unknown job sizes

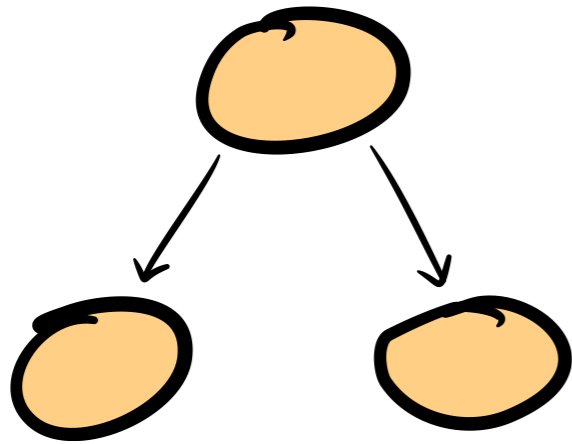
Optimal policy: *Gittins policy*  
(serve job of smallest *Gittins rank*)

**Open problem:** *partial information*

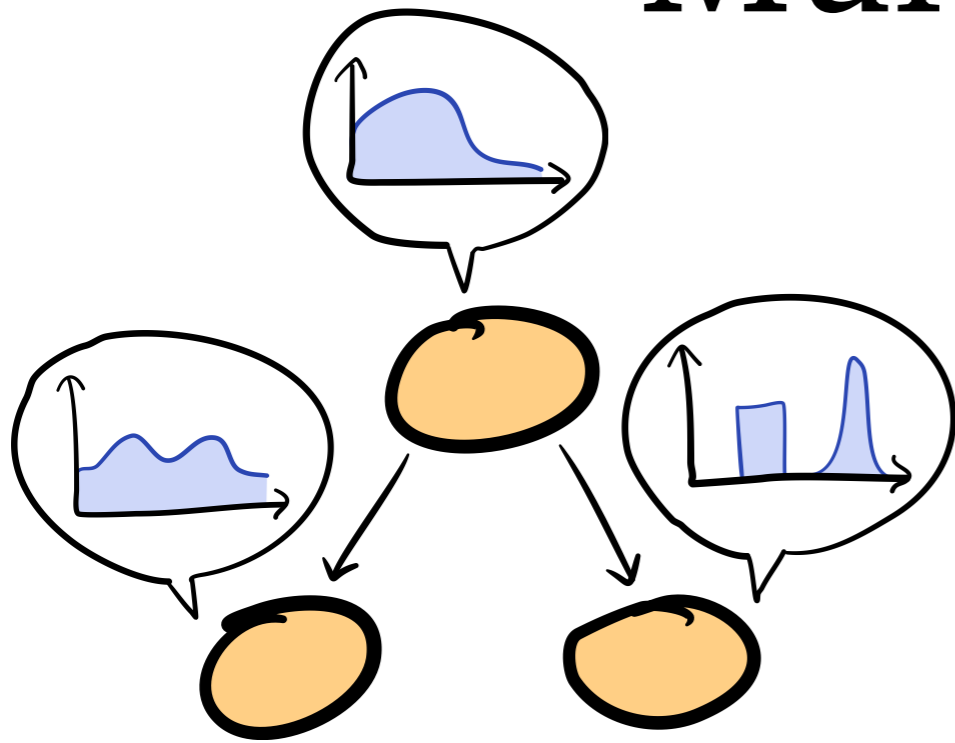
# Partial Information: Multistage Jobs

# Partial Information: Multistage Jobs

Jobs have *multiple stages*

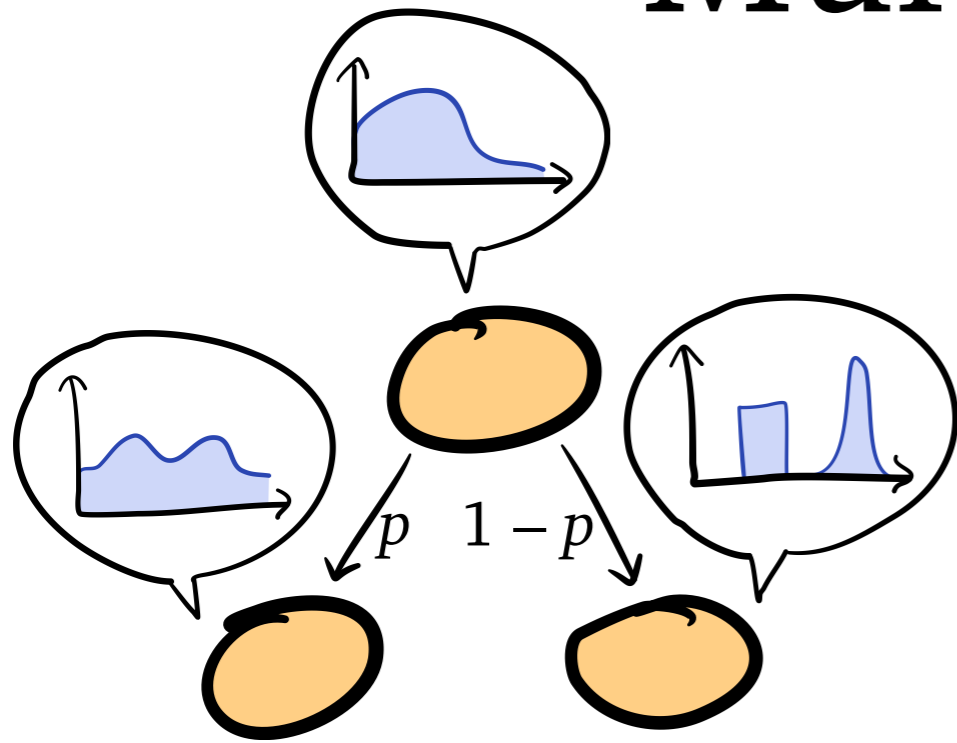


# Partial Information: Multistage Jobs



- Jobs have *multiple stages*
- unknown stage sizes

# Partial Information: Multistage Jobs

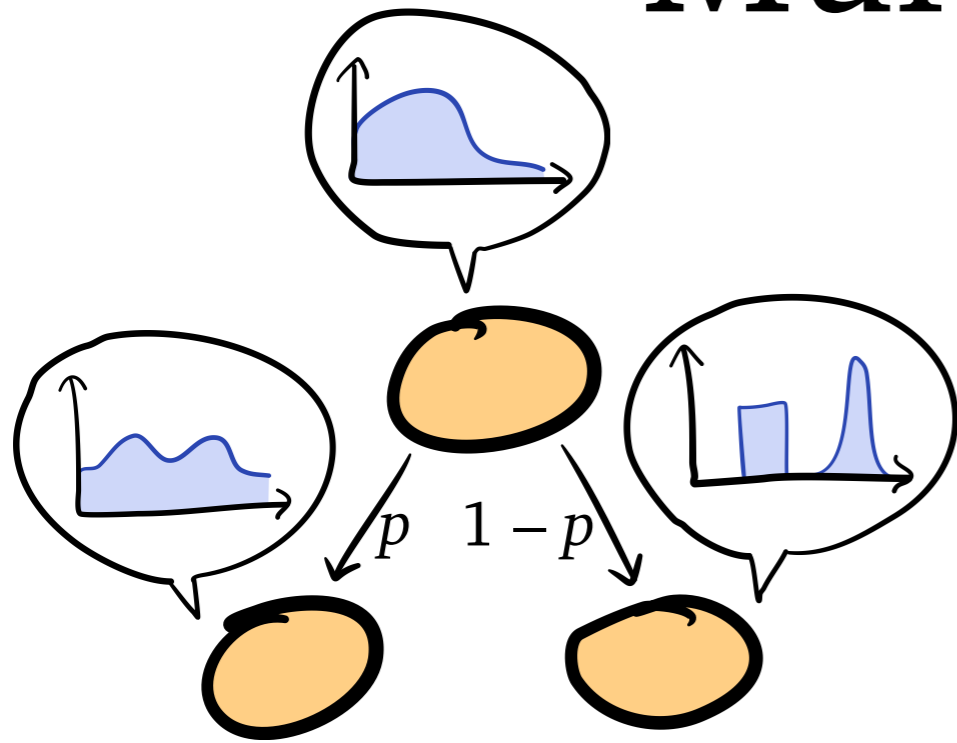


Jobs have *multiple stages*

- unknown stage sizes
- unknown stage sequence



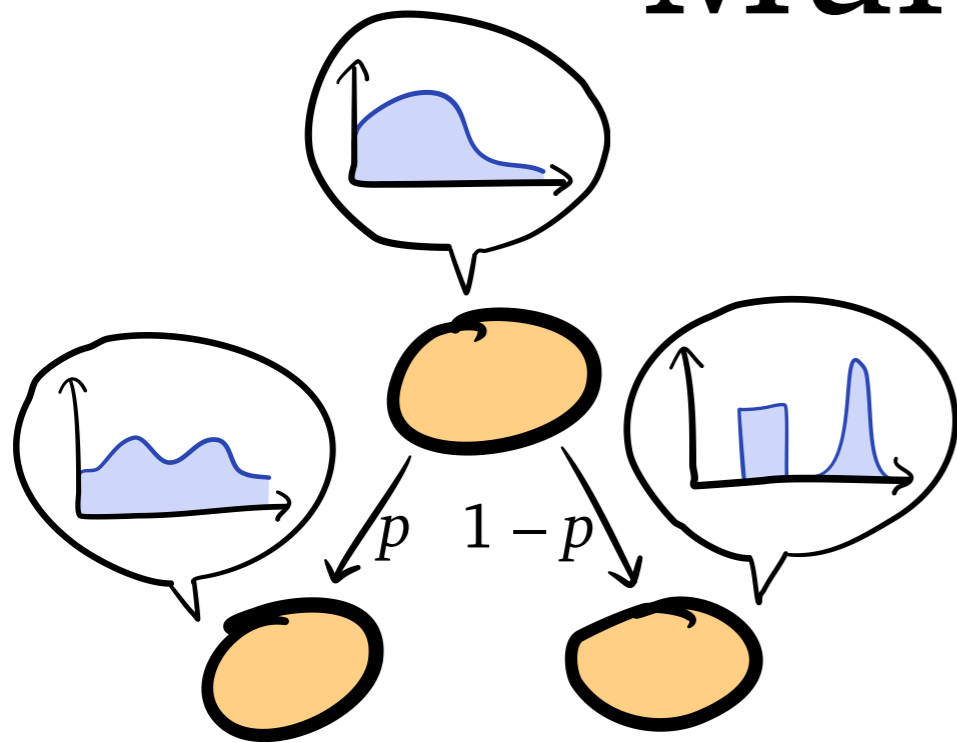
# Partial Information: Multistage Jobs



Jobs have *multiple stages*

- unknown stage sizes
- unknown stage sequence
- ... but know *which stage* we're on

# Partial Information: Multistage Jobs

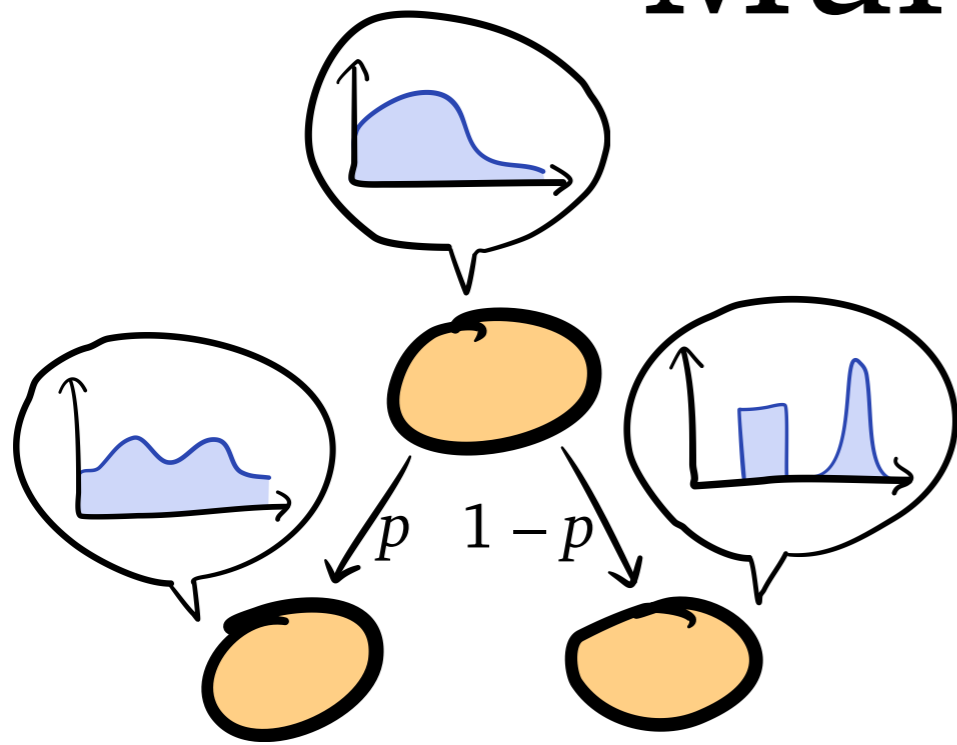


Jobs have *multiple stages*

- unknown stage sizes
- unknown stage sequence
- ... but know *which stage* we're on

For each job, scheduler knows:

# Partial Information: Multistage Jobs



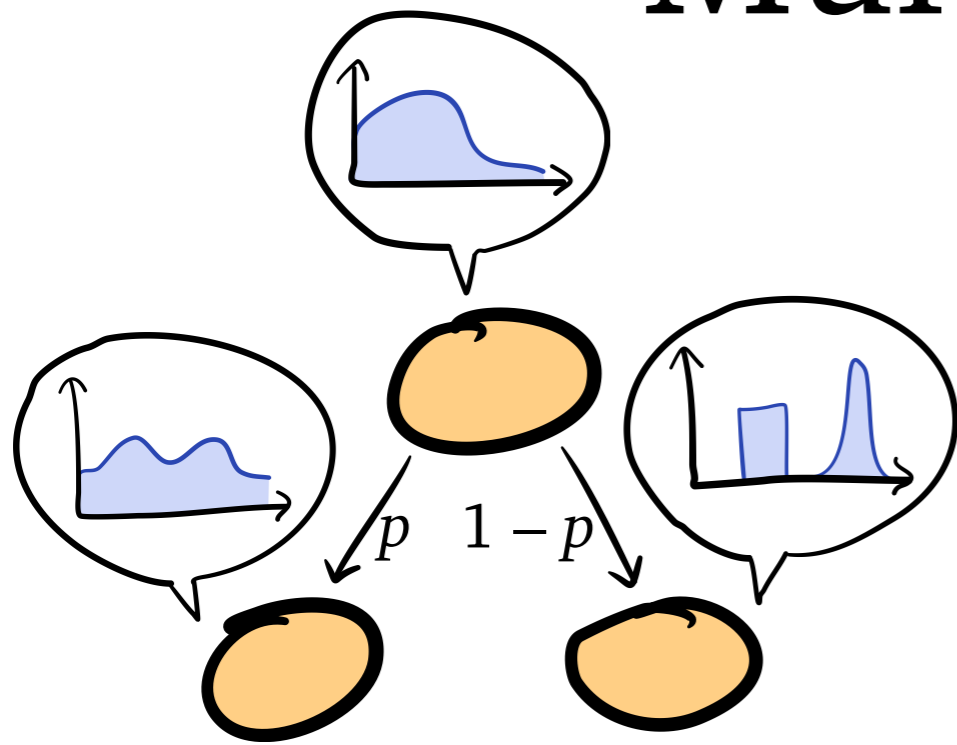
Jobs have *multiple stages*

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# Partial Information: Multistage Jobs



Jobs have *multiple stages*

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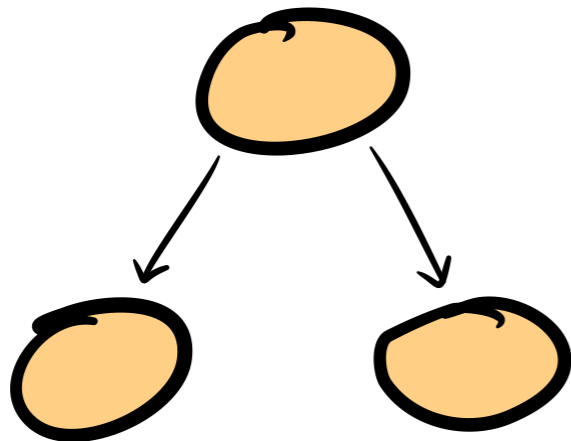
For each job, scheduler knows:

- *stage* in progress
- *age* of that stage

# Multistage Job Examples

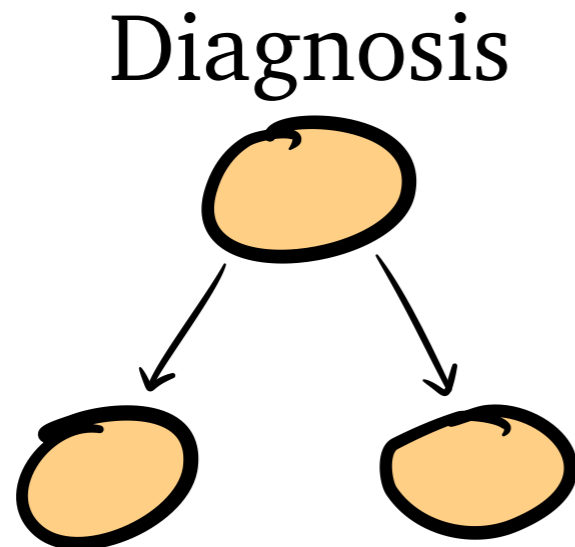
# Multistage Job Examples

Job R: Repairing an item



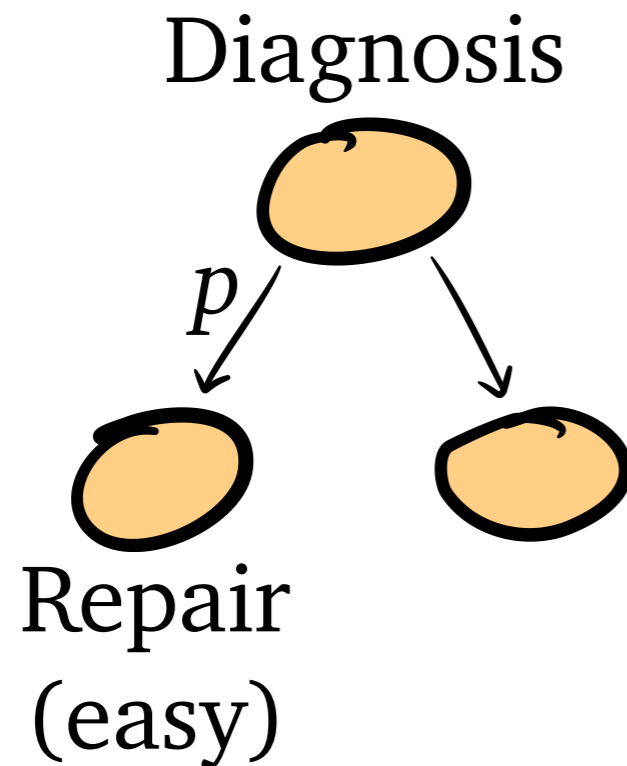
# Multistage Job Examples

Job R: Repairing an item



# Multistage Job Examples

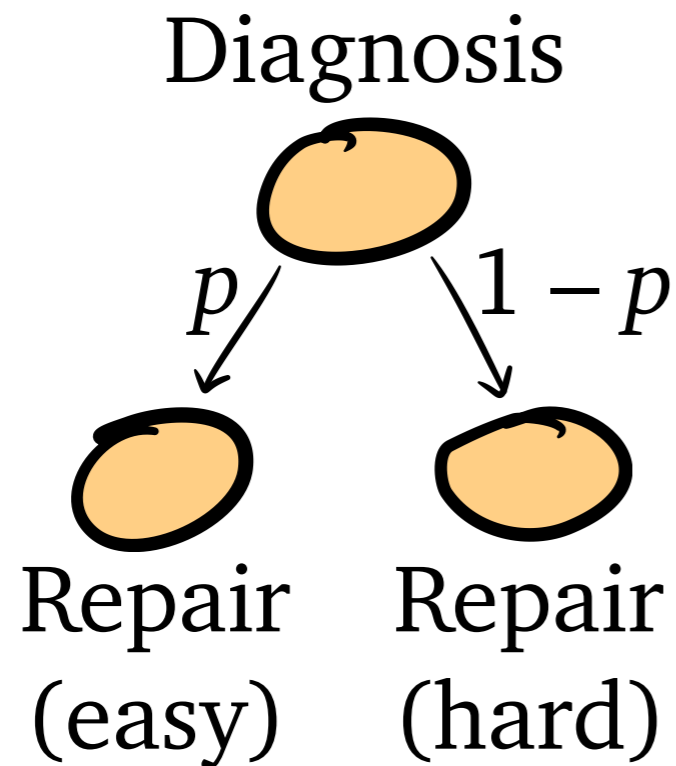
Job R: Repairing an item





# Multistage Job Examples

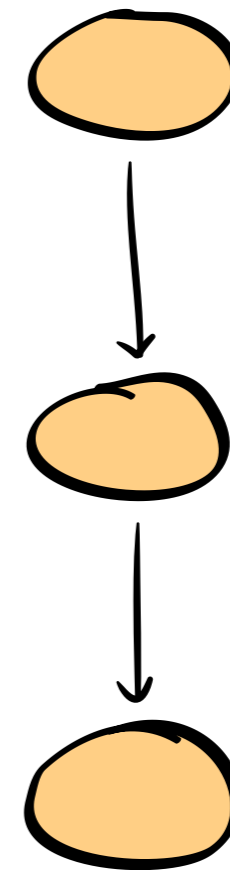
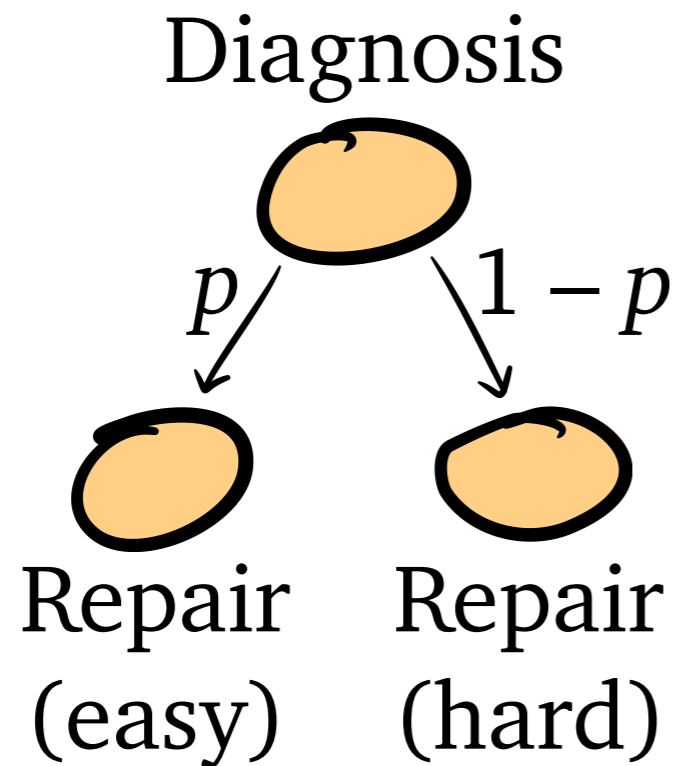
Job R: Repairing an item



# Multistage Job Examples

Job R: Repairing an item

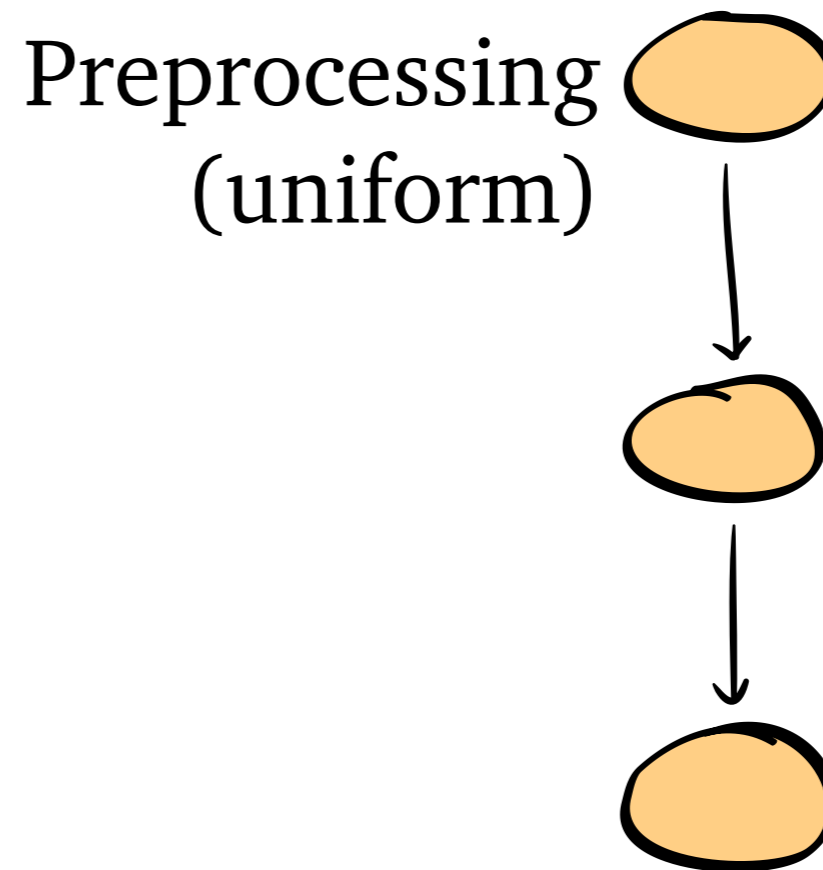
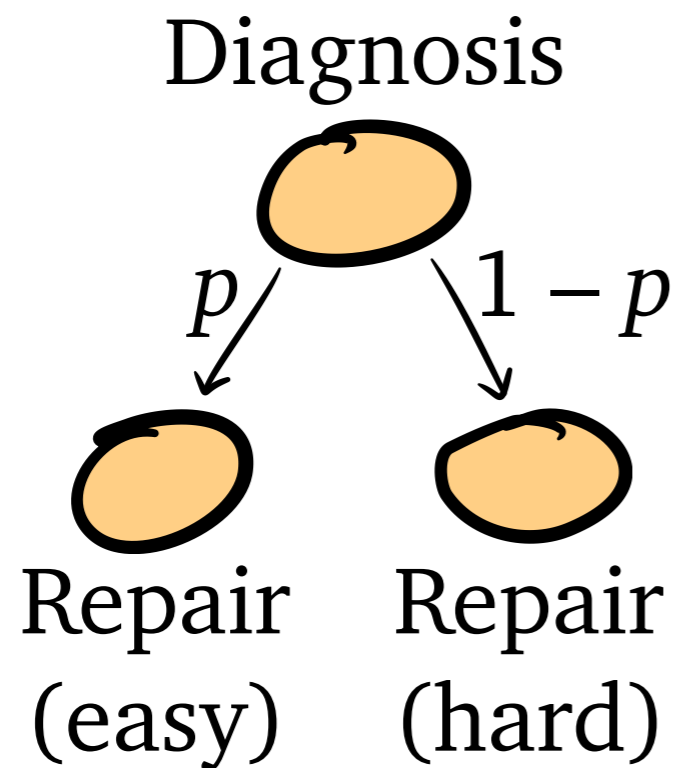
Job G: Google ad placement



# Multistage Job Examples

Job R: Repairing an item

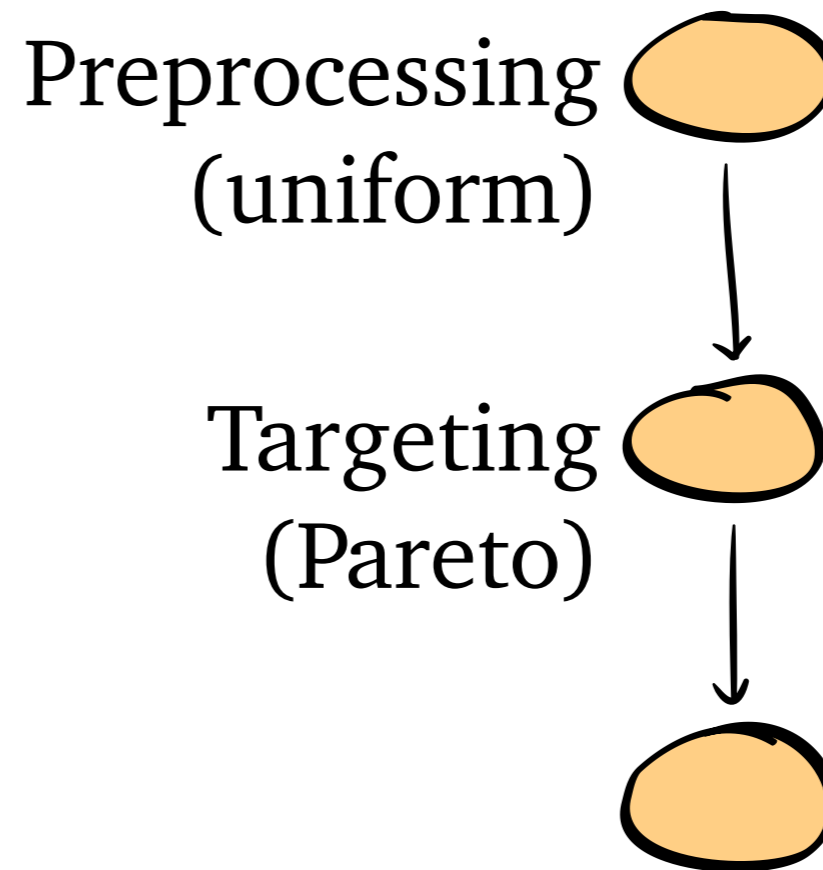
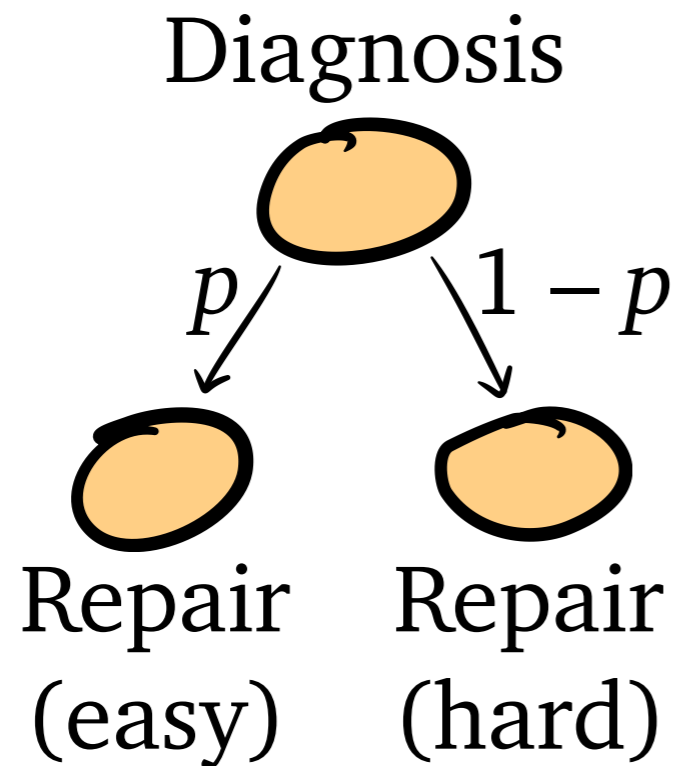
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# Multistage Job Examples

Job R: Repairing an item

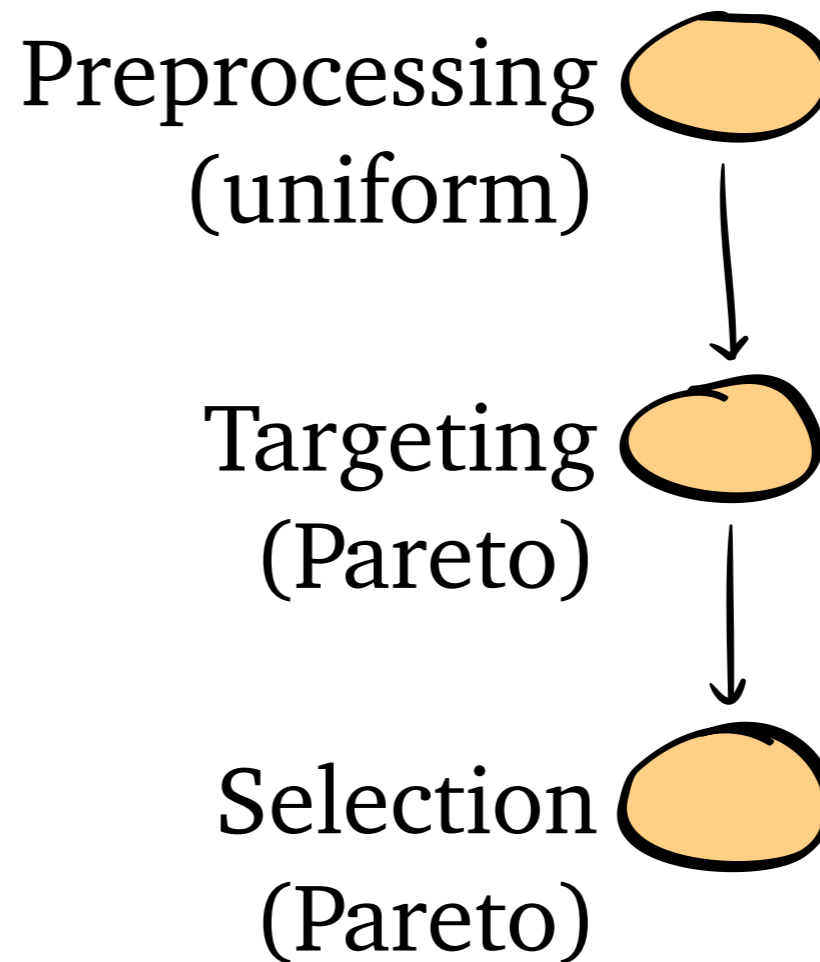
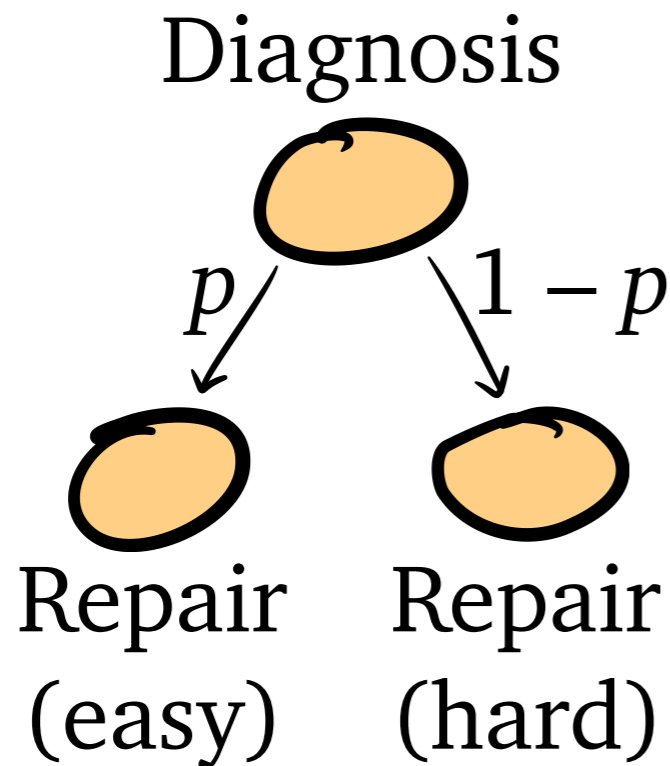
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# Multistage Job Examples

Job R: Repairing an item

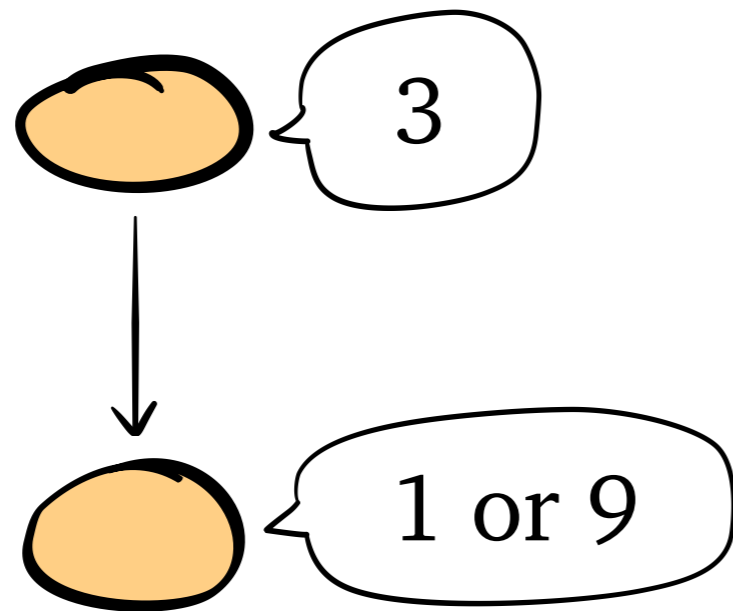
Job G: Google ad placement



# Scheduling Multistage Jobs

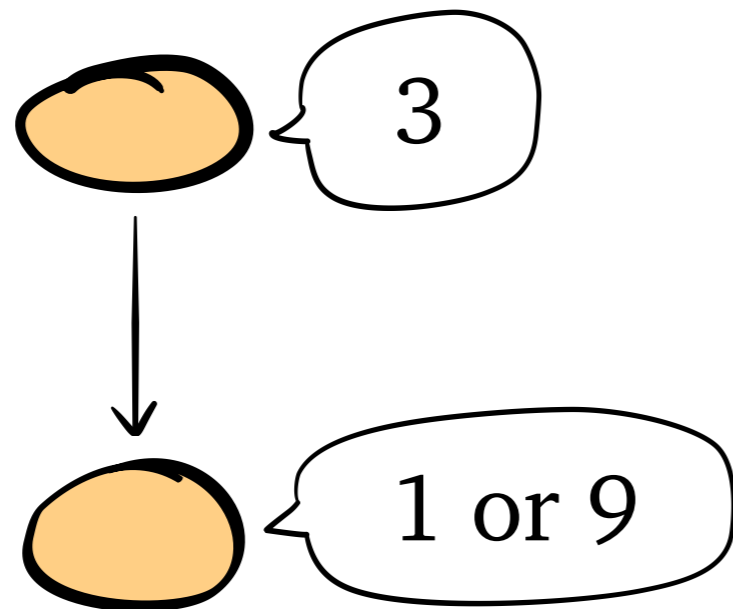
# Scheduling Multistage Jobs

Job J

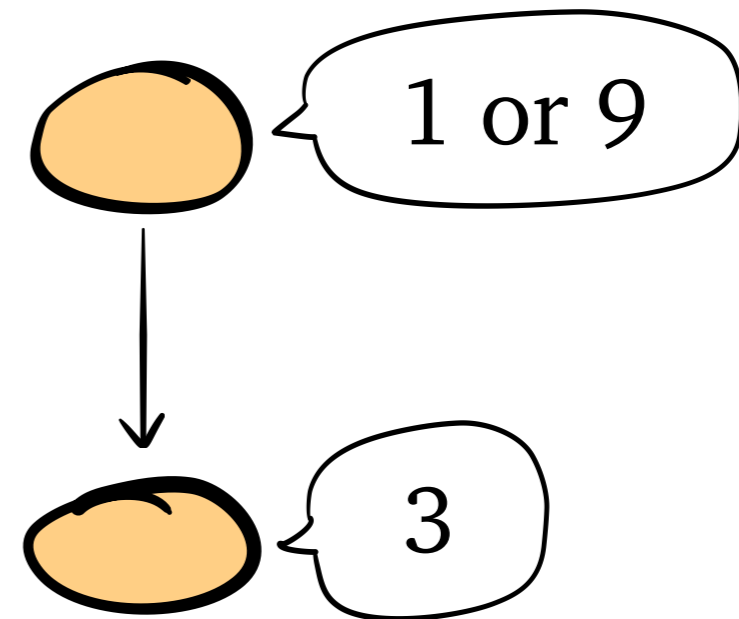


# Scheduling Multistage Jobs

Job J

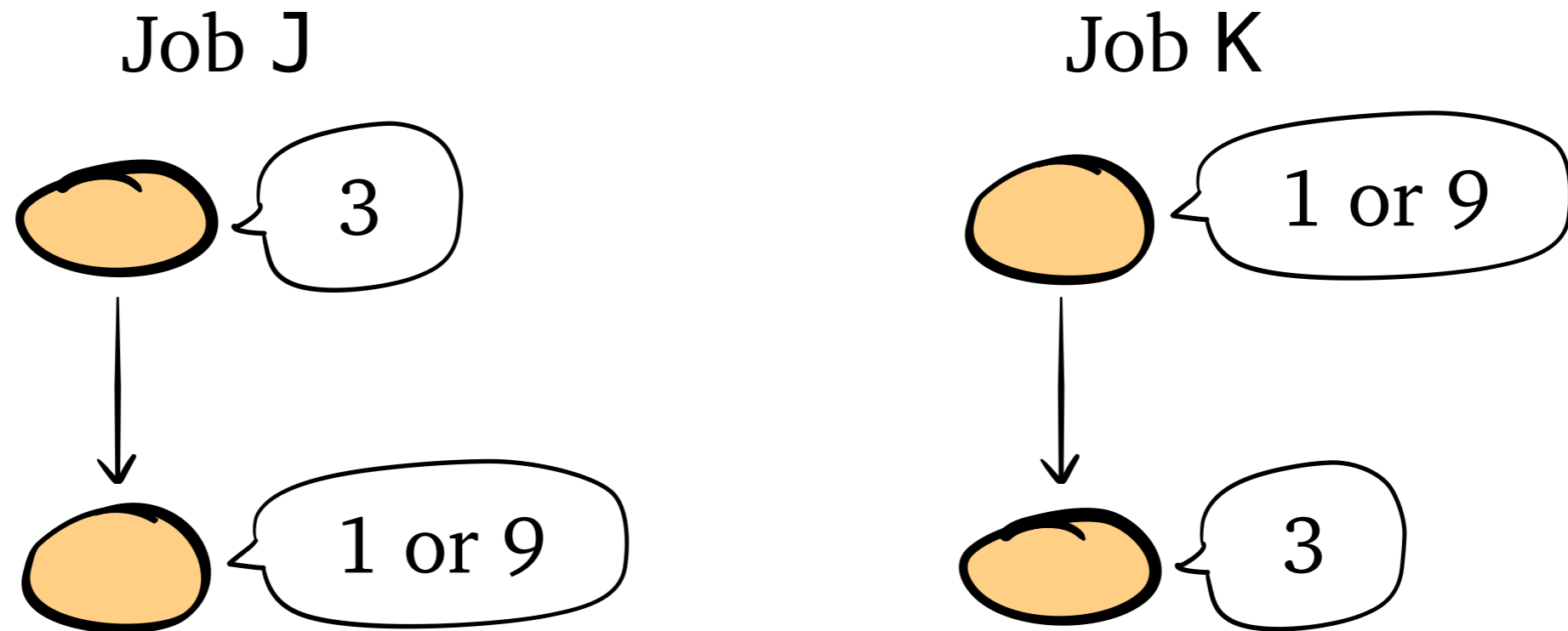


Job K



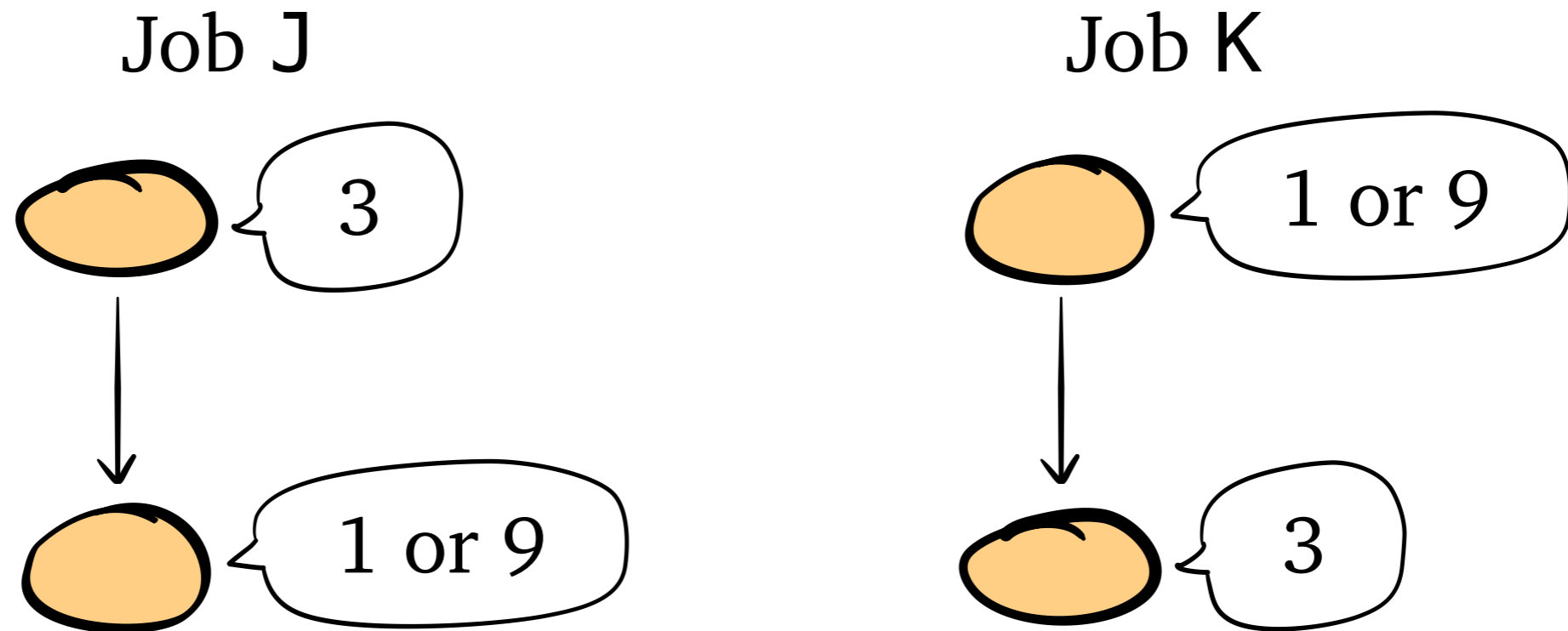


# Scheduling Multistage Jobs



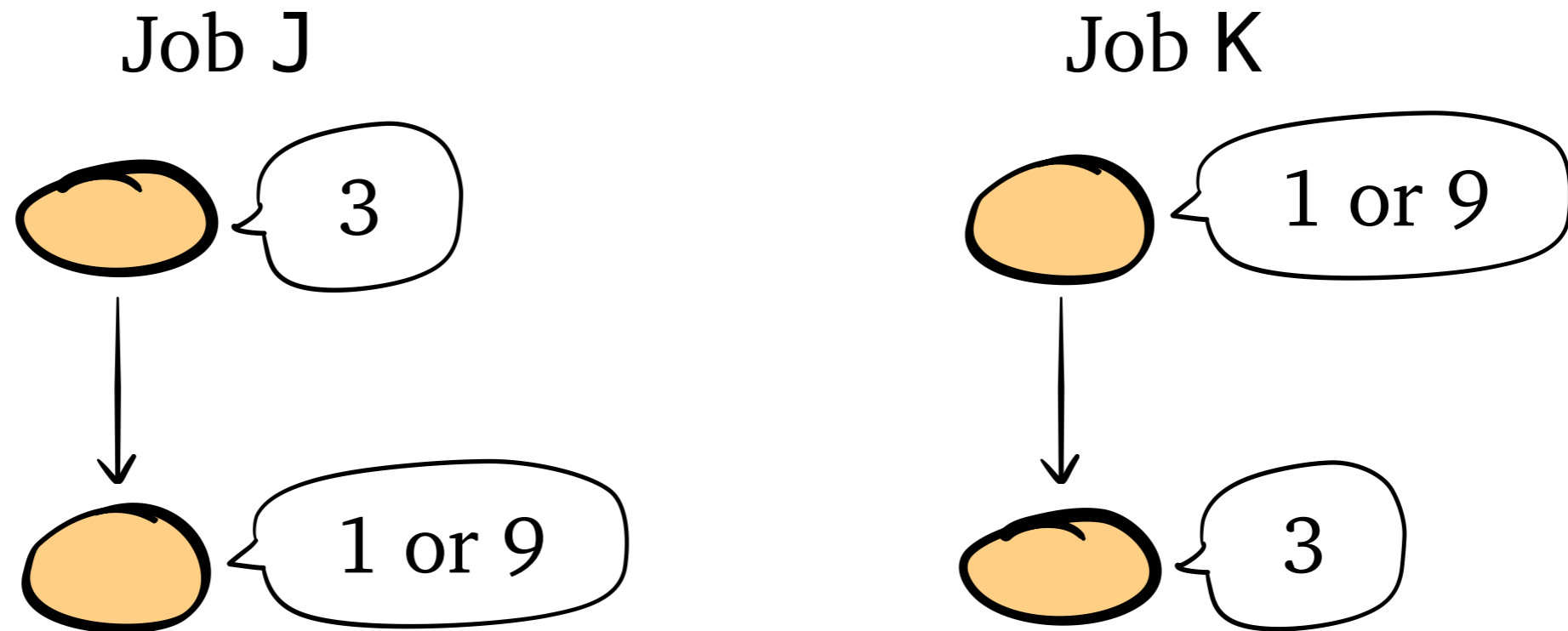
Which should we serve first?

# Scheduling Multistage Jobs



Which should we serve first? Job K first

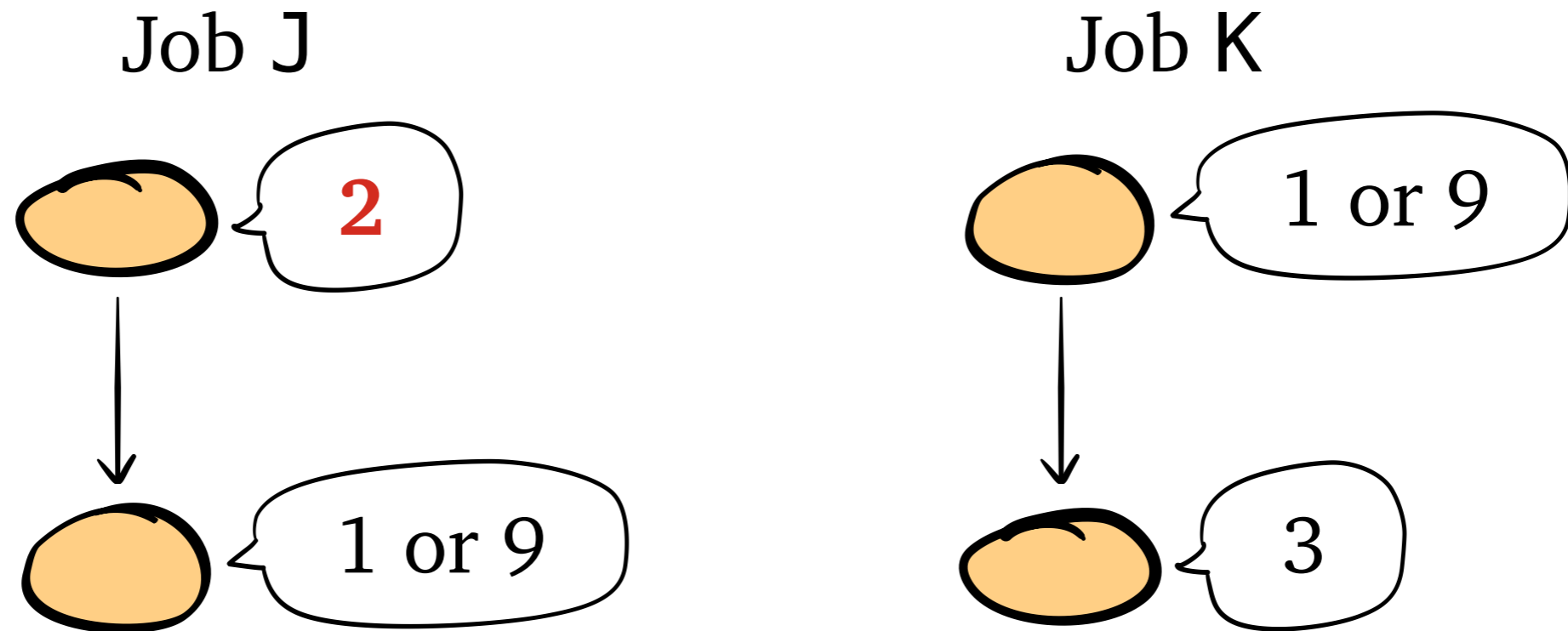
# Scheduling Multistage Jobs



Which should we serve first? Job K first

What if we shorten J's first stage?

# Scheduling Multistage Jobs

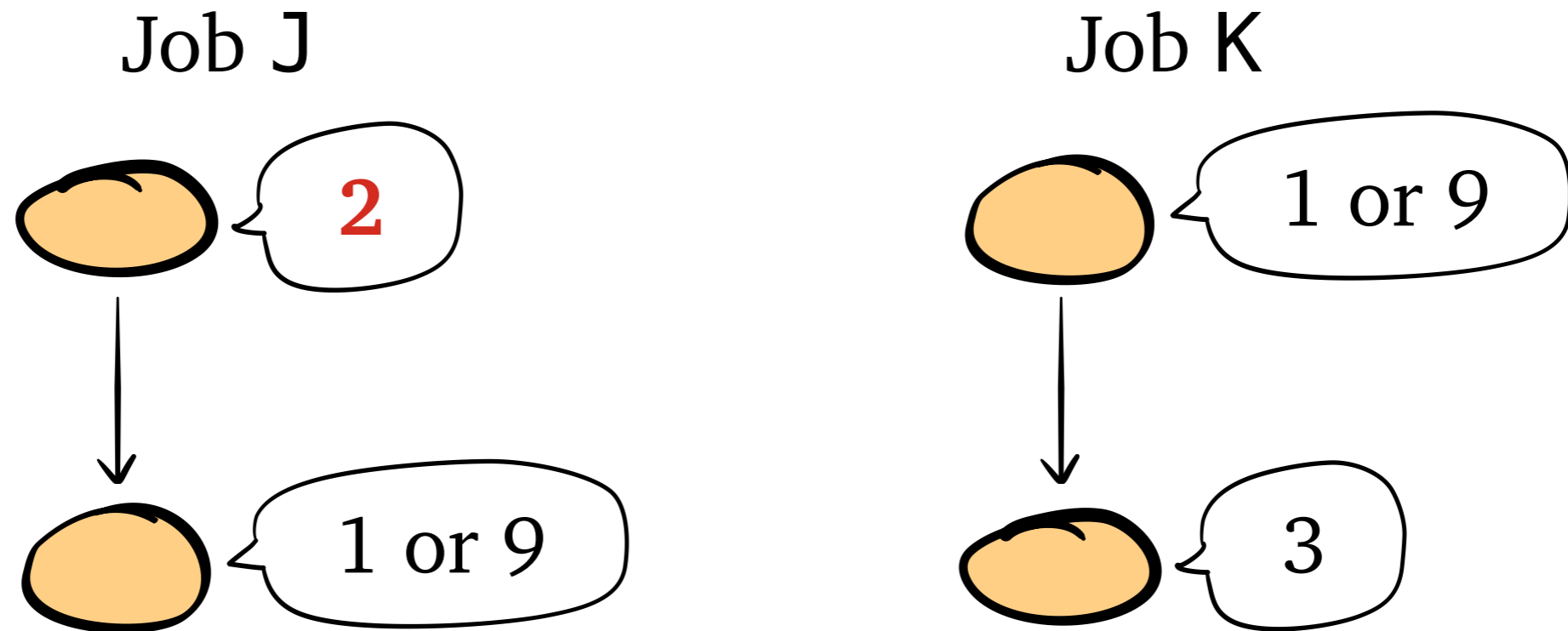


Which should we serve first? Job K first

What if we shorten J's first stage?

- Shorten to 2:

# Scheduling Multistage Jobs

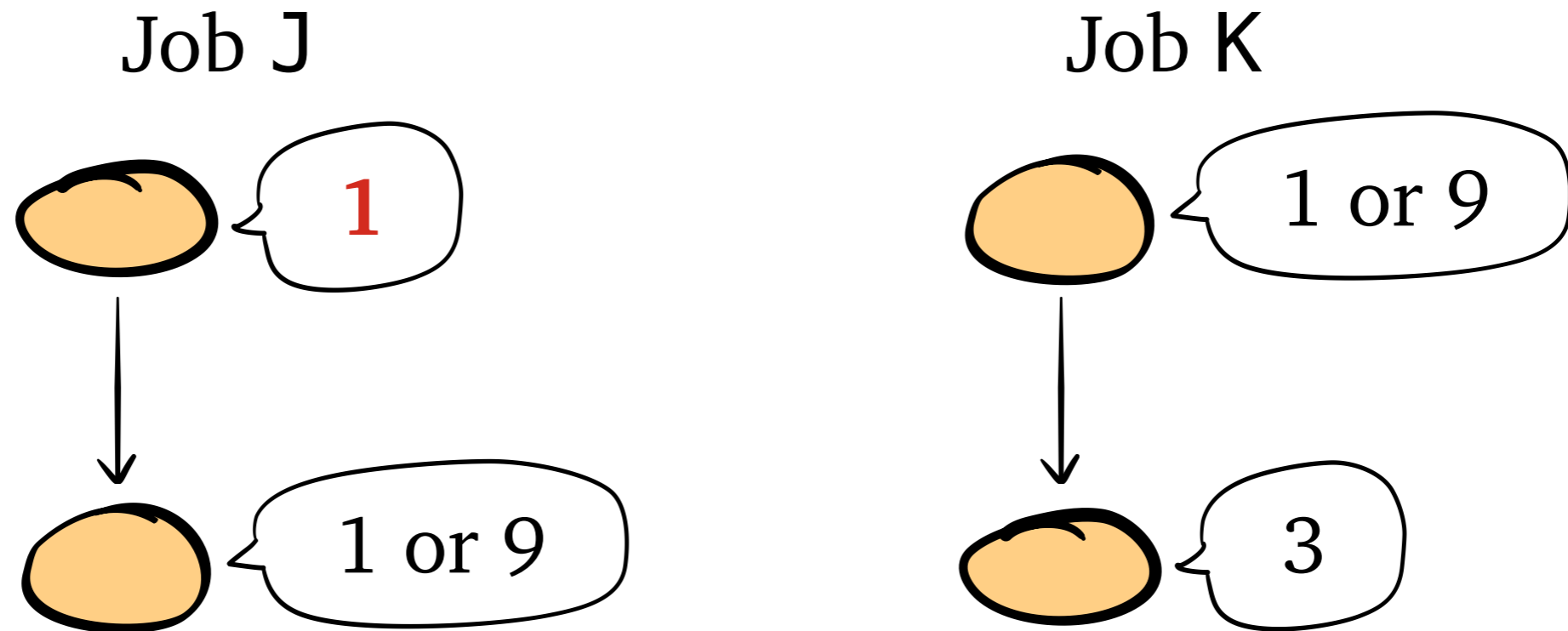


Which should we serve first? Job K first

What if we shorten J's first stage?

- Shorten to 2: still K first

# Scheduling Multistage Jobs

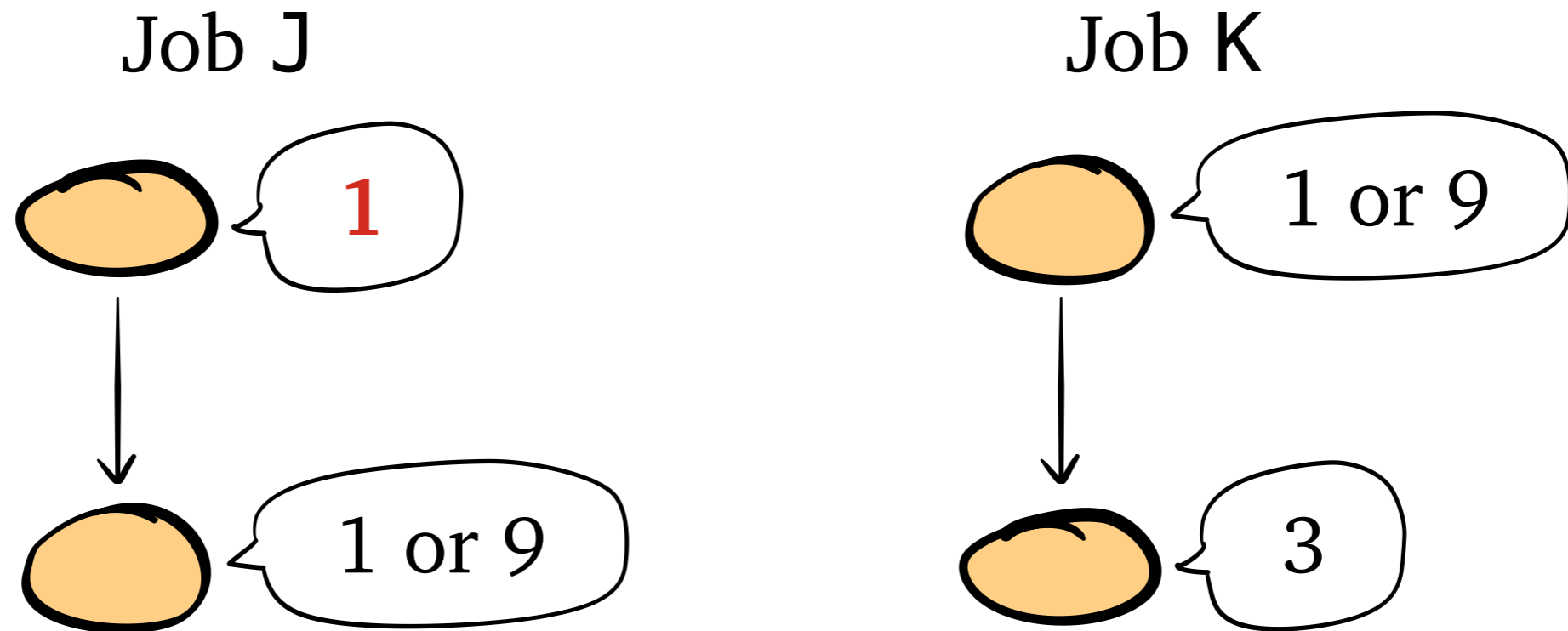


Which should we serve first? Job K first

What if we shorten J's first stage?

- Shorten to 2: still K first
- Shorten to 1:

# Scheduling Multistage Jobs

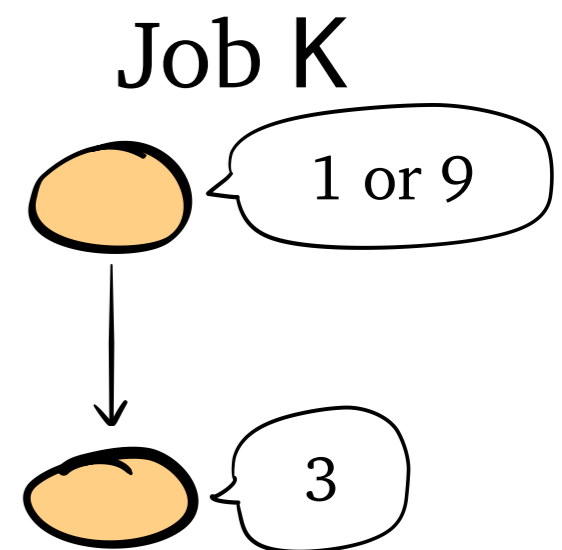
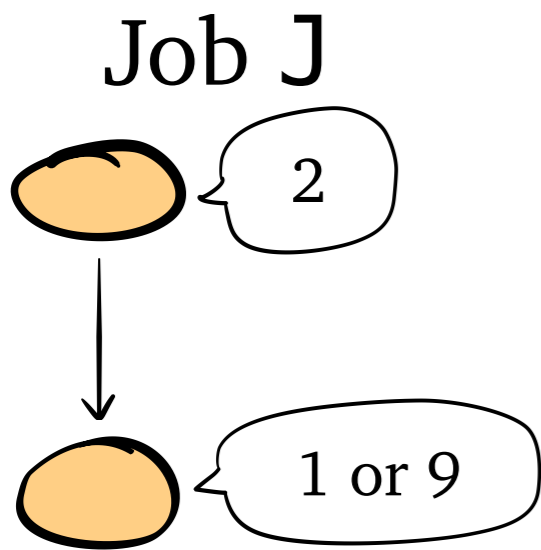


Which should we serve first? Job K first

What if we shorten J's first stage?

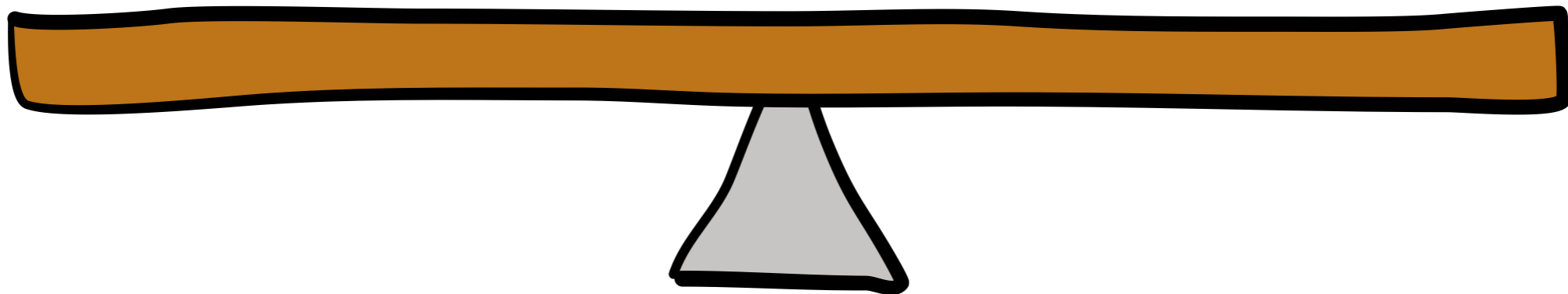
- Shorten to 2: still K first
- Shorten to 1: now J first

# Tradeoff



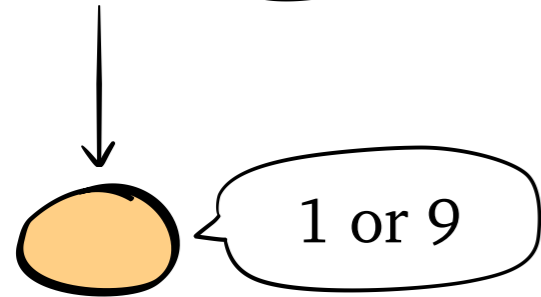
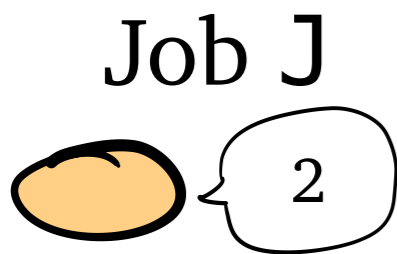
Prioritizing  
“short” jobs

Prioritizing  
“informative” jobs

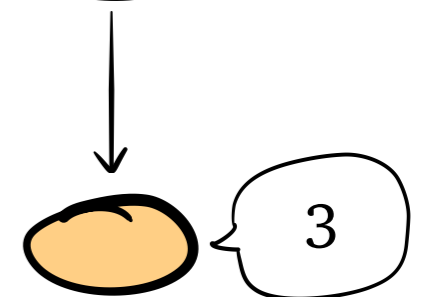
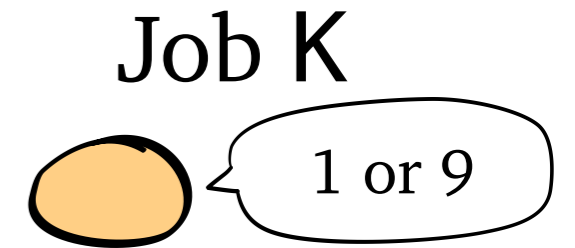




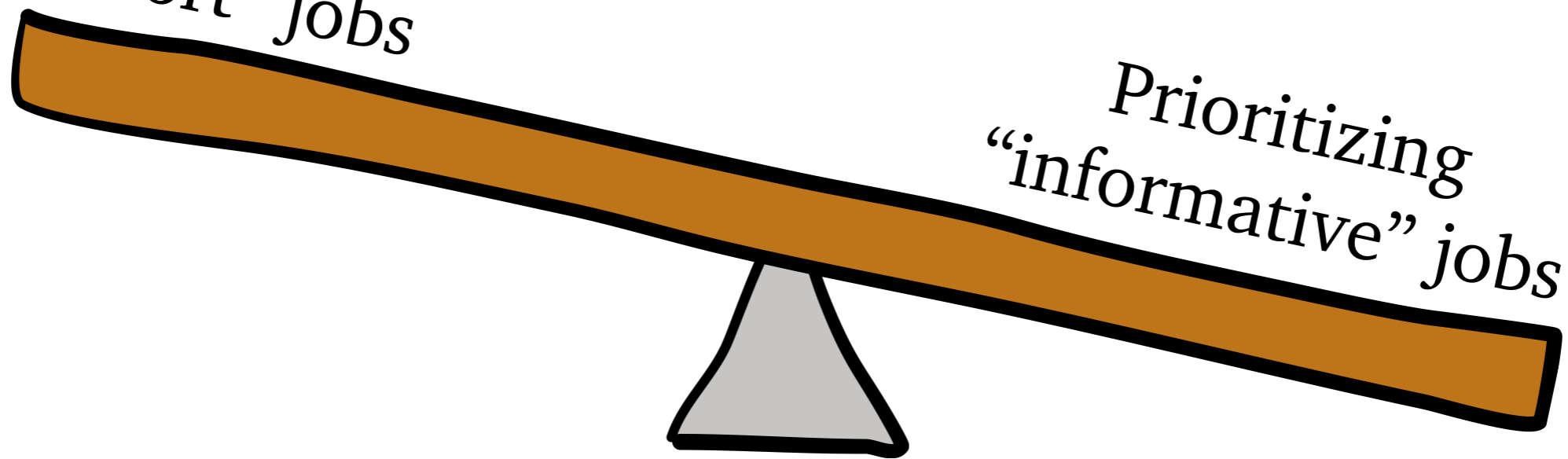
# Tradeoff



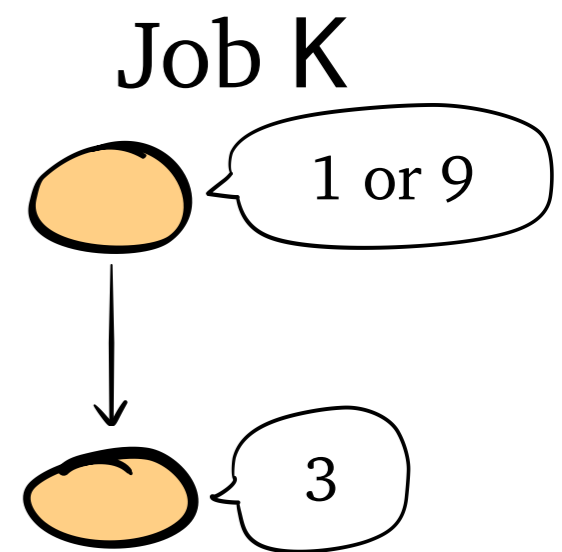
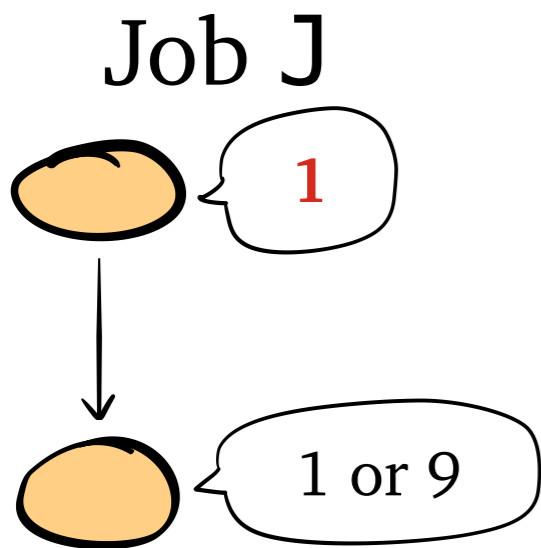
*Prioritizing  
“short” jobs*



*Prioritizing  
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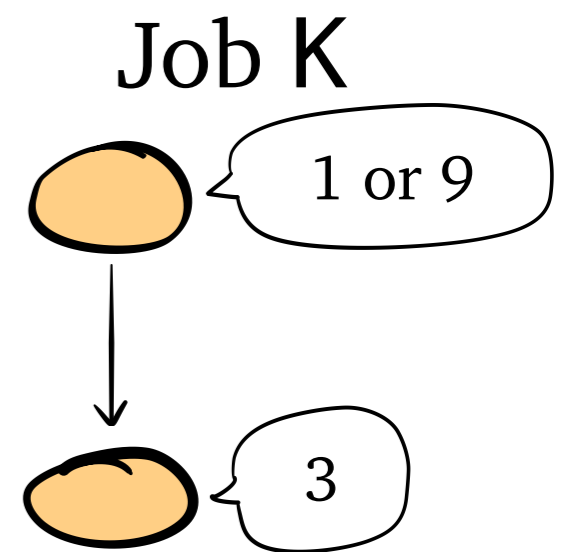
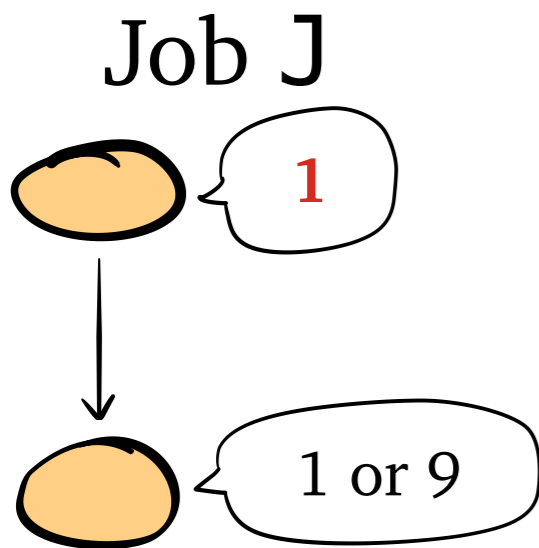
# Tradeoff



Prioritizing  
“short” jobs

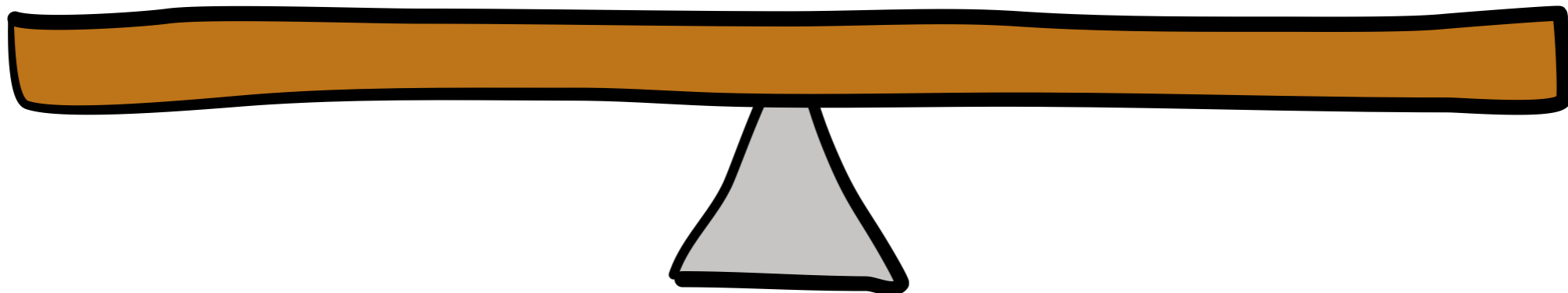
Prioritizing  
“informative” jobs

# Tradeoff



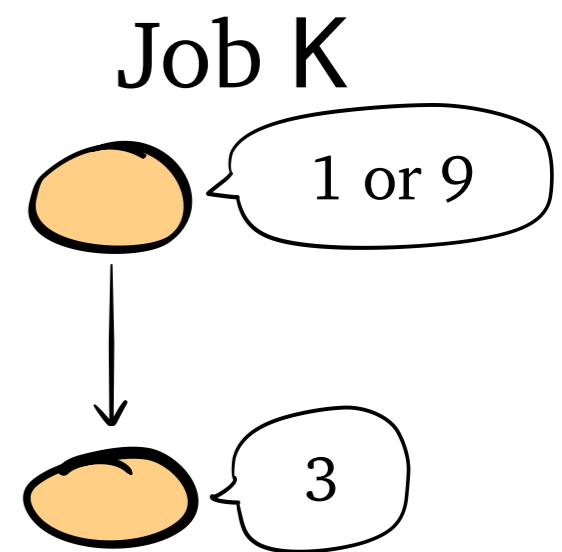
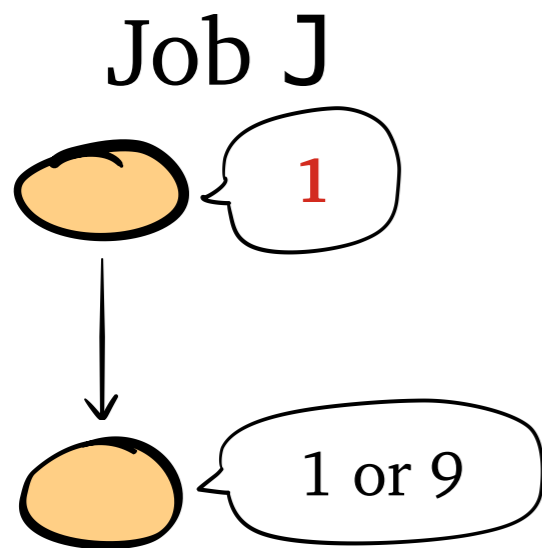
Prioritizing  
“short” jobs

Prioritizing  
“informative” jobs



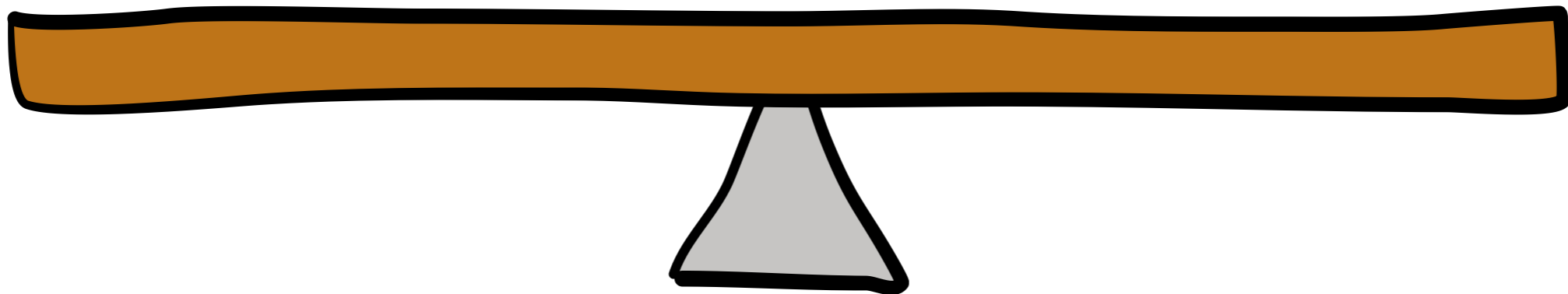
How do we balance the tradeoff?

# Tradeoff



Prioritizing  
“short” jobs

Prioritizing  
“informative” jobs



How do we balance the tradeoff?

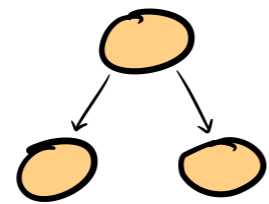
*Multistage Gittins policy*



For multistage jobs:



Gittins rank is *defined*...

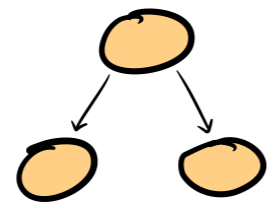


For multistage jobs:

Gittins rank is *defined*...

Gittins policy is *optimal*  
for minimizing  $E[T]$ ...

# Good News



For multistage jobs:

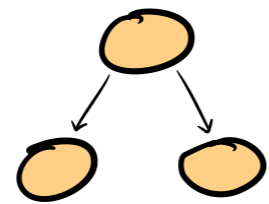
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# Good News

# Bad News



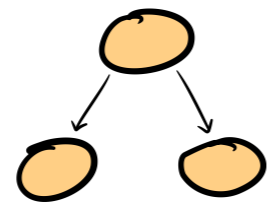
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# Good News

# Bad News



For multistage jobs:

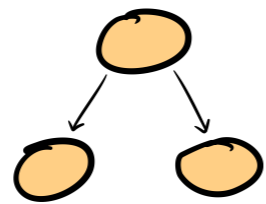
Gittins rank is *defined*...

... but is intractable to *compute*

Gittins policy is *optimal* for minimizing  $E[T]$ ...

# Good News

# Bad News



For multistage jobs:

Gittins rank is *defined*...

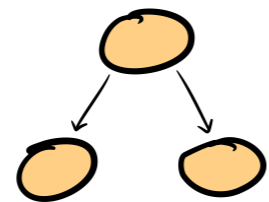
... but is intractable to *compute*

Gittins policy is *optimal* for minimizing  $E[T]$ ...

... but unknown how to *analyze*  $E[T]$

# Good News

# Bad News



For multistage jobs:

Gittins rank is *defined*...

... but is intractable to *compute*

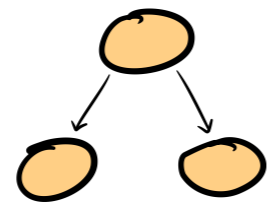
Gittins policy is *optimal* for minimizing  $E[T]$ ...

... but unknown how to *analyze*  $E[T]$

Need *new version* of Gittins policy

# Good News

# Bad News



For multistage jobs:

Gittins rank is *defined*...

... but is intractable to *compute*

Gittins policy is *optimal* for minimizing  $E[T]$ ...

... but unknown how to *analyze*  $E[T]$

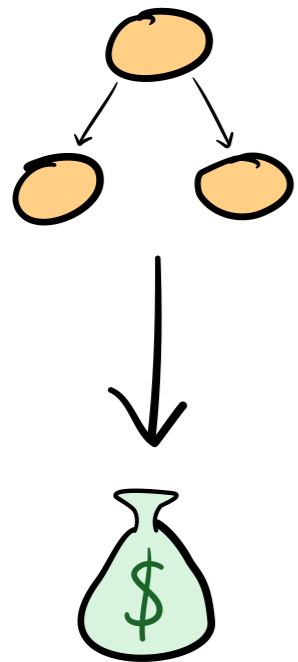
Need *new version* of Gittins policy  
with **no bad news**

# **Our contribution:**

*a new approach* to the Gittins policy  
that *naturally scales* to multistage jobs

# Our contribution:

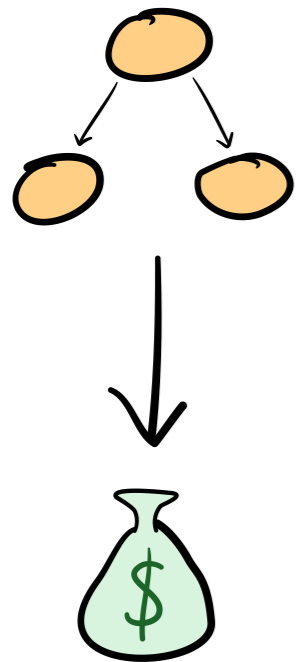
*a new approach* to the Gittins policy  
that *naturally scales* to multistage jobs



**New approach: single-job profit (SJP)**

# Our contribution:

*a new approach* to the Gittins policy  
that *naturally scales* to multistage jobs



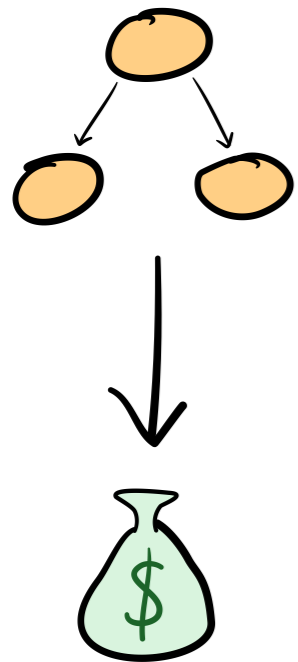
**New approach:** single-job profit (SJP)

- Helps *compute* Gittins rank of multistage jobs



# Our contribution:

*a new approach* to the Gittins policy  
that *naturally scales* to multistage jobs

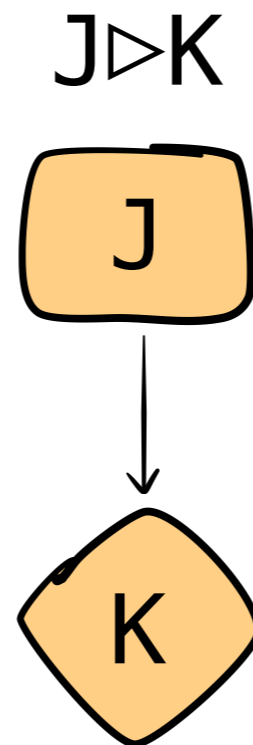


**New approach:** single-job profit (SJP)

- Helps *compute* Gittins rank of multistage jobs
- Yields *exact formula* for  $\mathbf{E}[T]$

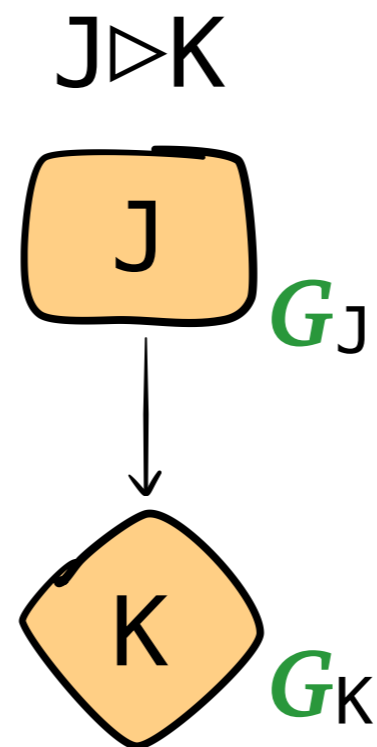
# Wanted: Composition Law

Sequential Composition



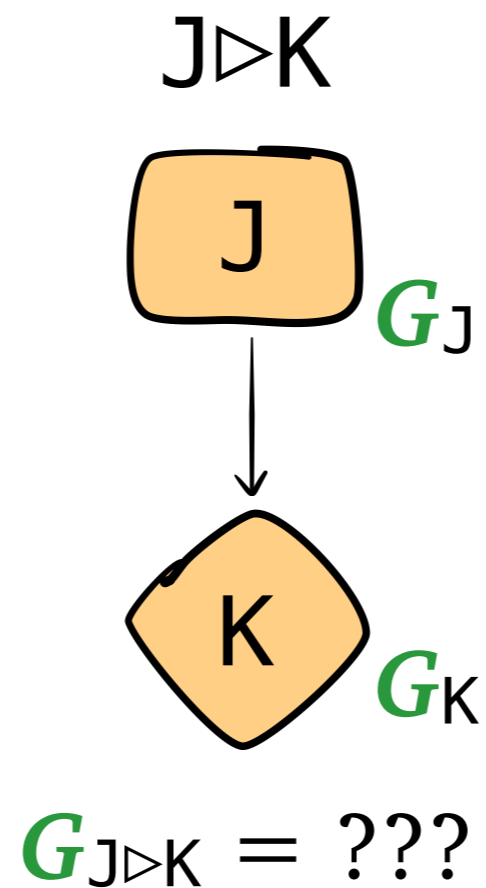
# Wanted: Composition Law

Sequential Composition

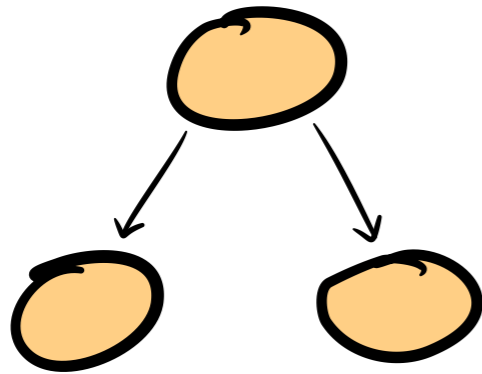


# Wanted: Composition Law

Sequential Composition



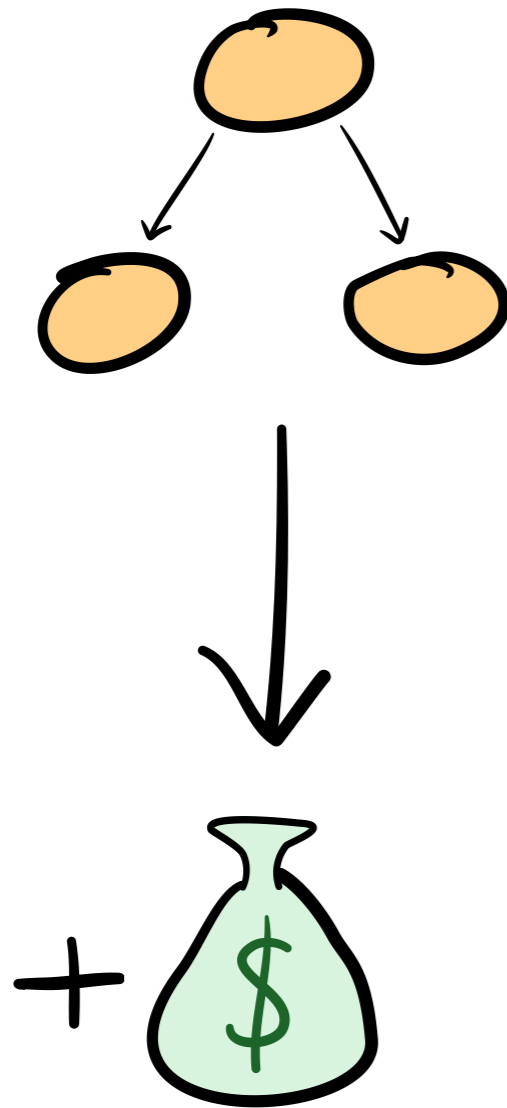
# Single-Job Profit



Game with a job and potential **reward**



# Single-Job Profit

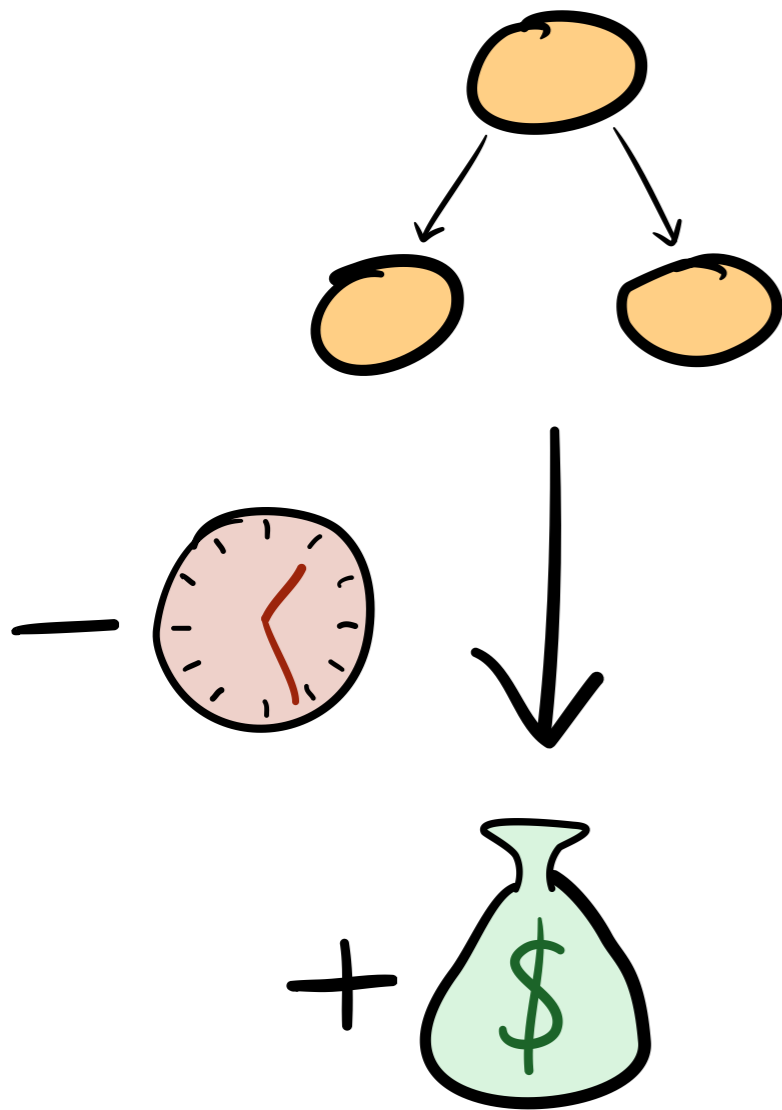


- Game with a job and potential **reward**
- Get **reward** if we complete the job

# Single-Job Profit

Game with a job and potential **reward**

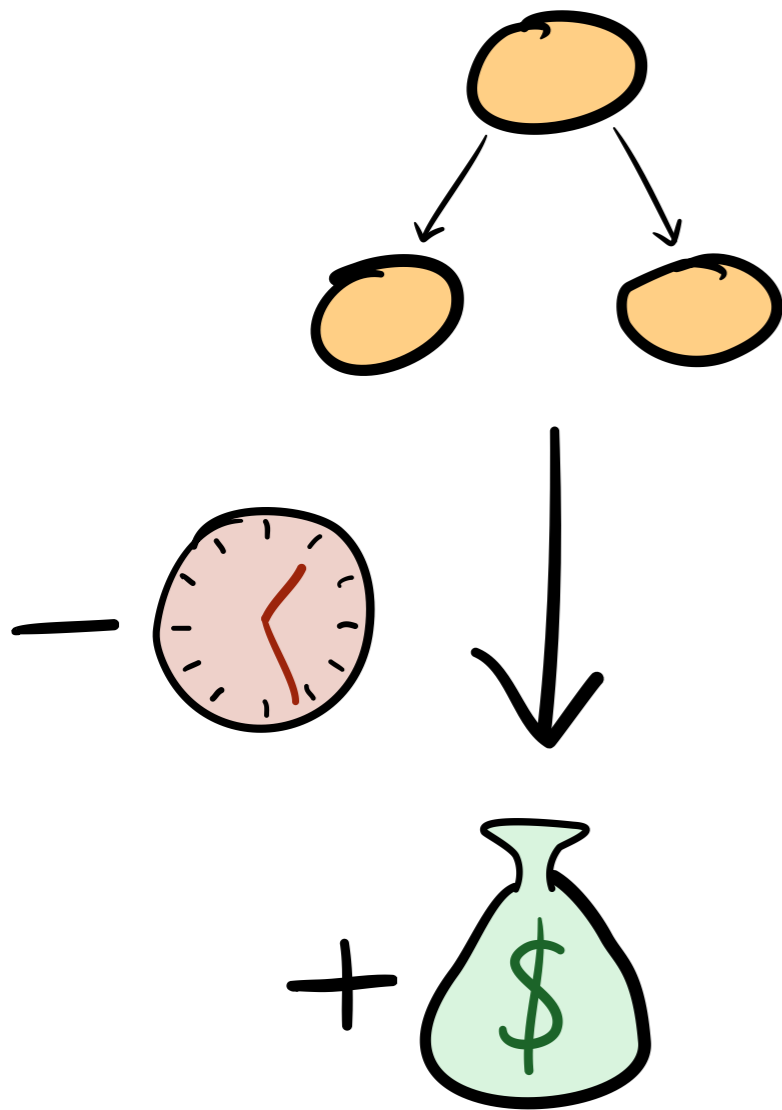
- Get **reward** if we complete the job
- Pay for **time** spent serving the job



# Single-Job Profit

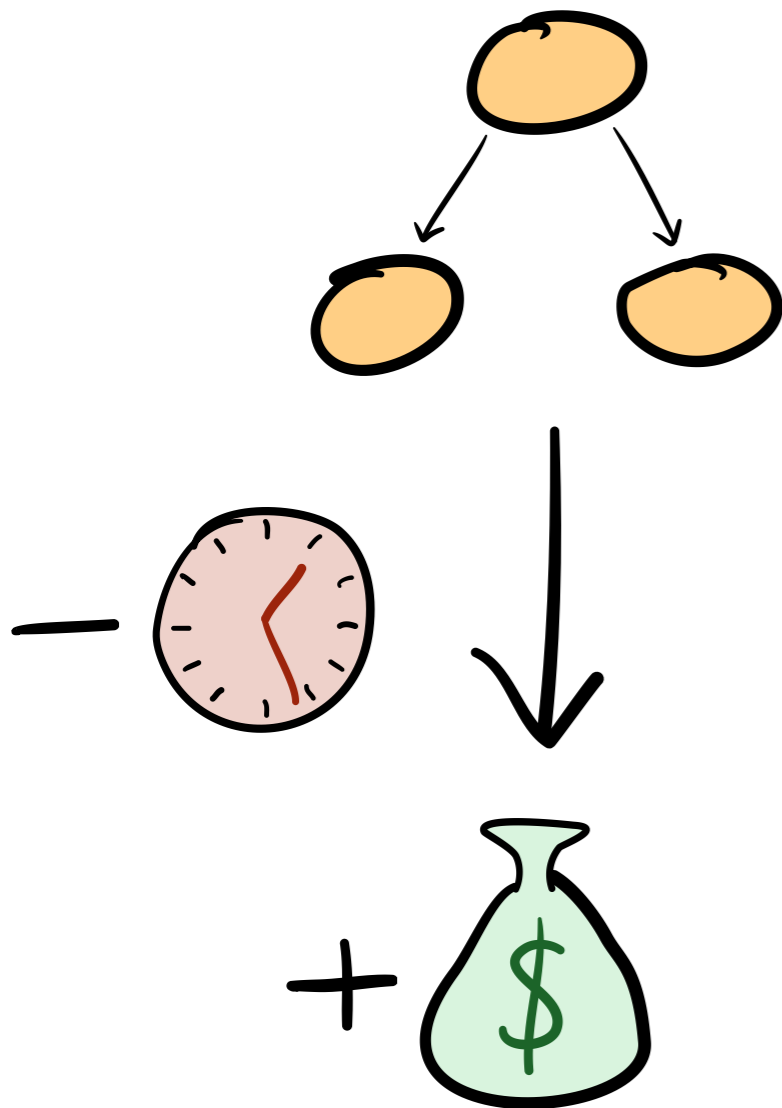
Game with a job and potential **reward**

- Get **reward** if we complete the job
- Pay for **time** spent serving the job
- Can *give up* at any time





# Single-Job Profit



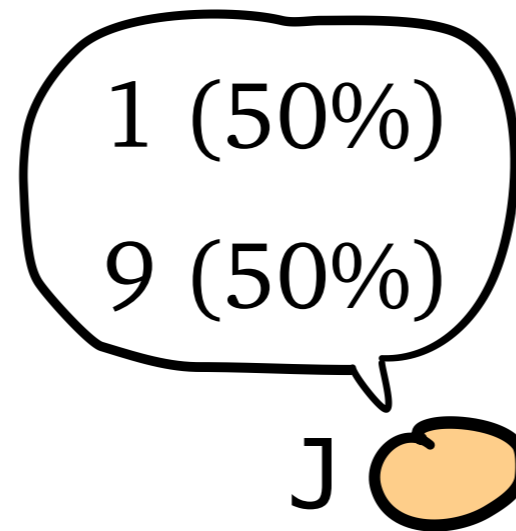
Game with a job and potential **reward**

- Get **reward** if we complete the job
- Pay for **time** spent serving the job
- Can *give up* at any time

Goal: maximize **profit**:

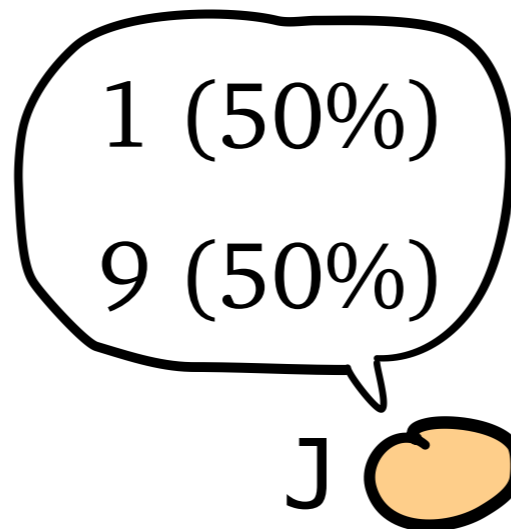
$$E[\text{reward received} - \text{time spent}]$$

# Single-Job Profit Example



# Single-Job Profit Example

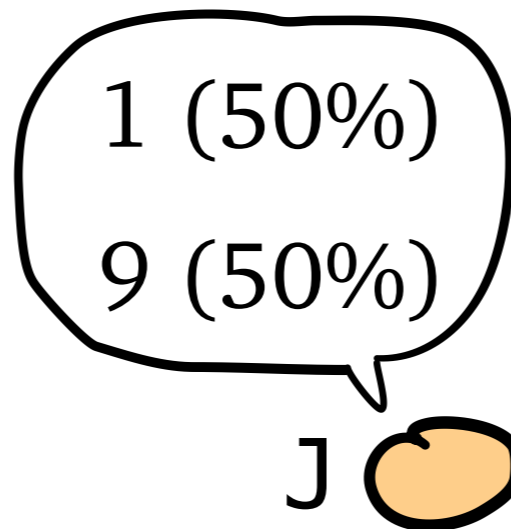
$V_J(r)$  = profit



$r$  = reward

# Single-Job Profit Example

$V_J(r)$  = profit

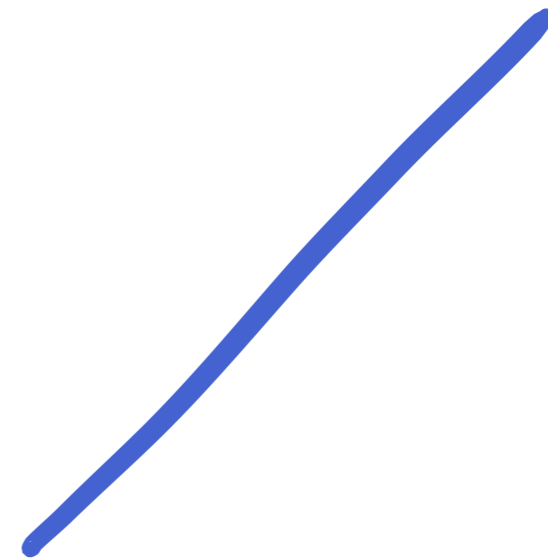
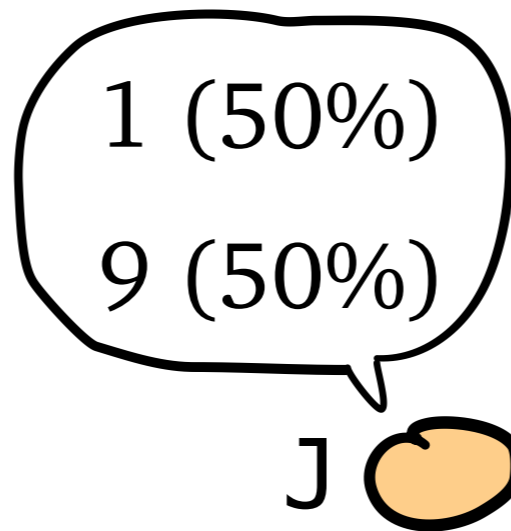


$r$  = reward

**Definition:**  $V_J$  is the *SJP function* of  $J$

# Single-Job Profit Example

$V_J(r)$  = profit

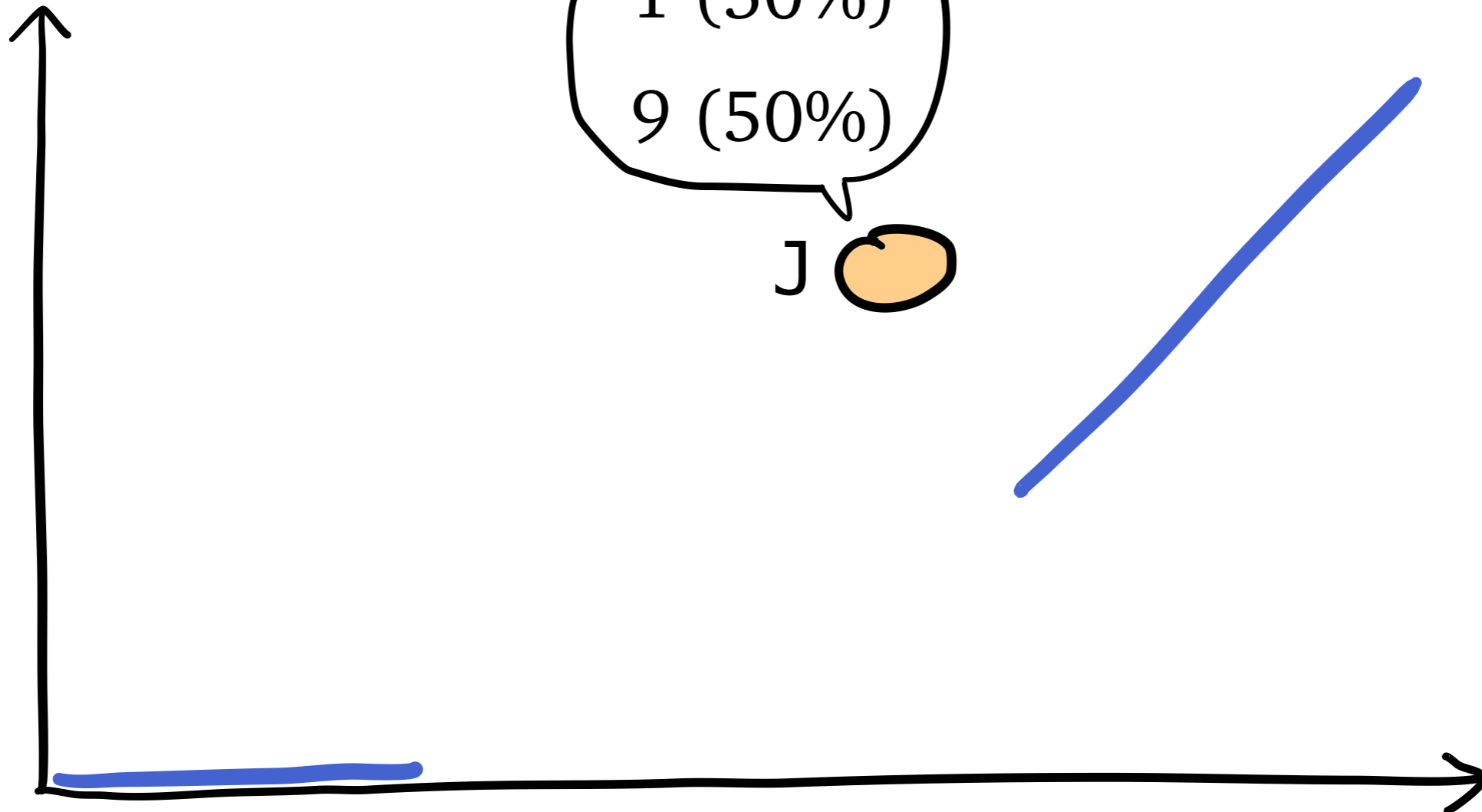


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# Single-Job Profit Example

$V_J(r)$  = profit

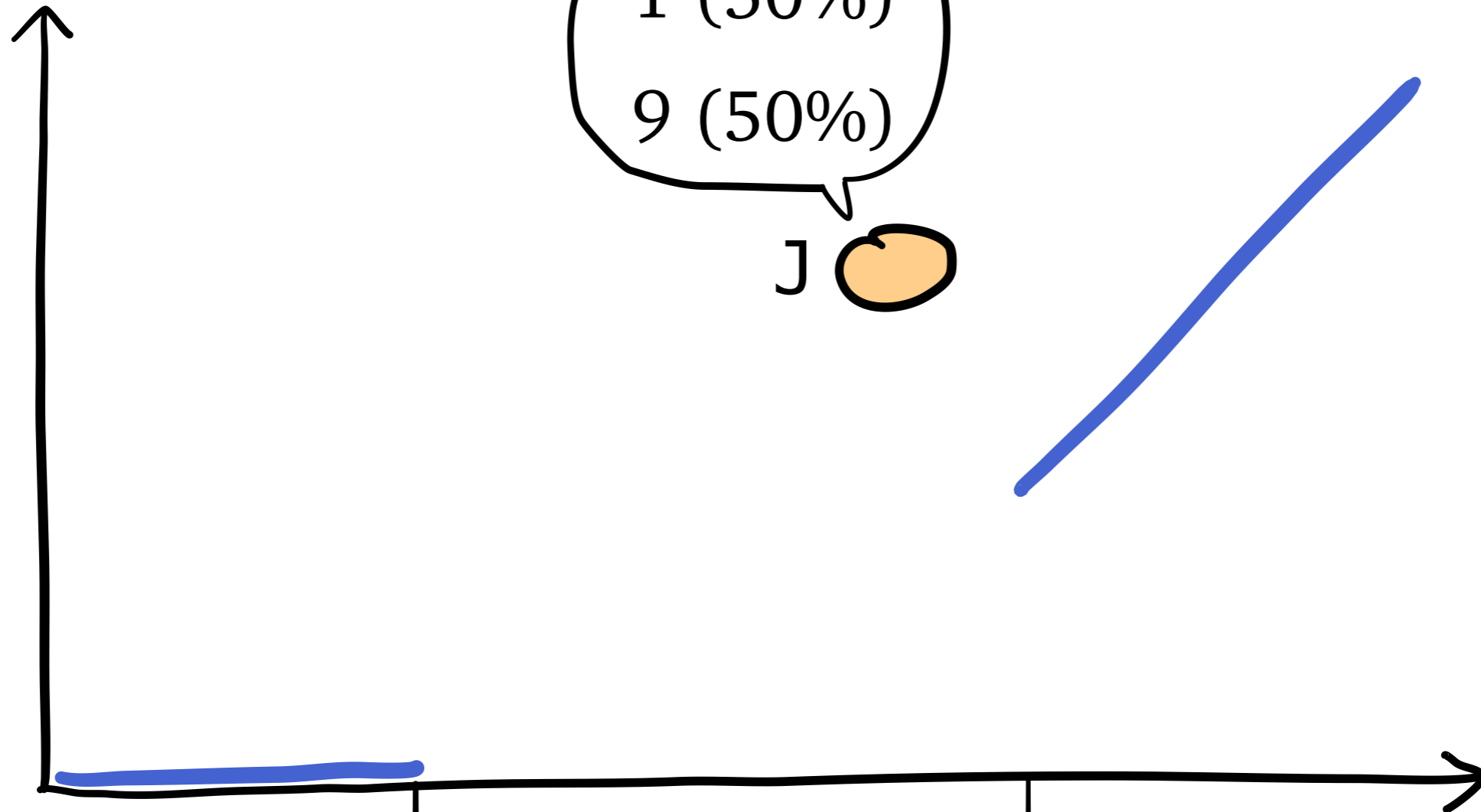


$r = \text{reward}$

**Definition:**  $V_J$  is the *SJP function* of  $J$

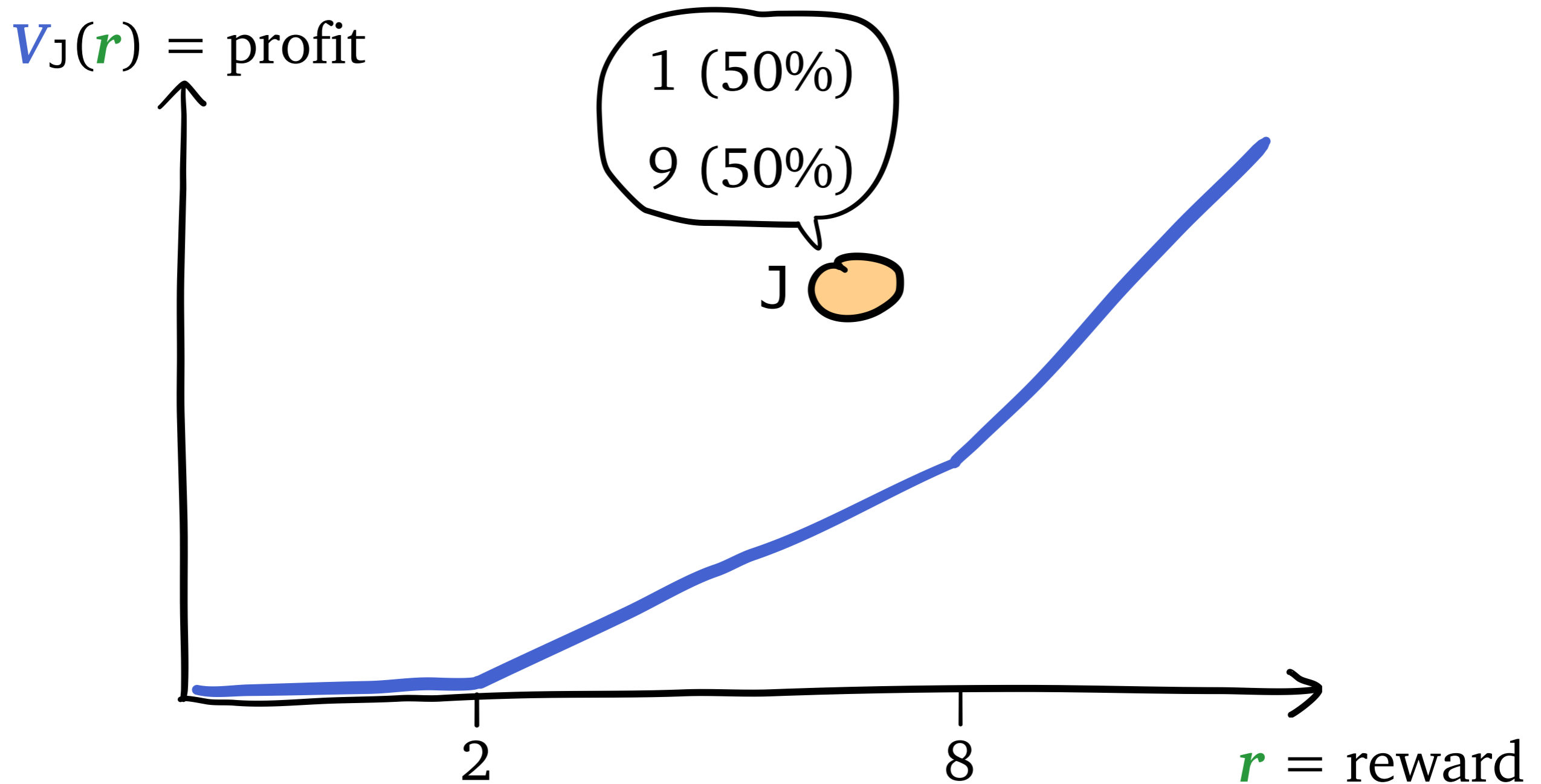
# Single-Job Profit Example

$V_J(r)$  = profit



**Definition:**  $V_J$  is the *SJP function* of  $J$

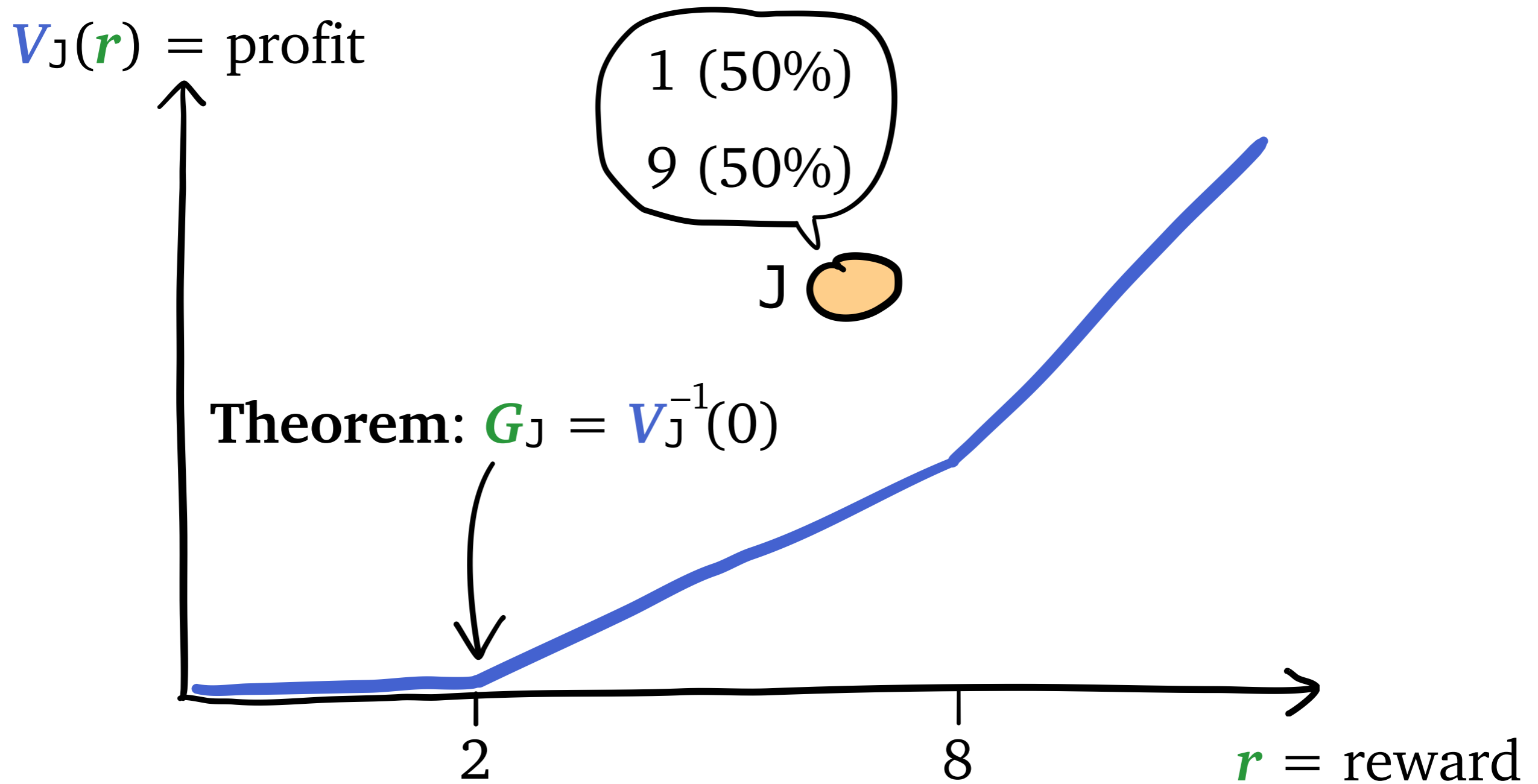
# Single-Job Profit Example



**Definition:**  $V_J$  is the *SJP function* of  $J$



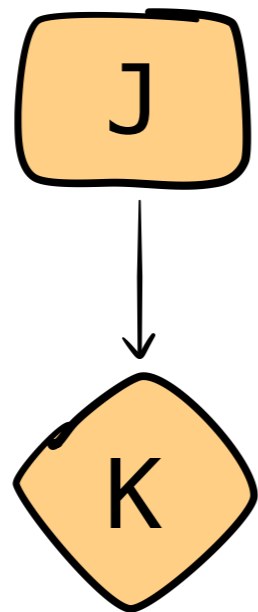
# Single-Job Profit Example



Definition:  $V_J$  is the *SJP function* of  $J$

# SJP Composition Law

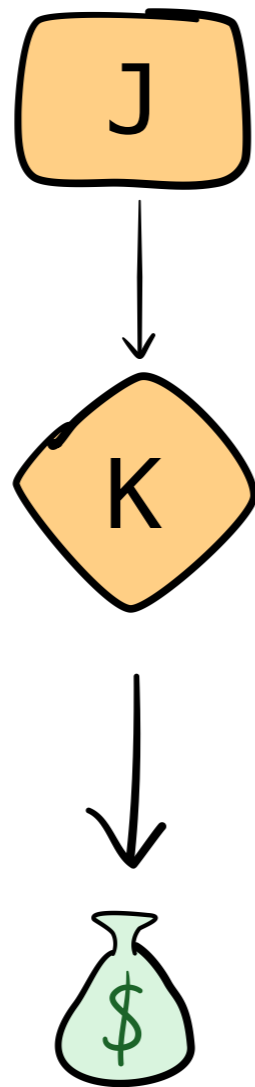
Theorem:  $V_{J \triangleright K}(r) = V_J(V_K(r))$



# SJP Composition Law

**Theorem:**  $V_{J \triangleright K}(r) = V_J(V_K(r))$

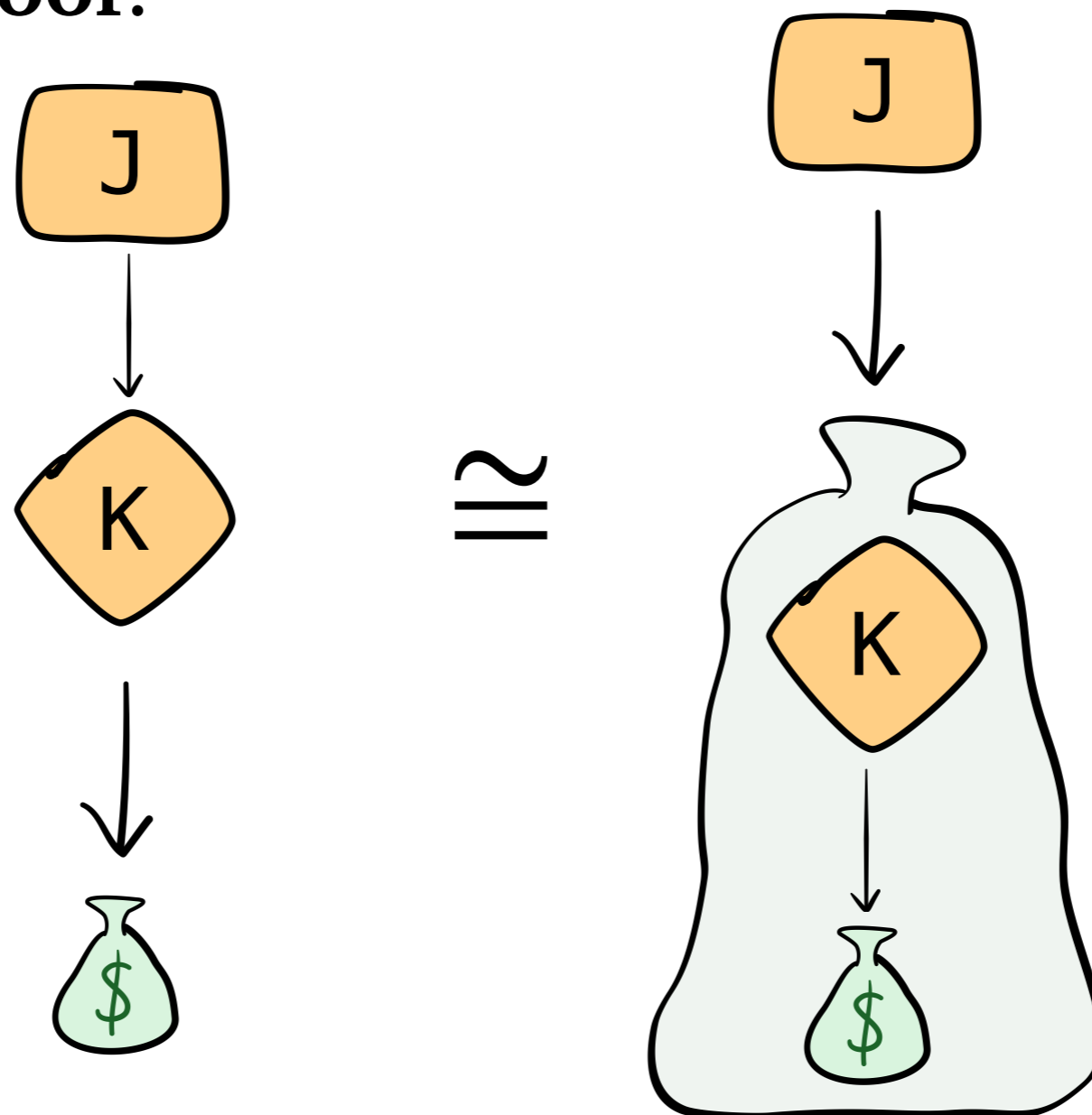
**Proof:**



# SJP Composition Law

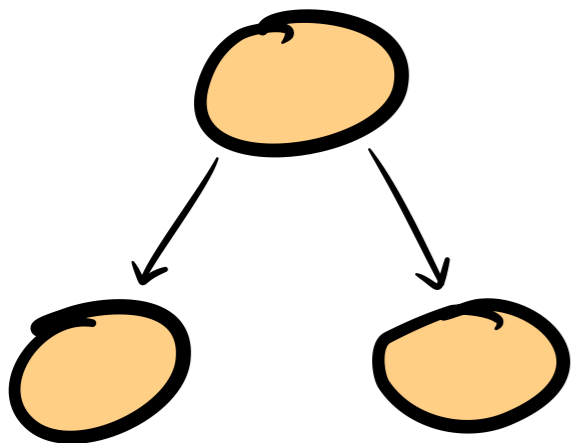
Theorem:  $V_{J \triangleright K}(r) = V_J(V_K(r))$

Proof:

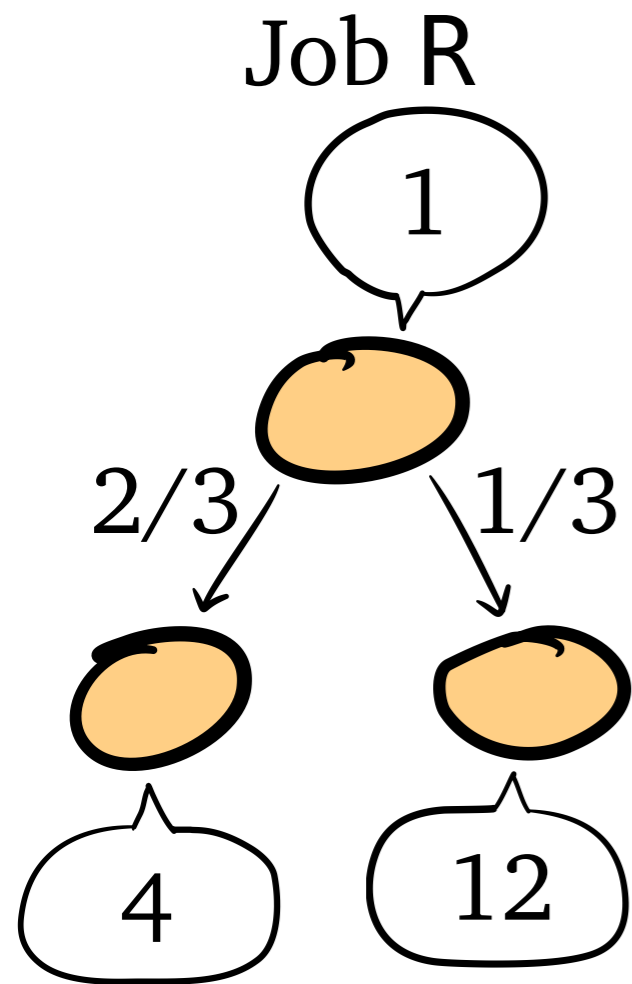


# Response Time Impact

Job R

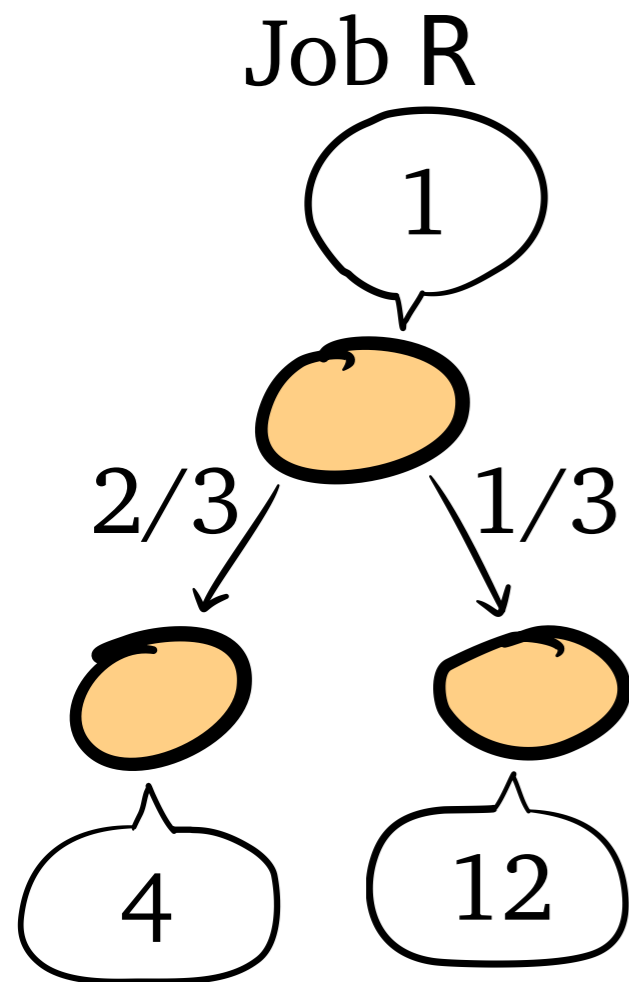


# Response Time Impact

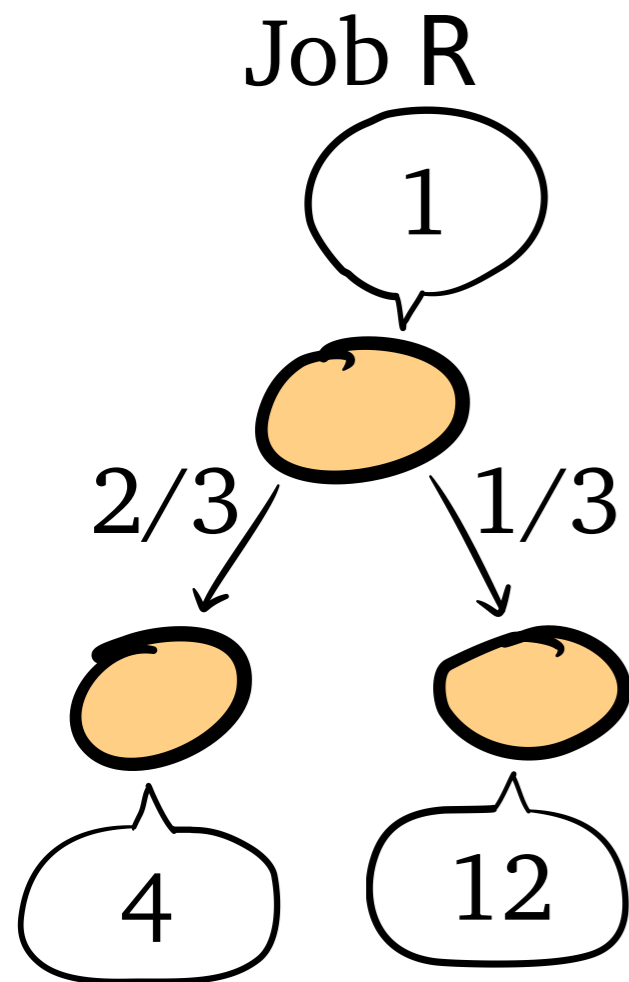


# Response Time Impact

Compare three policies:



# Response Time Impact

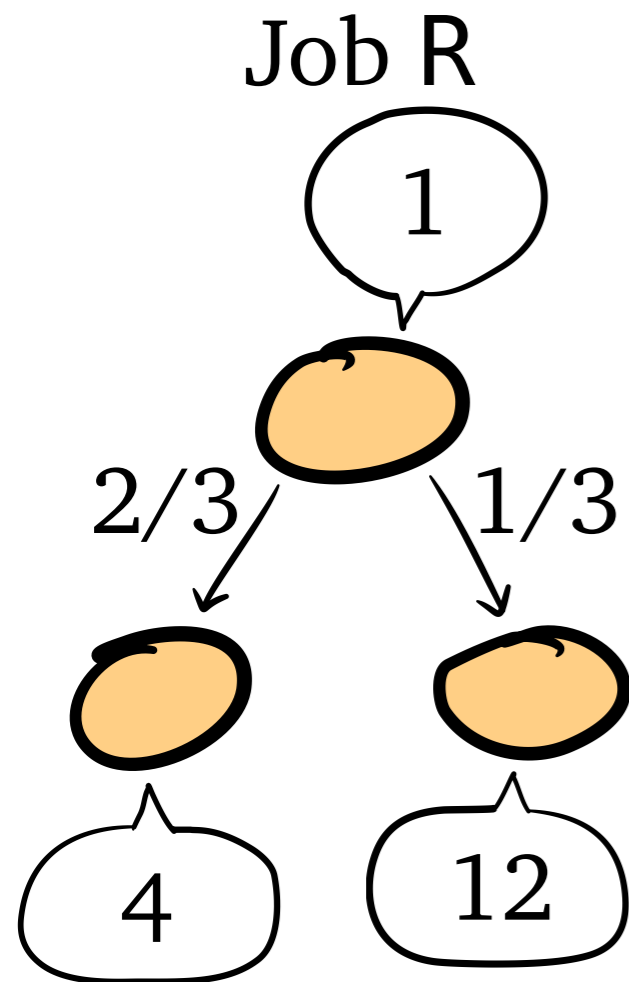


Compare three policies:

- *First-come, first-served* (FCFS)



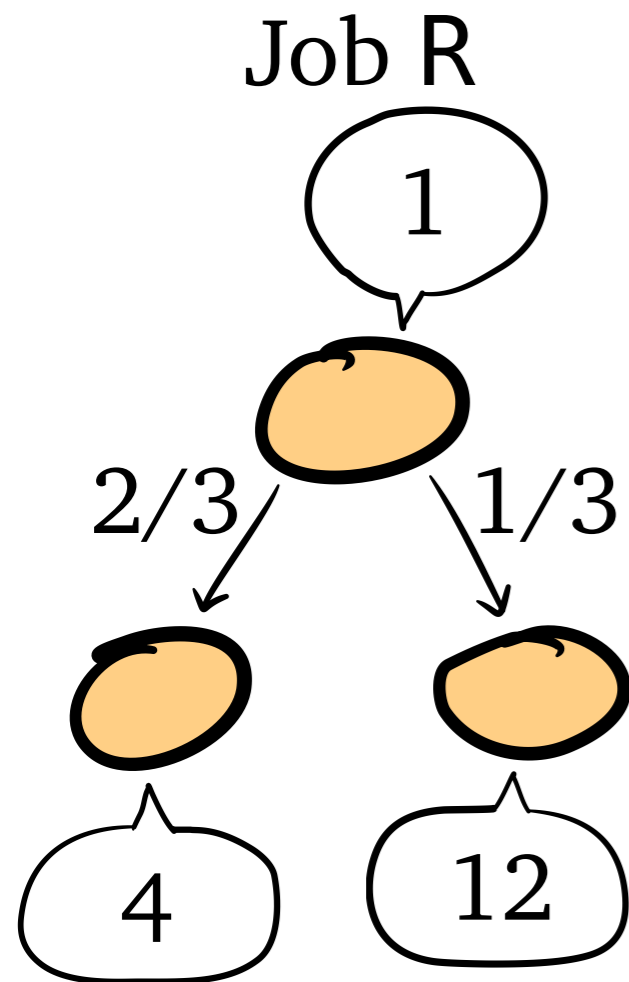
# Response Time Impact



Compare three policies:

- *First-come, first-served* (FCFS)
- *Blind Gittins policy* (BGP): ignores stage information

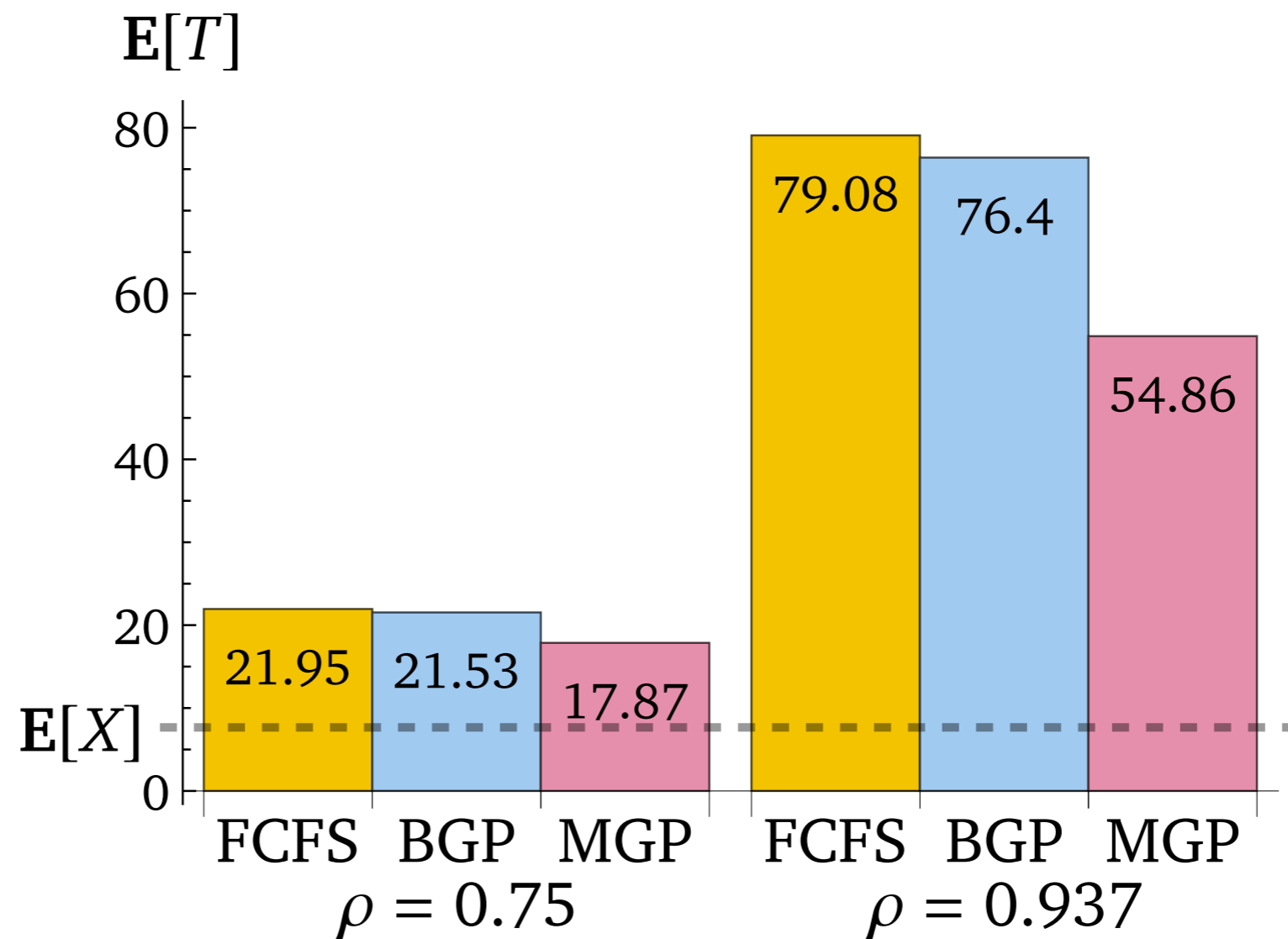
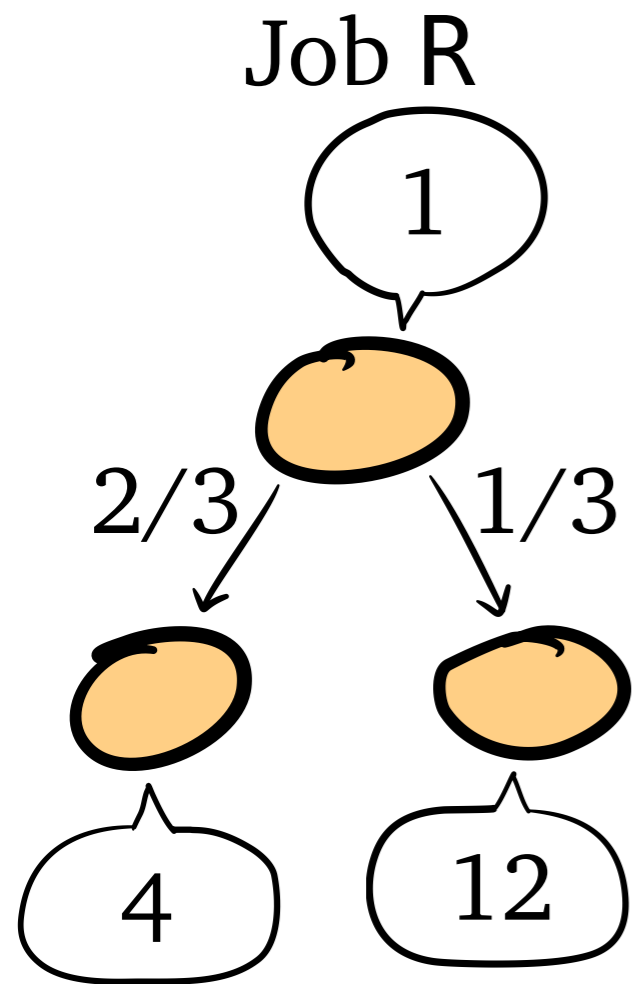
# Response Time Impact



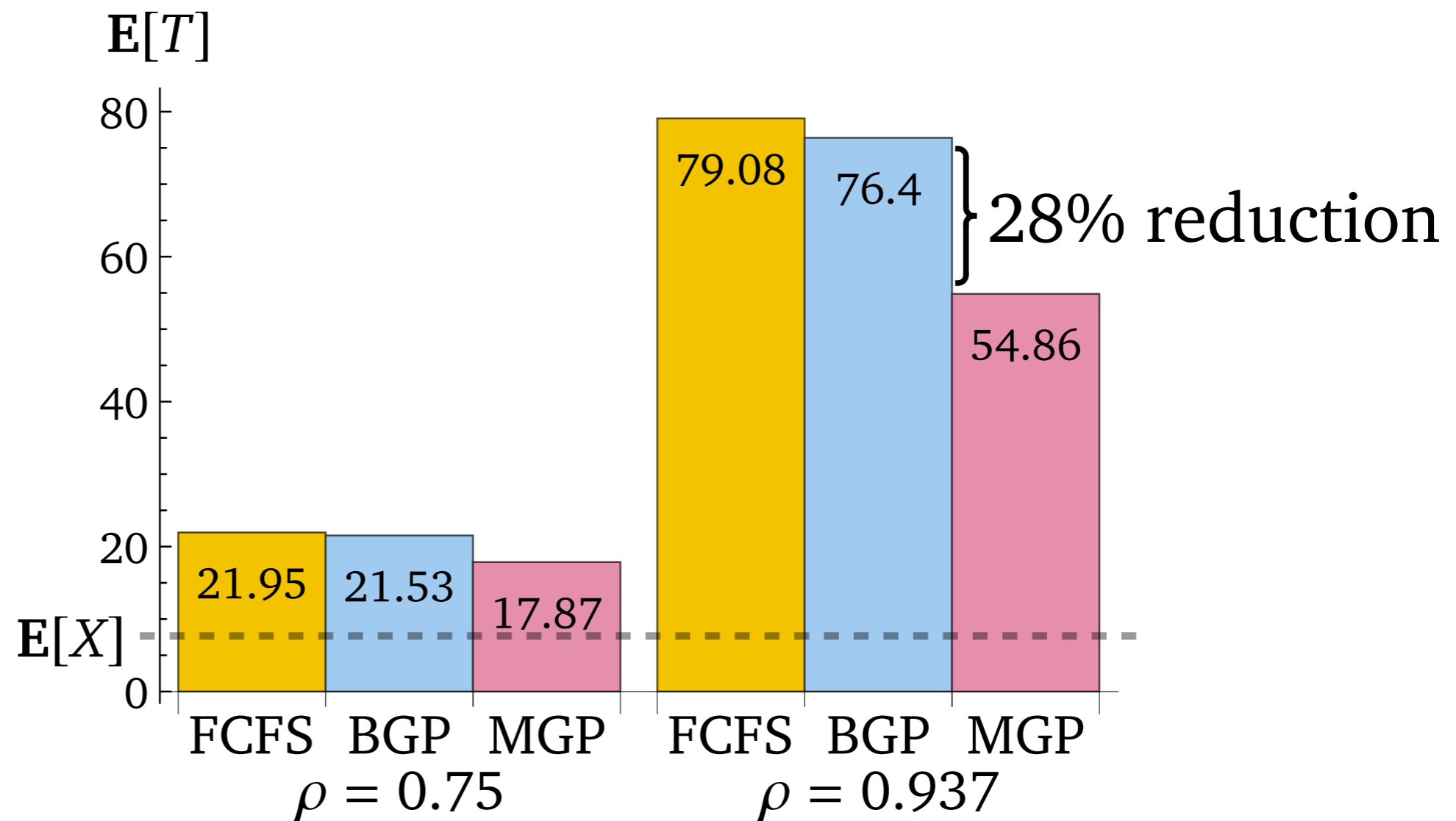
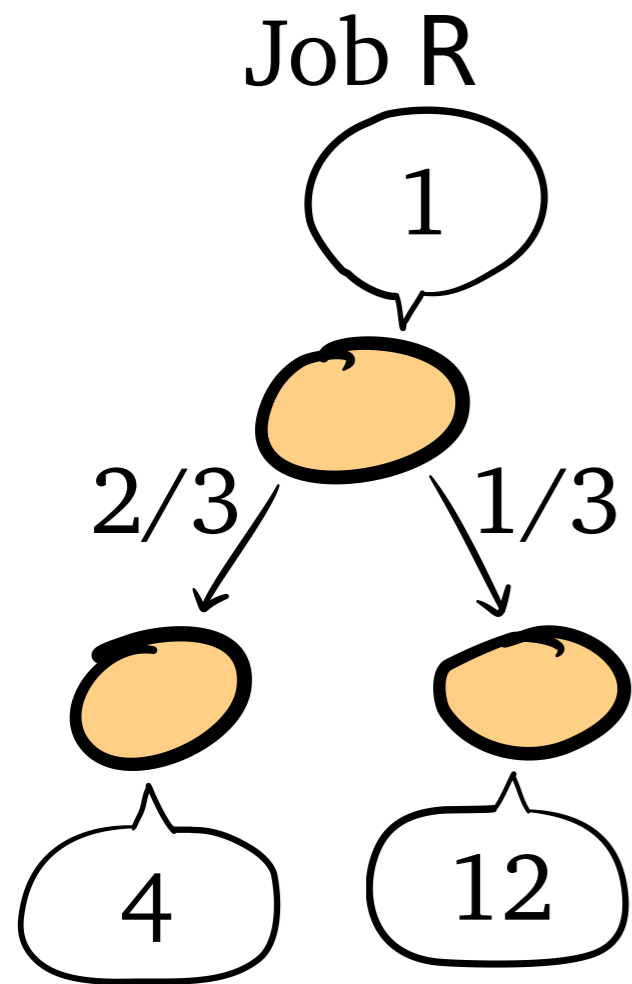
Compare three policies:

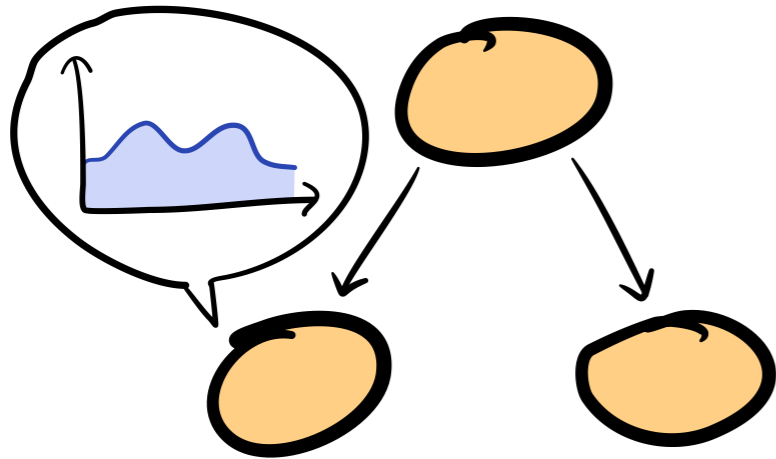
- *First-come, first-served* (FCFS)
- *Blind Gittins policy* (BGP): ignores stage information
- *Multistage Gittins policy* (MGP): exploits stage information

# Response Time Impact

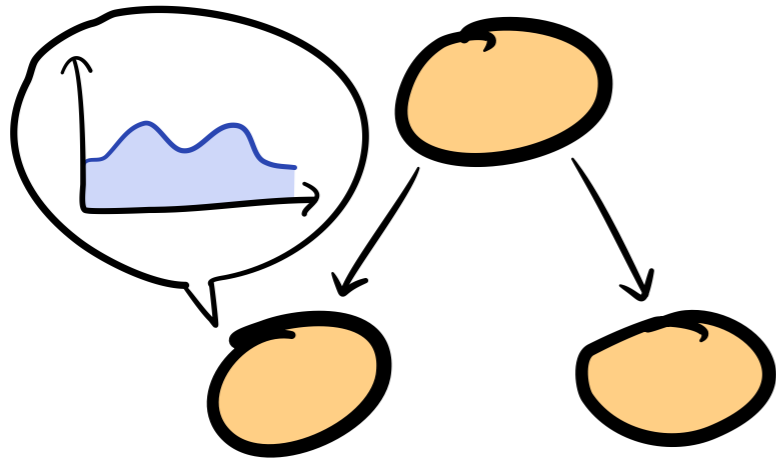


# Response Time Impact

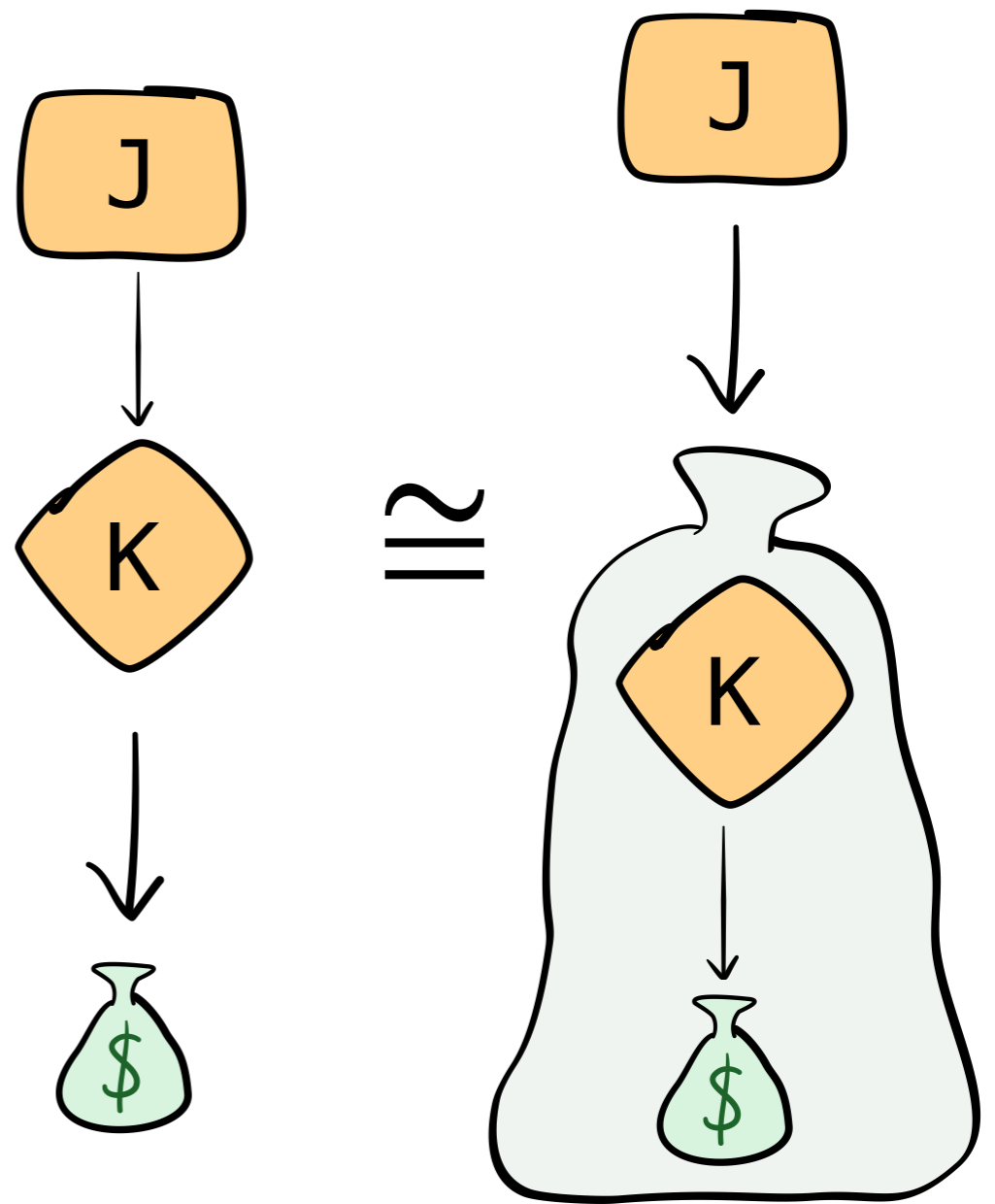




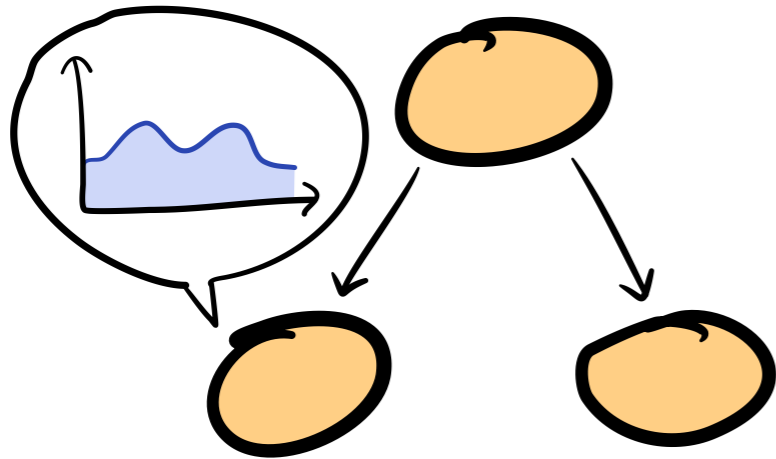
**Problem:** Gittins policy  
for *multistage jobs*



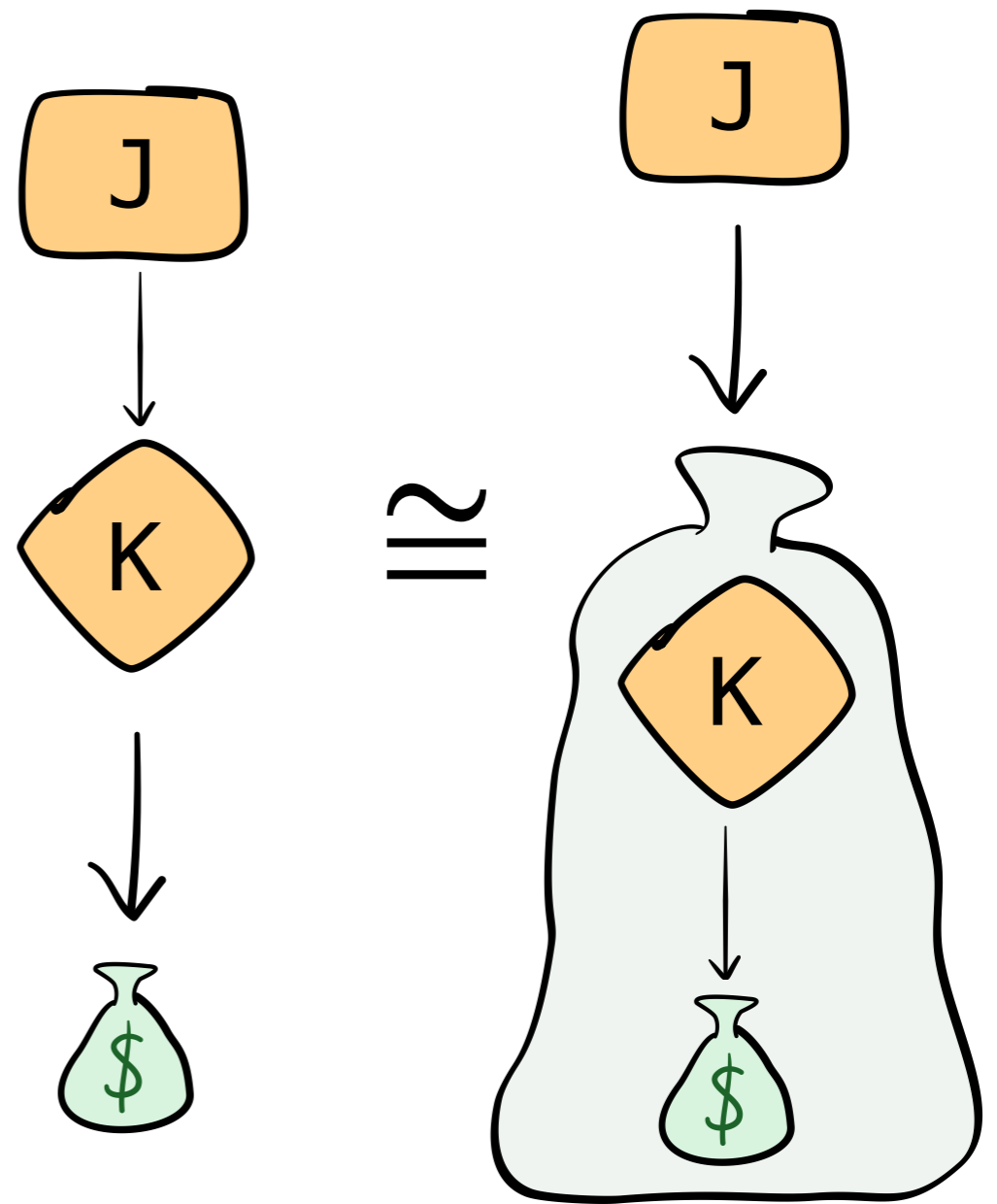
**Problem:** Gittins policy  
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**Solution:** new *single-job profit* (SJP) approach

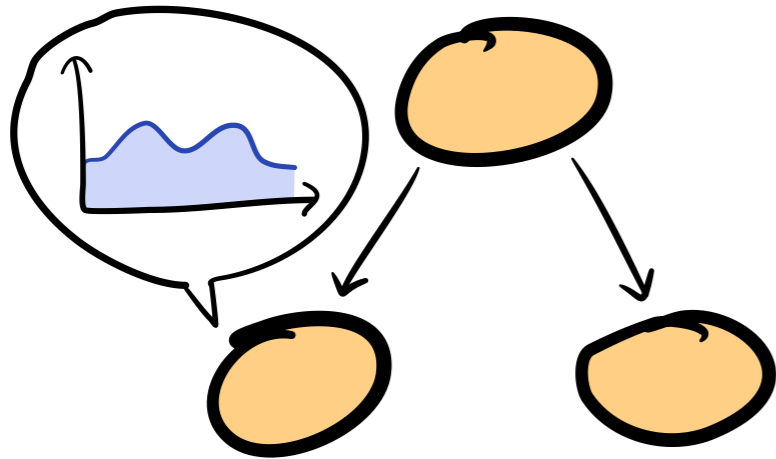


**Problem:** Gittins policy for *multistage jobs*

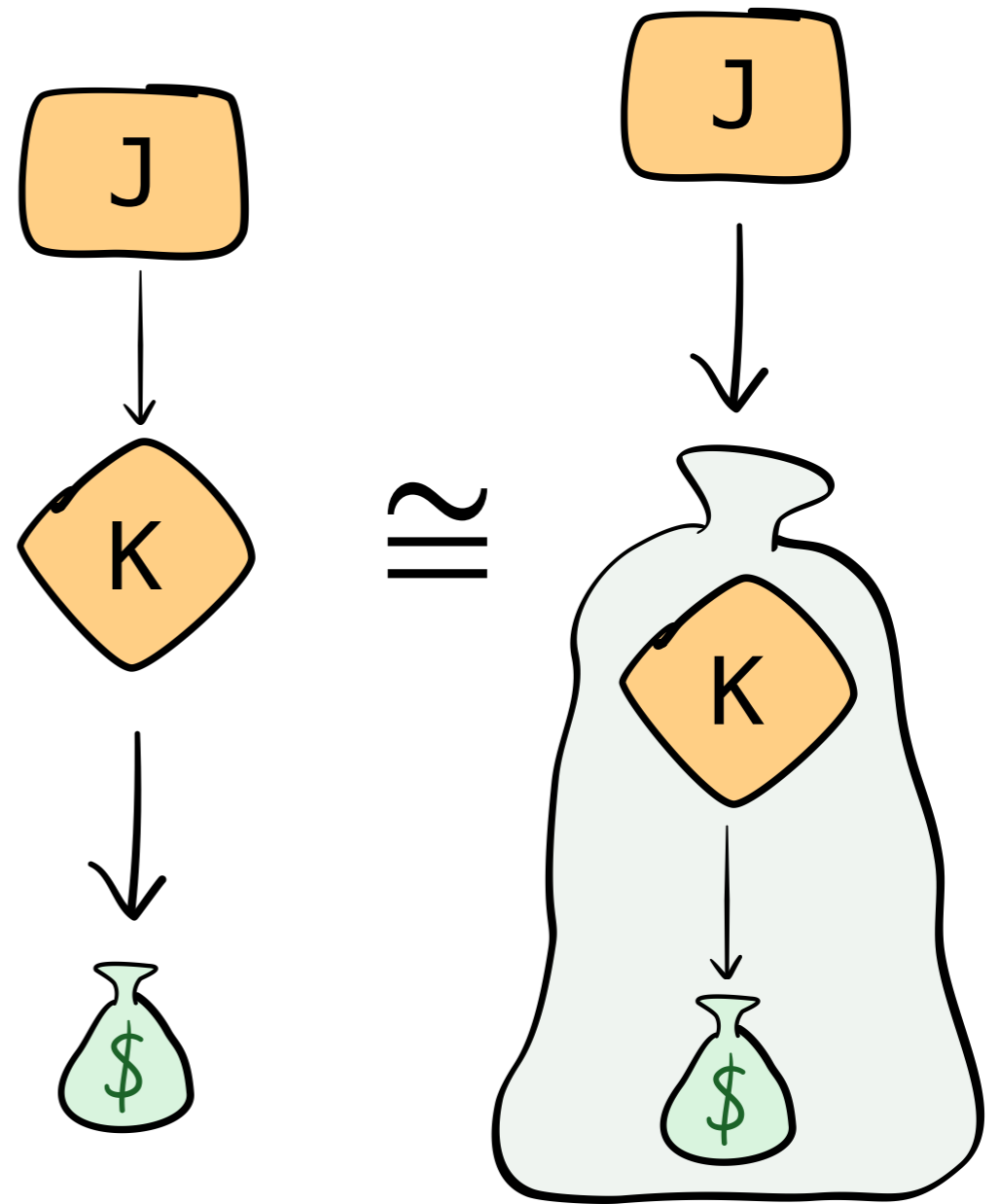


**Solution:** new *single-job profit* (SJP) approach

- SJP composition law

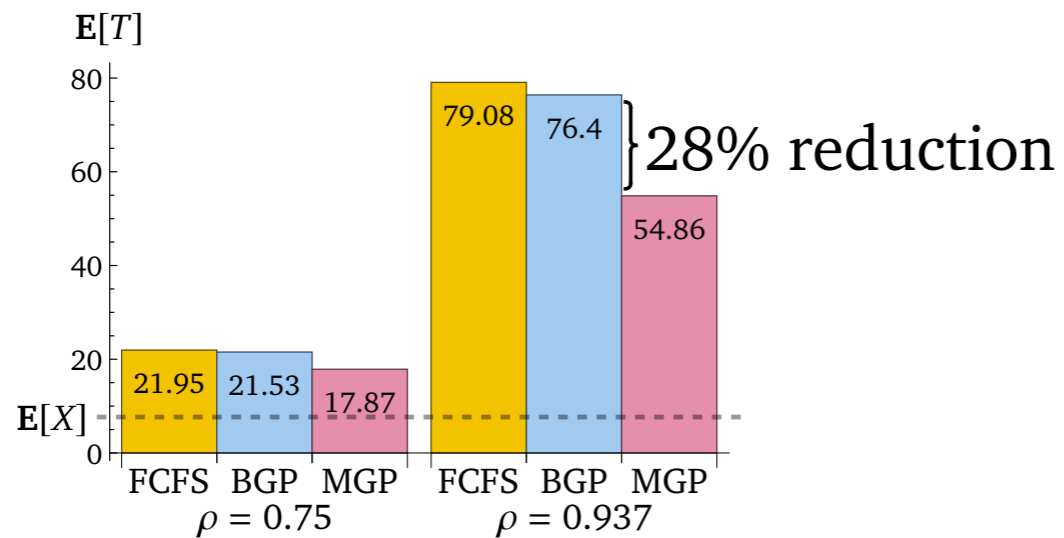


**Problem:** Gittins policy for *multistage jobs*



**Solution:** new *single-job profit* (SJP) approach

- SJP composition law



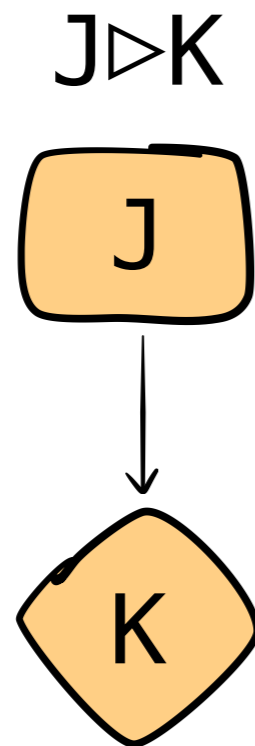
**Impact:** *significantly reduces*  $E[T]$



# Two Building Blocks

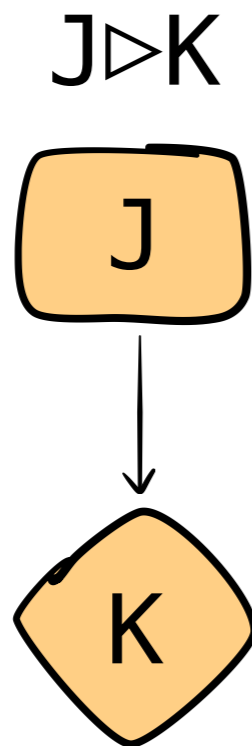
# Two Building Blocks

Sequential Composition



# Two Building Blocks

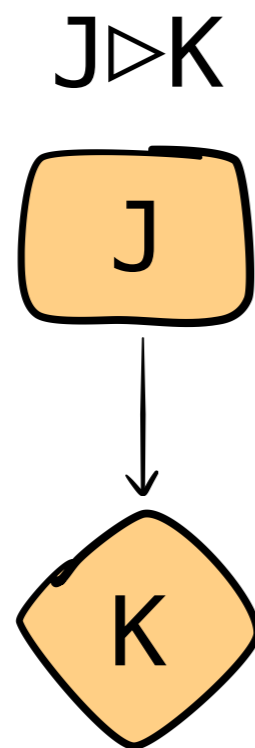
Sequential Composition



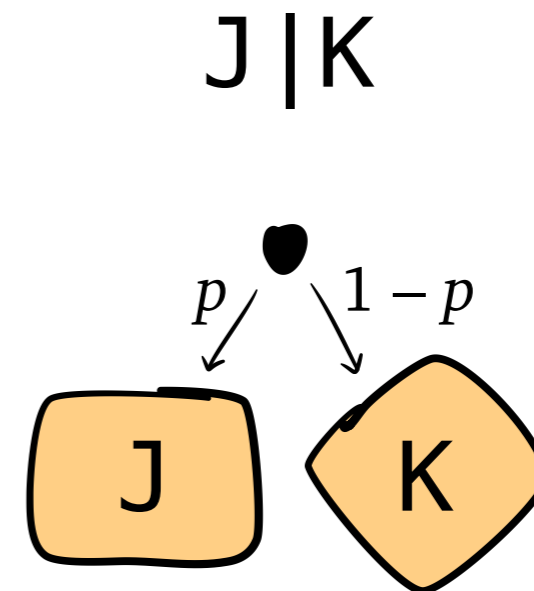
$$V_{J \triangleright K}(r) = V_J(V_K(r))$$

# Two Building Blocks

Sequential Composition



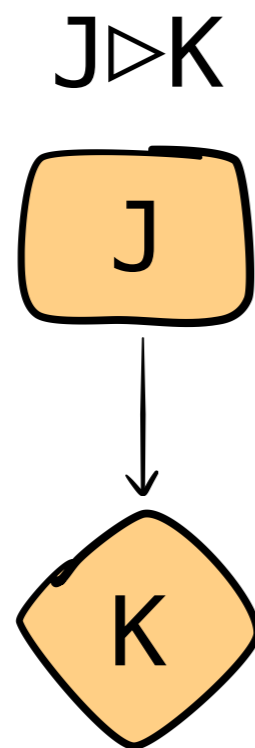
Mixture Composition



$$V_{J \triangleright K}(r) = V_J(V_K(r))$$

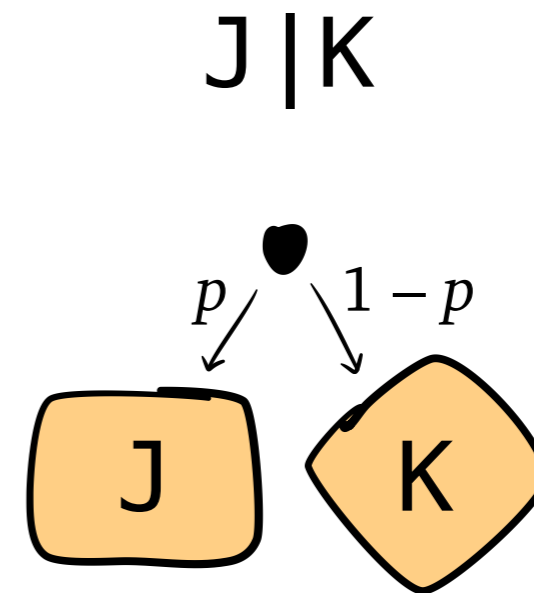
# Two Building Blocks

Sequential Composition



$$V_{J \triangleright K}(\mathbf{r}) = V_J(V_K(\mathbf{r}))$$

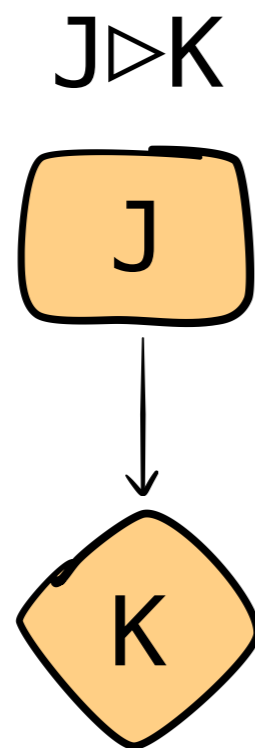
Mixture Composition



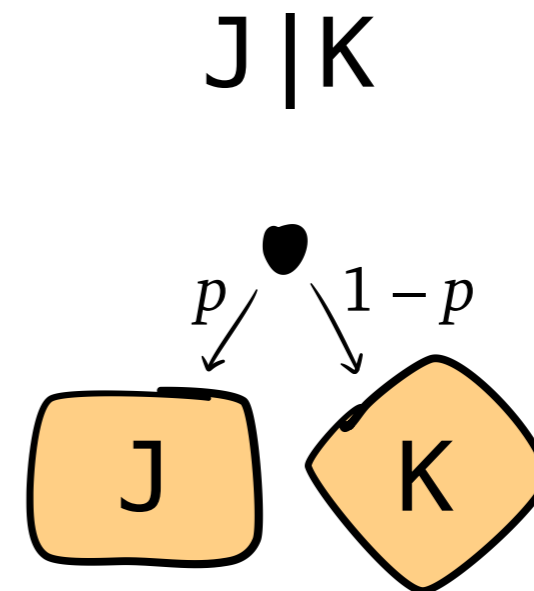
$$V_{J \mid K}(\mathbf{r}) = pV_J(\mathbf{r}) + (1-p)V_K(\mathbf{r})$$

# Two Building Blocks

Sequential Composition



Mixture Composition



$$V_{J \triangleright K}(\mathbf{r}) = V_J(V_K(\mathbf{r})) \quad V_{J | K}(\mathbf{r}) = pV_J(\mathbf{r}) + (1-p)V_K(\mathbf{r})$$

*Every* multistage job can be built from these